

A message-passing scheme for non-equilibrium stationary states

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E.A., H. Mahmoudi (2010) [in preparation]

I. Neri, D. Bollé, J. Stat Mech. (2009) P08009

Y. Kanoria, A. Montanari (2009) arXiv:0907.0449

Message-passing schemes are ways to approximately compute marginals of probability distributions.

In Artificial Intelligence known as Belief Propagation (BP); in Information Theory known as iterative decoding.

Bethe-Peierls approximation = Belief Propagation

JS Yedidia, WT Freeman, Y Weiss (2001)

M Mézard, A Montanari Physics, Oxford University Press (2009)

Configuration space; N discrete variables $\vec{s} \in \{1, \dots, q\}^N$

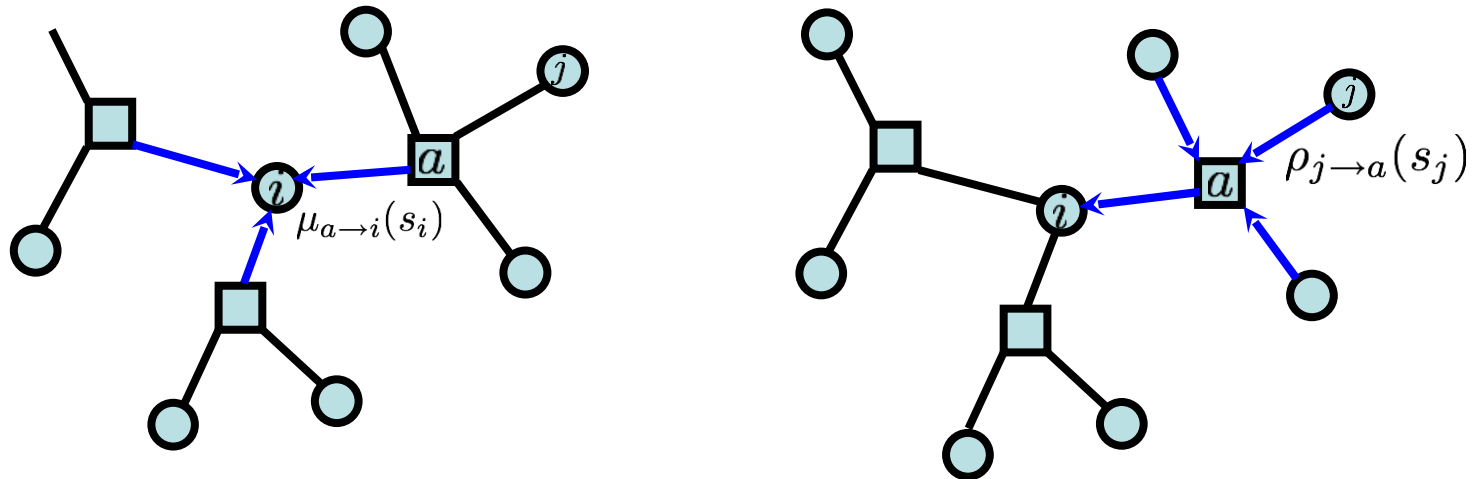
Cost or energy function; sum of local terms $\mathcal{H}(\vec{s}) = \sum_{a=1}^M e_a(\vec{s}_a)$

Marginal (one-spin) probabilities $p_i(s_i) = \frac{1}{Z} \sum_{\vec{s} \setminus s_i} e^{-\beta \mathcal{H}(\vec{s})}$

In statistical physics, artificial intelligence and information theory, such marginals (magnetizations, correlation functions etc) are typically what one wants to compute (or use)

$$\left\{ \begin{array}{l} p(\vec{s}) \propto \frac{\prod_{a=1}^M p_a(\vec{s}_a)}{\prod_{i=1}^N (p_i(s_i))^{d_i-1}} \\ p_i(s_i) = \sum_{\vec{s}_a \setminus s_i} p_a(\vec{s}_a) \end{array} \right. \quad \begin{array}{l} \longleftarrow \text{Bethe-Peierls approximation} \\ \longrightarrow \text{Belief propagation} \end{array}$$

Factor graph representation illustrates canonical BP



The “messages” $\mu_{a \rightarrow i}(s_i)$ and $\rho_{j \rightarrow a}(s_j)$ are Lagrange multipliers. They enforce the conditions that the marginal probabilities p_a over the spins partaking in one interaction a , summed over all those spins except i , is the marginal probability p_i , over that last spin.

$$p_i(s_i) = D_i \prod_{a \in \partial i} \mu_{a \rightarrow i}(s_i)$$

$$\mu_{a \rightarrow i}(s_i) = C_{a \rightarrow i} \sum_{\vec{s}_a \setminus i} \exp(-\beta e_a(\vec{s}_a)) \prod_{j \in \partial a \setminus i} \rho_{j \rightarrow a}(s_j)$$

$$\rho_{i \rightarrow a}(s_i) = D_{i \rightarrow a} \prod_{b \in \partial i \setminus a} \mu_{b \rightarrow i}(s_i)$$

- Iterative procedure to find fixed points of BP equations
- Exact on trees and an approximation on loopy graphs
- No guarantee to converge

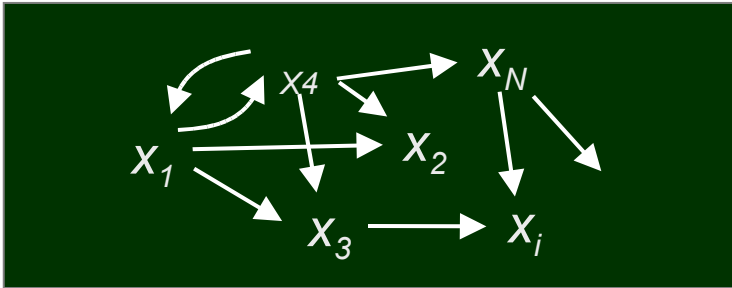


Non-equilibrium is the domain of kinetic theory.

There is no Gibbs measure as there is in equilibrium.

But can one nevertheless compute marginals by a message-passing scheme?

Today's case study: diluted asymmetric spin glass



S Kauffman (1969)

J Hopfield (1982)

B Derrida (1987)

A Crisanti, H Sompolinski (1988)

....and many others

$$\frac{d}{dt}p(\vec{\sigma}(t)) = W(t)p(\vec{\sigma}(t)) \quad \text{Fully asynchronous updates (master equations); not yet done}$$

$$p(\vec{\sigma}(0)...\vec{\sigma}(t)) = \prod_{s=1}^t W[\vec{\sigma}(s) | \vec{h}(s)] p(\vec{\sigma}(0)) \quad \text{Synchronous updates; which can yet be varied in several ways (here in two ways)}$$

$$W[\vec{\sigma}(s) | \vec{h}(s)] = \prod_{i=1}^N \frac{\exp(\beta h_i(s) \sigma_i(s))}{2 \cosh(\beta h_i(s))}$$

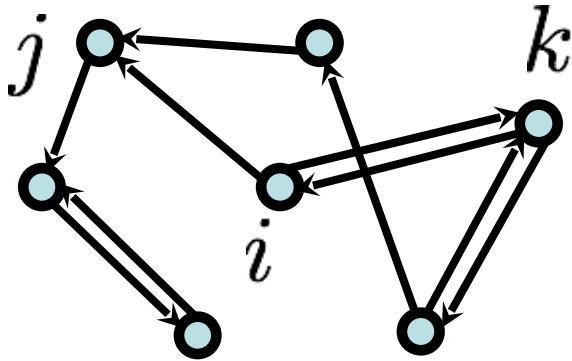
$$h_i(t) = \sum_{j \in \partial i} c_{ji} J_{ji} \sigma_j(t-1) + \theta_i(t)$$

- parallel : simultaneously update all spins

- sequential : one spin updated at a time

$$\begin{aligned} \sigma_i(t+1) &= +1 && \text{with probability } \{1 + \exp(2\beta h_i(t))\}^{-1} \\ \sigma_i(t+1) &= -1 && \text{with probability } \{1 + \exp(-2\beta h_i(t))\}^{-1} \end{aligned}$$

Dilution, asymmetry, and interaction strength



connectivity $\rightarrow c$

asymmetry $\rightarrow \epsilon$

Derrida (1987) parametrization

connectivity $c_{ij} (i \rightarrow j)$

$$p(c_{ij}) = \frac{c}{N} \delta_{c_{ij},1} + (1 - \frac{c}{N}) \delta_{c_{ij},0}$$

Starts as directed Erdős-Renyi graphs; where average connectivity would be c

Connections $i \rightarrow j$ and $j \rightarrow i$ dependent

$$p(c_{ji}|c_{ij}) = \epsilon \delta_{c_{ij},c_{ji}} + (1 - \epsilon) p(c_{ji})$$

Gaussian or binary $J_{ij} \longrightarrow h_i(t) = \sum_{j \in \partial i} c_{ji} J_{ji} \sigma_j(t-1) + \theta_i(t)$

Mean-field theory for magnetizations and correlations

$$p(\sigma_i(0), \dots, \sigma_i(t)) = \sum_{\vec{\sigma}_{\setminus i}(0), \dots, \vec{\sigma}_{\setminus i}(t)} p(\vec{\sigma}(0), \dots, \vec{\sigma}(t)) \longrightarrow m_i(t)$$

$$p_{ij}(\sigma_i(0), \dots, \sigma_i(t), \sigma_j(0), \dots, \sigma_j(t')) = \sum_{\vec{\sigma}_{\setminus i,j}(0), \dots, \vec{\sigma}_{\setminus i,j}(t)} p(\vec{\sigma}(0), \dots, \vec{\sigma}(t)) \longrightarrow c_{ij}(t, t')$$

$$\frac{dm_i(t)}{dt} = -m_i(t) + \langle \tanh(\beta H_i(t)) \rangle$$

$$\frac{dc_{ij}(t, t')}{dt} = -c_{ij}(t, t') + \langle \tanh(\beta \sigma_j(t') H_i(t)) \rangle$$

$$\text{nMF} \quad m_i = \tanh \left[\beta \left(\sum_j J_{ji} m_j + \theta_i \right) \right]$$

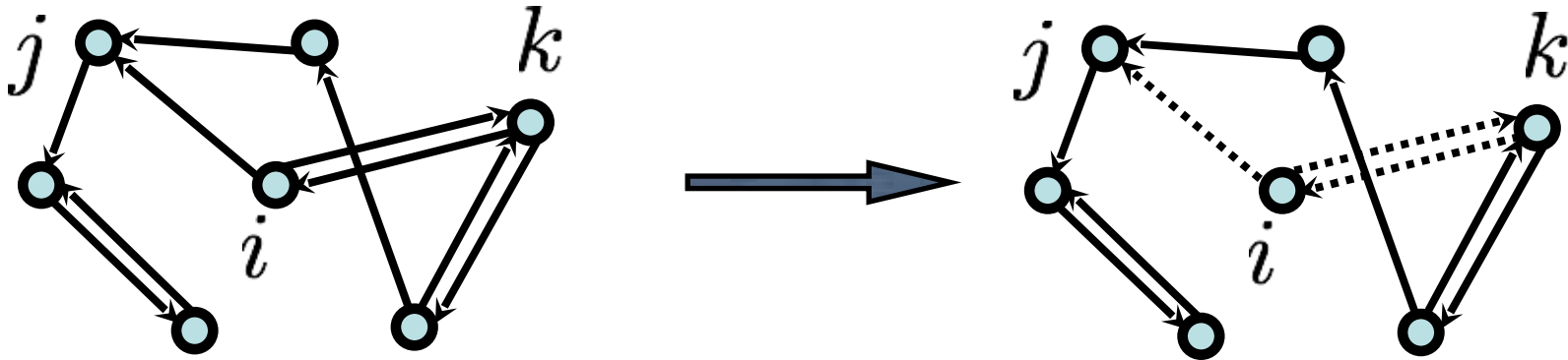
$$\text{TAP} \quad m_i = \tanh \left[\beta \left(\sum_j J_{ji} m_j + \theta_i - m_i \sum_j J_{ji}^2 (1 - m_j)^2 \right) \right]$$

Crisanti, Sompolinski (1988)
Kappen, Spanjers (2000)

Hertz et al (2010)
Hertz, Roudi arXiv:1009.5946
Zeng et al arXiv:1011.6216

Bethe - Peierls approximation for spin histories

Cavity graph



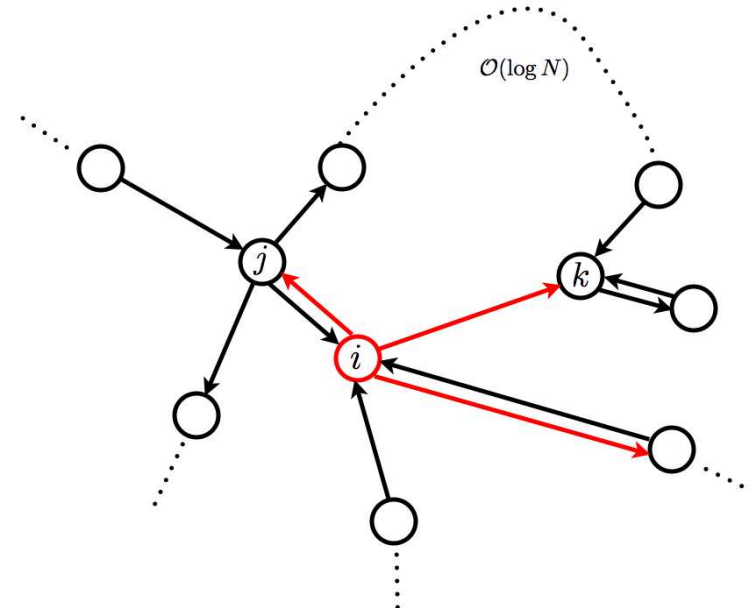
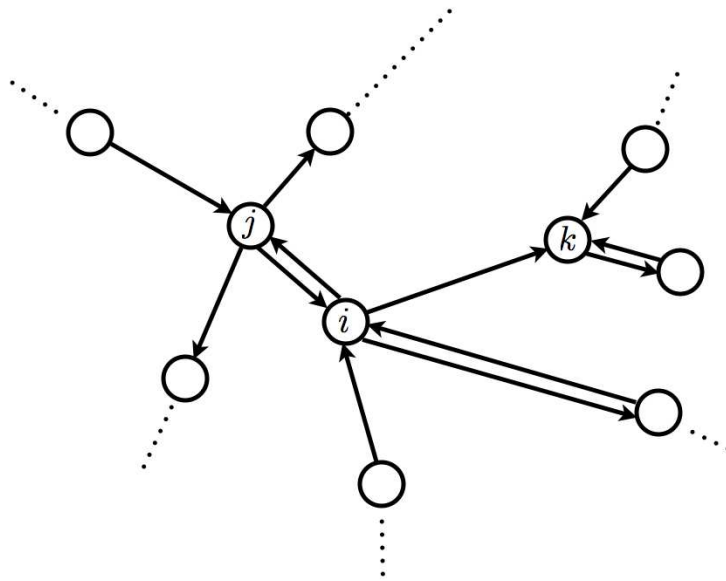
$$p(\vec{\sigma}(0) \dots \vec{\sigma}(t)) = p^{(i)}(\vec{\sigma}(0), \dots, \vec{\sigma}(t) | \sigma_i(0), \dots, \sigma_i(t)) p_i(\sigma_i(0), \dots, \sigma_i(t))$$

The cavity assumption: spins in cavity independent

$$p^{(i)}(\vec{\sigma}(0), \dots, \vec{\sigma}(t) | \sigma_i(0), \dots, \sigma_i(t)) = \prod_{k \in \partial i} m_{k \rightarrow i}(\sigma_k(0), \dots, \sigma_k(t) | \sigma_i(0), \dots, \sigma_i(t))$$

The “messages” $m_{k \rightarrow i}$ are conditional probabilities

The (dynamic) cavity equation (parallel updates)



$$m_{i \rightarrow j}(\sigma_i(0), \dots, \sigma_i(t)) = \sum_{\vec{\sigma}_{\partial i \setminus j}(0), \dots, \vec{\sigma}_{\partial i \setminus j}(t)} \prod_{k \in \partial i \setminus j} m_{k \rightarrow i}(\sigma_k(0), \dots, \sigma_k(t) | \sigma_i(0), \dots, \sigma_i(t))$$

$$\prod_{s=1}^t \frac{e^{\beta h_{i \rightarrow j}(s) \sigma_i(s)}}{2 \cosh(\beta h_{i \rightarrow j}(s))} m_{i \rightarrow j}(\sigma_i(0))$$

In static (equilibrium) case this would be BP,
Here history dependent, hence hard to use directly.

The time-factorized approximation (parallel updates)

$$m_{i \rightarrow j}(\sigma_i(0), \dots, \sigma_i(t)) = \prod_{s=0}^t m_{i \rightarrow j}(\sigma_i(s))$$

$$m_{i \rightarrow j}(\sigma_i(t)) = \sum_{\sigma_i(t-2), \vec{\sigma}_{\partial i \setminus j}(t-1)} \prod_{k \in \partial i \setminus j} m_{k \rightarrow i}(\sigma_k(t-1) | \sigma_i(t-2)) \frac{e^{\beta(\sum_{j \in \partial i} J_{ji} \sigma_j(t-1) + \theta_i) \sigma_i(t)}}{2 \cosh(\beta(\sum_{j \in \partial i} J_{ji} \sigma_j(t-1) + \theta_i))} m_{i \rightarrow j}(\sigma_i(t-2))$$

(formally) time-dependent
magnetization

I Neri, D Bolle (2009)
Y Kanoria, A Montanari (2009)

Aurell, Mahmoudi (2010)

$$m_i(t) = \sum_{\vec{\sigma}_{\partial i}(t-1)} \prod_{j \in \partial i} m_{j \rightarrow i}(\sigma_j(t-1)) \tanh \left[\beta \left(\sum_{j \in \partial i} \frac{c_{ij}}{c} J_{ji} \sigma_j(t-1) + \theta_i \right) \right]$$

The sequential update model (poor man's Master eq.)

$$\frac{dp(\vec{\sigma}(t))}{dt} = \sum_{i=1}^N \{w_i(F_i\vec{\sigma}(t)) p(F_i\vec{\sigma}(t)) - w_i(\vec{\sigma})(t) p(\vec{\sigma})(t)\}$$

Fully asynchronous updates (Master equations) is not yet done. In sequential updates one (randomly picked) spin is updated at a time.

$$p(\vec{\sigma}(t)) = \sum_{\vec{\sigma}(t-1)} W(\vec{\sigma}(t) | \vec{\sigma}(t-1)) p(\vec{\sigma}(t-1))$$

$$W(\vec{\sigma}(t) | \vec{\sigma}(t-1)) = \delta_{\vec{\sigma}(t), \vec{\sigma}(t-1)} + \frac{1}{N} \sum_{i=1}^N \{w_i(F_i\vec{\sigma}(t)) \delta_{\vec{\sigma}(t), F_i\vec{\sigma}(t-1)} - w_i(\vec{\sigma}(t)) \delta_{\vec{\sigma}(t), \vec{\sigma}(t-1)}\}$$

When N goes to infinity, it is reasonable to expect that sequential update tends to fully asynchronous updates. But at finite N there will be a difference.

The dynamic cavity equations for sequential updates

The full dynamic cavity equations :

$$m_{i \rightarrow j}(\sigma_i(0), \dots, \sigma_i(t)) = \sum_{\vec{\sigma}_{\partial i \setminus j}(0), \dots, \vec{\sigma}_{\partial i \setminus j}(t)} \prod_{k \in \partial i \setminus j} m_{k \rightarrow i}(\sigma_k(0), \dots, \sigma_k(t) | \sigma_i(0), \dots, \sigma_i(t))$$

$$\prod_{s=1}^t \left[\frac{1}{N} \frac{e^{\beta h_i^{(j)}(s) \sigma_i(s)}}{2 \cosh(\beta h_i^{(j)}(s))} + \left(1 - \frac{1}{N}\right) \delta_{\sigma_i(s), \sigma_i(s-1)} \right] m_{i \rightarrow j}(\sigma_i(0))$$

The time factorized approximation :

$$m_{i \rightarrow j}(\sigma_i(t)) = \frac{1}{N} \sum_{\vec{\sigma}_{\partial i \setminus j}(t-1), \sigma_i(t-2)} \prod_{k \in \partial i \setminus j} m_{k \rightarrow i}(\sigma_k(t-1) | \sigma_i(t-2))$$

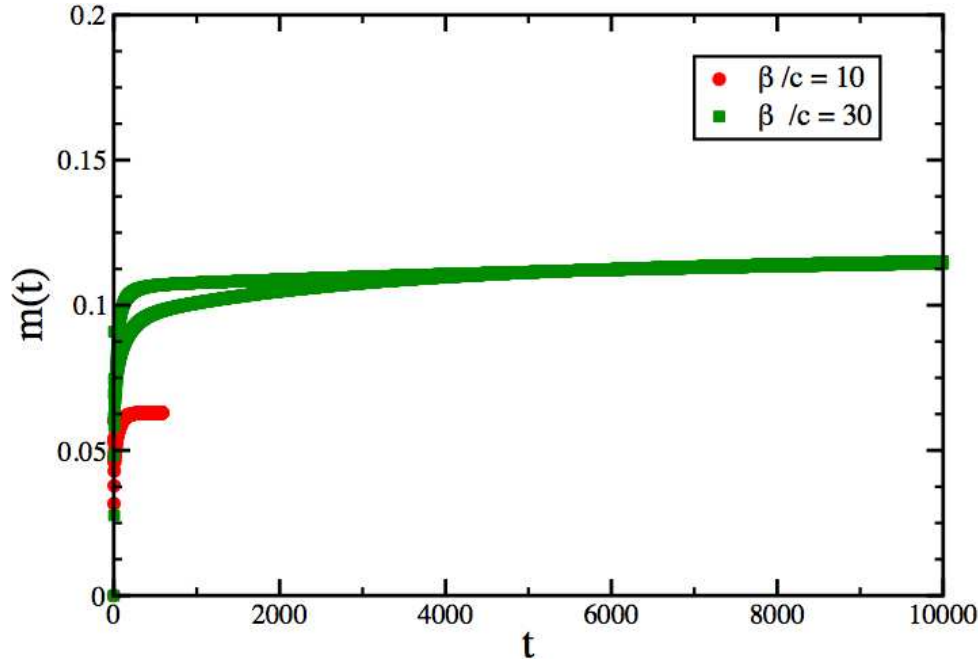
$$\frac{e^{\beta h_i^{(j)}(t) \sigma_i(t)}}{2 \cosh(\beta h_i^{(j)}(t))} m_{i \rightarrow j}(\sigma_i(t-2)) + \left(1 - \frac{1}{N}\right) \sum_{\sigma_i(t-1)} m_{i \rightarrow j}(\sigma_i(t-1)) \delta_{\sigma_i(t), \sigma_i(t-1)}$$

Aurell, Mahmoudi (2010)

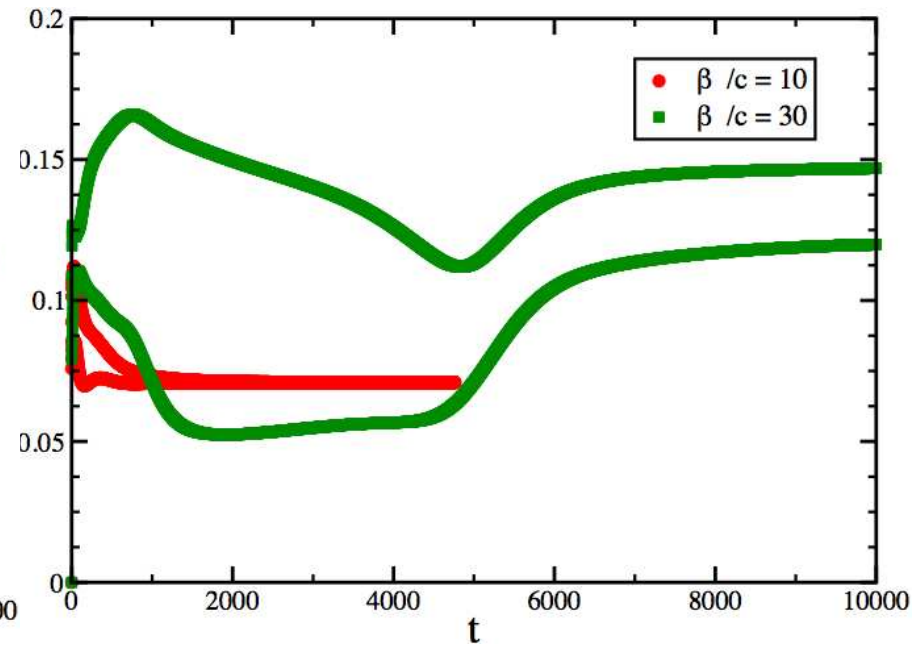
Comparing dynamic cavity equations to Monte Carlo

work in progress...

Parallel updates, different temperatures



fully asymmetric

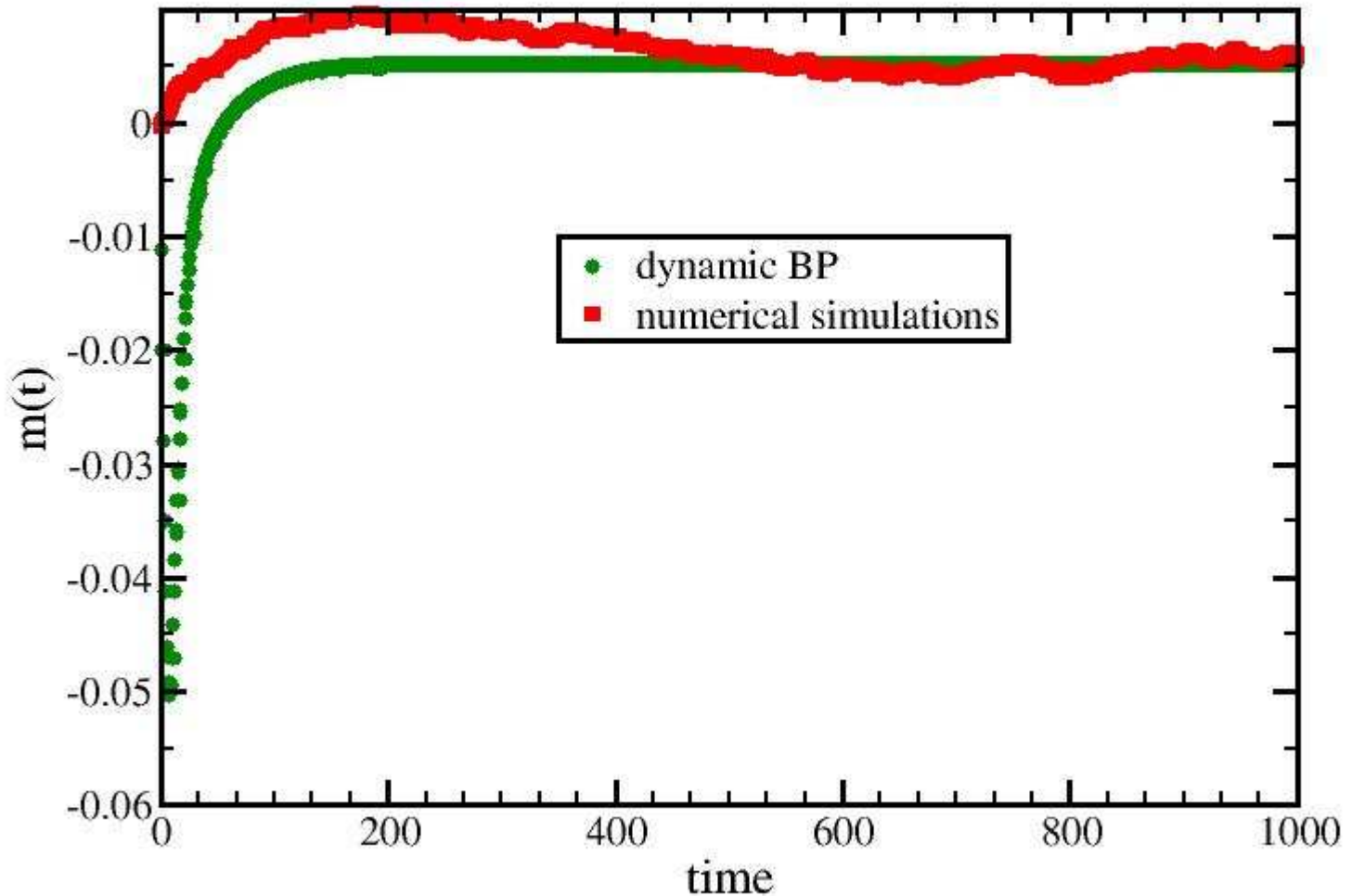


fully symmetric

Average magnetization measured

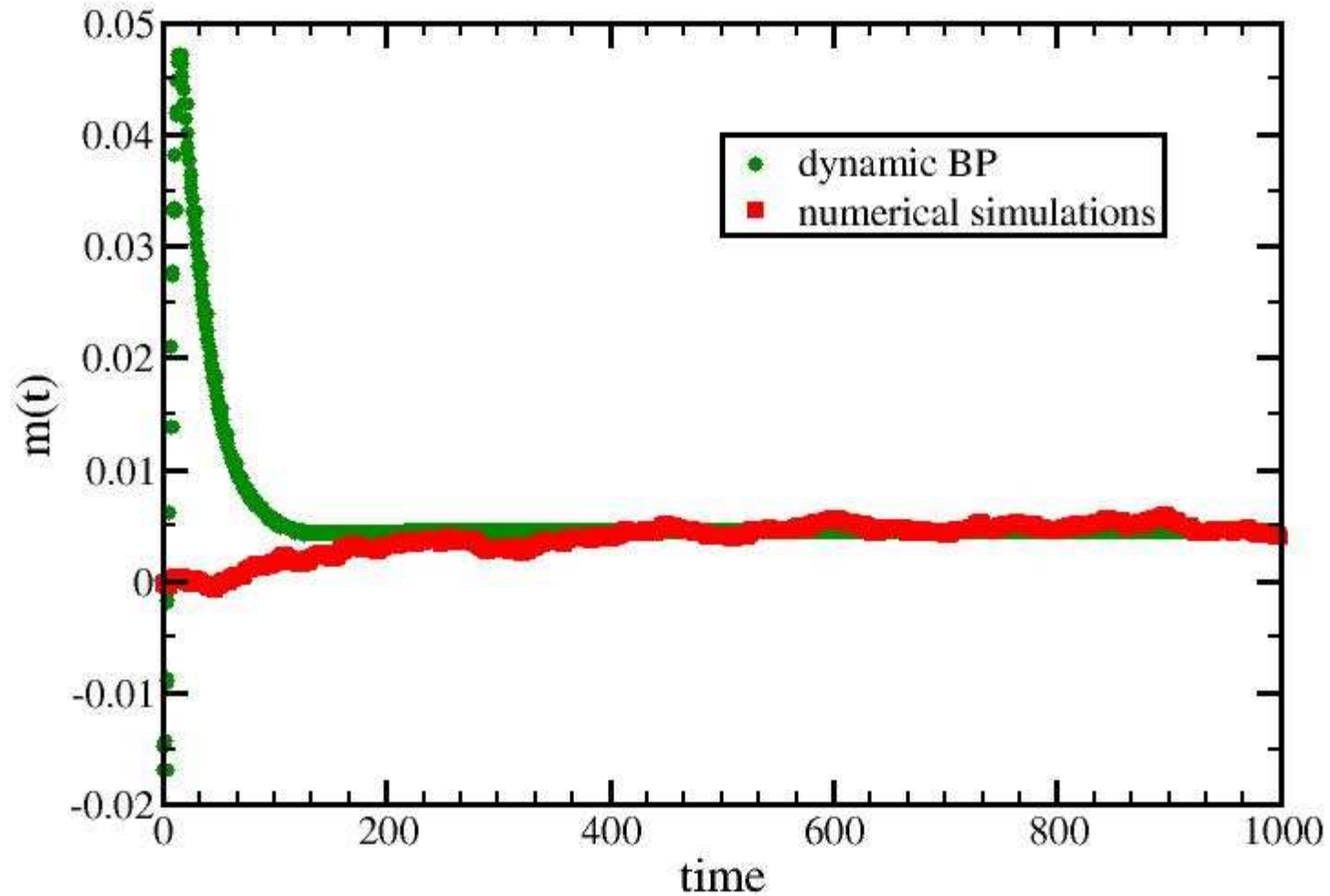
$$m(t) = \frac{1}{N} \sum_{i=1}^N m_i(t)$$

Sequential updates, $N=100$, $\beta=15$, $c=3$

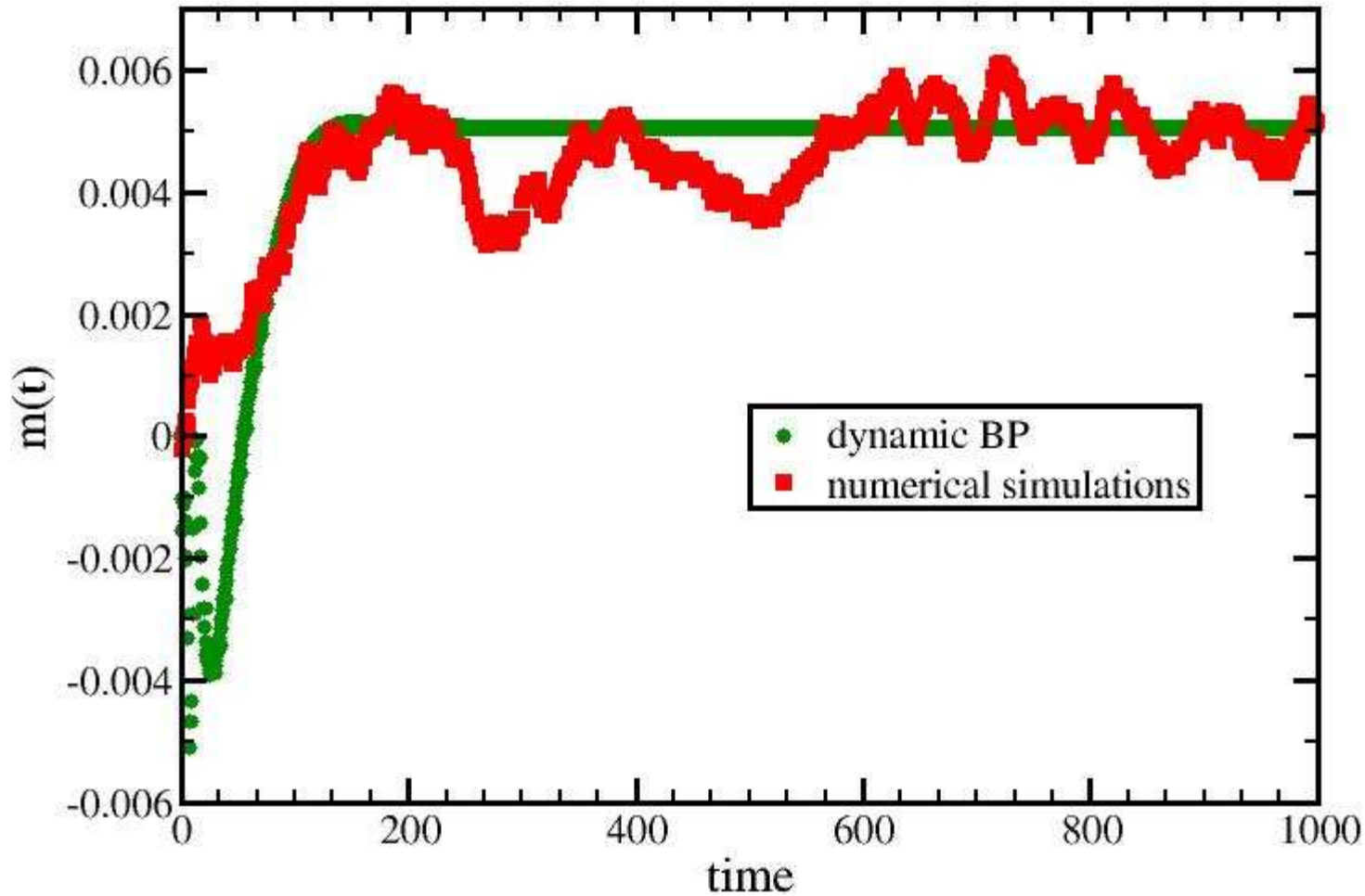


Monte Carlo averaged over very many realizations.
Dynamic cavity method run once.

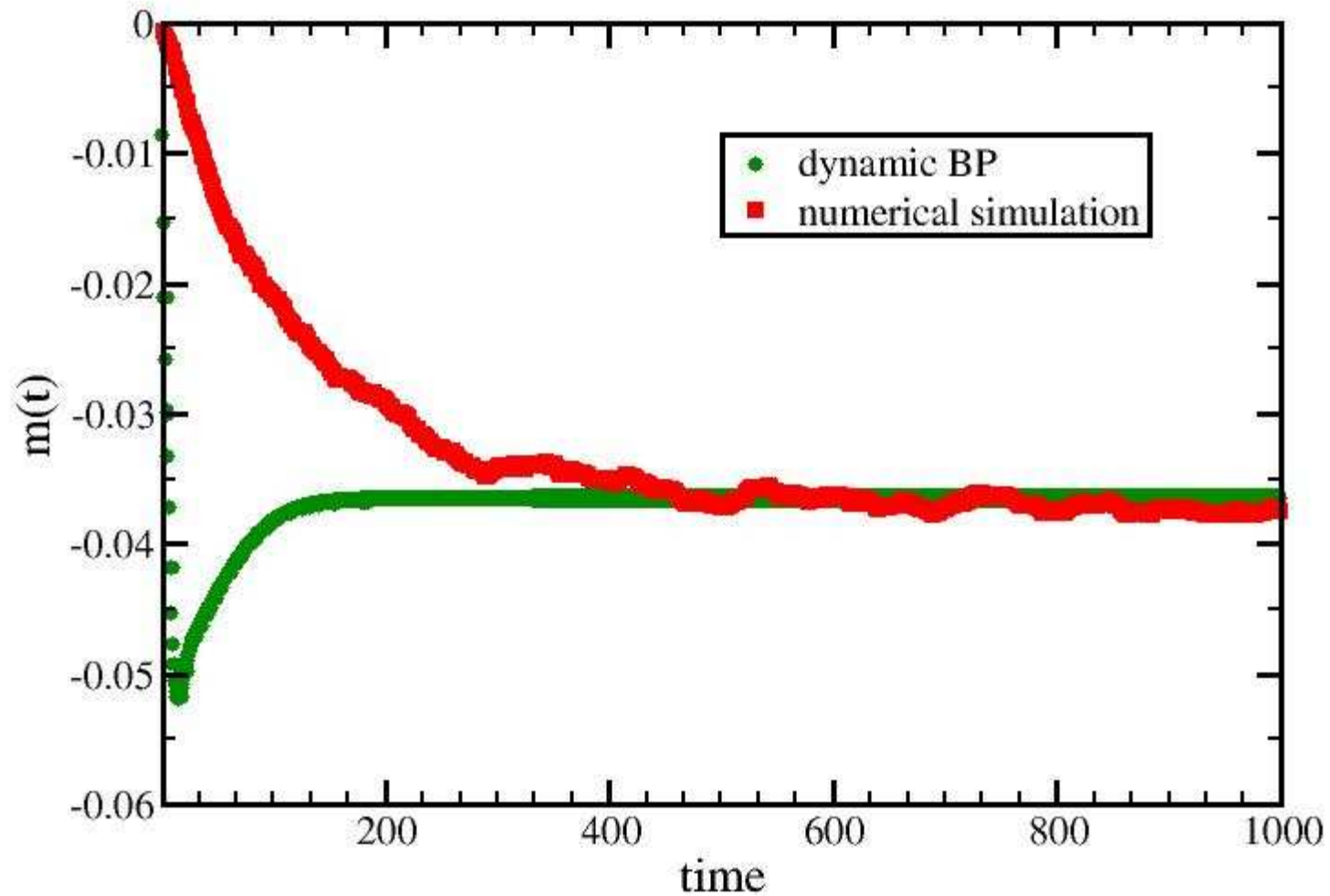
Some more sequential update cases....



Yet some more sequential update cases....



And yet more still.

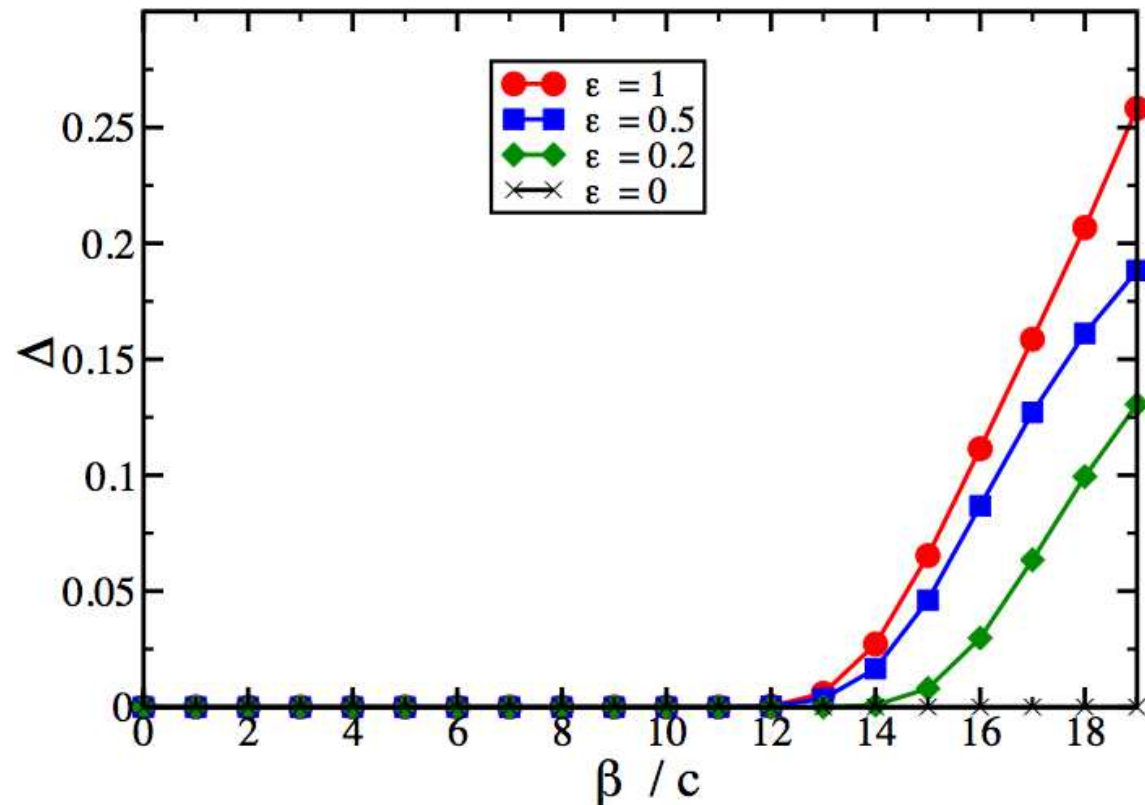


There seems to be
something to it.

Therefore...to be continued...

Parallel updates can have cyclic behaviour

$$\Delta(t) = \frac{1}{N} \sum_{i=1}^N (m_i(t) - m_i(t-1))^2$$





KTH/CSC

Thanks