

Time scales, persistence, and dynamic multiscaling in homogeneous, isotropic fluid turbulence

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19 October 2011 NORDITA, Stockholm.





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Many happy returns of the day!





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- This work has been done with
 - Dhrubaditya Mitra
 - Prasad Perlekar
 - Samriddhi Sankar Ray
- ► Support: CSIR, DST, UGC (India) and SERC (IISc)

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- Long residence time of tracers in vortical regions.
- ► $\tau_{\ell} \sim \ell^{z}$

• K41:
$$\tau_{\ell} \sim \ell/v_{\ell} \sim \ell^{2/3} \Rightarrow z^{K41} = 2/3.$$

• Mean flow: $\ell = U\tau_{\ell} \Rightarrow z = 1$ (Heisenberg and Onsager).

Outline



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- Two-dimensional turbulence in soap films :
 - Persistence
- Multiscaling in homogeneous, isotropic, turbulence:
 - Structure functions;
 - Kolmogorov 1941 simple scaling;
 - Multiscaling and dynamic multiscaling.
- Conclusions.



Two-dimensional turbulence in soap films.







Cardoso, B. Gluckmann, O. Parcollet, and P. Tabeling, Phys. Fluids **8** (1), 1996.

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Two-dimensional turbulence:



$$D_t \mathbf{u} = -\nabla p + v \nabla^2 \mathbf{u},$$
 (1)
 $\nabla \mathbf{u} \equiv \mathbf{0}$

or

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• No vortex stretching, $\omega \cdot \nabla \mathbf{u}$ is absent.



Conservation laws:



• Energy conservation in the inviscid, unforced limit.

$$\partial_t E = -2\nu\Omega, \qquad (3)$$
$$E = 1/2 \int_{\mathbf{x} \in \mathbb{R}^3} |\mathbf{u}|^2,$$
$$\Omega = 1/2 \int_{\mathbf{x} \in \mathbb{R}^3} |\omega|^2, \qquad (4)$$

Enstrophy conservation in the inviscid, unforced limit.

$$\partial_t \Omega = -2\nu P,$$
 (5)
 $P = 1/2 \int_{\mathbf{x} \in \mathbb{R}^3} |\nabla \times \omega|^2.$ (6)

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Cascades



[Kraichnan, Phys. Fluids, **10**, (1967*a*), Batchelor, Phys. Fluids Suppl. *II*, **12**, (1969)]

- Energy injected at a length scale l_{inj} will inverse-cascade to large length scales with $E(k) \sim k^{-5/3}$.
- ► Energy injected at a length scale *l_{inj}* will forward-cascade to small length scales with *E(k)* ~ *k*⁻³.



Electromagnetically forced soap films



[M. Rivera, Ph.D. Thesis, arXiv:physics/010305v1]



Soap film: 400ml distilled water + 40ml glycerol + 5ml commercial liquid detergent,

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- The soap film is suspended on a rectangular frame,
- The magnetic array produces a Kolmogorov forcing $F_x = F_0 sin(k_y y)$.

Modelling soap films: Incompressible limit



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[Chomaz et al., PRA, **41**, (1990), Chomaz, JFM, (2001), P. Fast, arXiv:physics/0511175v1, (2005).]

- ► Mach Number M_e ≡ u_{rms}/c, where c is the speed of the sound in the soap films. For the experiments with electromagnetically forced soap films M_e ~ 0.06.
- To leading order soap-film behaviour is governed by the Navier-Stokes (NS) equations in two dimensions + an air drag

$$D_t \mathbf{u} = \mathbf{v} \nabla^2 \mathbf{u} - \nabla p - \alpha \mathbf{u},$$

$$\nabla \cdot \mathbf{u} = 0.$$

• $D_t \equiv \partial_t + \mathbf{u} \cdot \nabla$, $p \equiv$ pressure, and $\mathbf{u} \equiv$ the velocity

Direct Numerical Simulation(DNS)



Vorticity-streamfunction formulation:

$$D_t \omega = \nu \nabla^2 \omega - \alpha \omega,$$

$$\nabla^2 \psi = \omega,$$

$$u_x = -\partial_y \psi, u_y = \partial_x \psi.$$

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- Incompressibility satisfied by construction.
- No-slip boundary condition on the walls.



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- Impose the Kolmogorov forcing $F_y = F_0 \sin(k_x x)$ at all times.
- Study the evolution of the energy E and the dissipation rate ε with α and ν.
- Study velocity and vorticity structure functions.
- Study the topological properties via PDFs of the Weiss parameter Λ.

Evolution of energy and dissipation



Time evolution of E(t)/E' [(a) and (b)], $\epsilon(t)/\epsilon'$ [(c) and (d)], and $\epsilon_e(t)/\epsilon'$ [(e) and (f)].



In (a), (c), and (d) we keep \mathcal{G} fixed and vary γ ($\gamma = 0.25$ (red lines with circles) and $\gamma = 0.71$ (black line)). In (b), (d), and (f) we maintain $Re \simeq 21.2$ and vary γ ($\gamma = 0.25$ (red lines with circles) and $\gamma = 0.71$ (black line with squares)).

Pseudocolor plots





Pseudocolor plots of (a) $S_2(\mathbf{r_c}, \mathbf{R})$, for $\mathbf{r_c} = (2, 2)$, (b) $S_2(R)$ (average of $S_2(\mathbf{r_c}, \mathbf{R})$ over $\mathbf{r_c}$), (c) $S_2^{\omega}(\mathbf{r_c}, \mathbf{R})$, for $\mathbf{r_c} = (2, 2)$, and (d) $S_2^{\omega}(R)$ (average of $S_2^{\omega}(\mathbf{r_c}, \mathbf{R})$ over $\mathbf{r_c}$).

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Velocity Structure Functions





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Vorticity Structure Functions





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Distribution of centers and saddles



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- A. Okubo, Deep-Sea Res. **17**, 17 (1970), J. Weiss, Physica, **48D**, 273 (1991).
 - Local flow topology determined by

$$\Lambda \equiv \left| \begin{array}{c} \partial_x u_x & \partial_x u_y \\ \partial_y u_x & \partial_y u_y \end{array} \right| \text{ and }$$

 $D \equiv \nabla \cdot \mathbf{u}$

- For incompressible flows, D = 0
- $\Lambda = (\omega^2 \sigma^2)/4, \ \omega^2 \equiv \sum_{i,j} (\partial_i u_j \partial_j u_i)^2/2,$ $\sigma^2 \equiv \sum_{i,j} (\partial_i u_j + \partial_j u_i)^2/2.$
- ► At a point (x, y), $\Lambda(x, y) > 0 \implies$ centers, and $\Lambda(x, y) < 0 \implies$ saddles.

ψ and Λ





• Contours of ψ overlayed on the pseudocolor plot of Λ .

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- ► Λ > 0(centers)
- ► Λ < 0(saddles)</p>

PDF of Λ : fixed Re





- runs R4 and R6
- Left: Our DNS. $\gamma = 0.25(red)$, $\gamma = 0.71(blue)$.
- Right: Experiments. $\gamma = 0.28$ (diamond), $\gamma = 0.56$ (triangle), $\gamma = 0.97$ (circle).

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PDF of Λ : fixed Re





- runs R4 and R6
- PDF normalized by Λ_{rms} .
- Left: Our DNS. $\gamma = 0.25(red)$, $\gamma = 0.71(blue)$.
- Right: Experiments. γ = 0.28(diamond), γ = 0.56(triangle), γ = 0.97(circle).

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Persistence problem



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- Satya N. Majumdar, Persistence in Nonequilibrium Systems, Curent Science, 77, 370 (1999); cond-mat/9907407v1 Let φ(x, t) be a nonequilibrium field fluctuating in space and time according to some dynamics. Persistence is simply the probability P₀(t) that, at a fixed point in space, the quantity sgn[φ(x, t) - ⟨φ(x, t)⟩] does not change upto time t.
- $P^{\varphi}(\tau) \sim \tau^{-\beta}$ as $\tau \to \infty$, where β is the *persistence exponent*.

The Okubo-Weiss parameter



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- From the velocity-gradient tensor A, with components A_{ij} ≡ ∂_iu_j, we obtain the Okubo-Weiss parameter Λ, the discriminant of the characteristic equation for A.
- ► If A is positive (negative) then the flow is vortical (extensional).
- In an incompressible flow in two dimensions A = detA; and the PDF of A has been shown to be asymmetrical about A = 0 (vortical regions are more likely to occur than strain-dominated ones).

Motivation



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- Note $\langle \Lambda \rangle = 0$.
- ► How long does a Lagrangian particle stay in region where $\Lambda > 0$ (center) or where $\Lambda < 0$ (saddle).
- How long does the Λ field not change sign at a position (x, y)
 i.e., persistence time of a center or a saddle.

Persistence in two-dimensional turbulence



- Lagrangian persistence: We follow N_p particles and evaluate Λ along their trajectories.
- Eulerian persistence: We monitor the time evolution of Λ at N positions in the simulation domain.
- For both the cases we find the time-intervals τ over which Λ > 0 or Λ < 0. The PDF of these intervals characterizes the analog of persistence in two dimensional turbulence.

Persistence-time PDF



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- We denote the persistence-time PDFs by P; the subscripts E and L on these PDFs signify Eulerian and Lagrangian frames, respectively; and the superscripts + or - distinguish PDFs from vortical points from those from extensional ones.
- To find out the persistence-time PDF P⁺_E(τ) [resp., P⁻_E(τ)] we analyse the time-series of Λ obtained from each of the N_p Eulerian points and construct the PDF of the time-intervals τ over which Λ remains positive (resp., negative).
- ► The same method applied to the time series of Λ, obtained from each of the N_p Lagrangian particles, yields P⁺_L(τ) [resp., P⁻_L(τ)].

Simulation details



N	ν	μ	F ₀	k_{inj}	I _d	λ	Re_{λ}	$T_{\rm E}^{-}$	$T_{\rm L}^{-}$	$T_{\rm E}^+$
512	0.016	0.1	45	10	0.023	0.17	59.2	0.6	0.12	0.34
512	0.016	0.45	45	10	0.021	0.11	26.8	0.4	0.15	0.28
1024	10^{-5}	0.01	0.005	10	0.0043	0.125	827.3	20.0	9.9	14.28
1024	10^{-5}	0.01	0.005	4	0.0054	0.198	1318.8	33.3	12.5	25.0



Time series of Λ



Lagrangian versus Eulerian frame



- Lagrangian A tracks (red) show rapid fluctuations in comparison to the corresponding Eulerian tracks (black).
- Autocorrelation $C_{\Lambda} = \langle \Lambda(t_0) \Lambda(t_0 + t) \rangle$ decays faster for the Lagrangian case.

Persistence: particle in a vortex





Re = 59.2, *k_{inj}* = 10, α = 0.1 (×), *Re* = 26.8, *k_{inj}* = 10, α = 0.45 (□), *Re* = 827.3, *k_{inj}* = 4, α = 0.01 (△), *Re* = 1318.8, *k_{inj}* = 10, α = 0.01 (+).

Persistence: particle in a vortex





- $P^{C}(\tau) = \tau^{-(\beta-1)}$, $\beta = 2.9 \pm 0.2$.
- Independent of *Re*, k_{inj} , and α

Persistence: particle in a region of strain





 Lin-log plot of the persistence time of the particle in a region of strain.

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Persistence: Region of vorticity at (x, y)





► Lin-log plot of the persistence time of the region of vorticity at position (x, y).

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Persistence: Region of strain at (x, y)





Lin-log plot of the persistence time of the region of strain at position (x, y).

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Conclusion



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- The Okubo-Weiss parameter provides us with a natural way of formulating and studying the persistence problem in two-dimensional fluid turbulence.
- The persistence-time PDF of Lagrangian particles in vortical and strain-dominated regions are different.
- The persistence-time PDF of Lagrangian particles in vortical regions show a power-law tail with an exponent β = 2.9.
- ► The persistence-time PDF of Lagrangian particles in strain-dominated regions shows an exponential tail.


Multiscaling in Fluid and Passive-Scalar Turbulence



Multiscaling in homogeneous, isotropic, turbulence:



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- Structure functions;
- Kolmogorov 1941 simple scaling;
- multiscaling and dynamic multiscaling;
- passive-scalar turbulence.

Critical Phenomena



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$\Gamma(\mathbf{r}, \mathbf{t}, \mathbf{h}) \approx \frac{1}{r^{d-2+\eta}} \mathcal{F}(t^{\nu} \xi, \mathbf{h}/t^{\Delta})$

- r: separation between the spins in d dimensions
- $\bullet \ t \equiv (T T_c)/T_c$
- $h \equiv H/k_B T_c$
- *k_B*: Boltzmann constant
- ► T: temperature
- *T_c*: critical temperature
- H: magnetic field
- ξ: correlation length (diverges at criticality)
- η , ν and Δ : static critical exponents
- ► *F*: universal scaling function

Critical Phenomena

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In Fourier space $\tilde{\Gamma}(q, t, h) \approx \frac{1}{q^{2-\eta}} \mathcal{F}(t^{\gamma}\xi, h/t^{\Delta});$ \vec{q} : wave vector with magnitude qDynamic scaling for time-dependent correlation functions in the vicinity of a critical point. $\tilde{\Gamma}(q, \omega, t, h) \approx \frac{1}{q^{2-\eta}} \mathcal{G}(q^{-z}\omega, t^{\gamma}\xi, h/t^{\Delta});$

- z: dynamic critical exponent
- ω: frequency
- \mathcal{G} : a scaling function

Relaxation time τ diverges as

 $\tau \sim \xi^z$.

Equal-Time Structure Functions

Order-p, equal-time, structure functions:

$$S_{p}(r) \equiv \langle [\delta u_{\parallel}(\vec{x},\vec{r},t)]^{p} \rangle \sim r^{\zeta_{p}}$$

$$\delta u_{\parallel}(\vec{x},\vec{r},t) \equiv \left[\vec{u}(\vec{x}+\vec{r},t) - \vec{u}(\vec{x},t)\right] \cdot \frac{\vec{r}}{r}$$

 η_d : Kolmogorov dissipation scale;

L: large length scale at which energy is injected into the system.

- Experiments favour multiscaling: ζ_p a nonlinear, convex monotone increasing function of p.
- Simple-scaling prediction of Kolmogorov: $\zeta_p^{K41} = p/3$.



Introduction : Frames of Reference



Eulerian :

The Navier-Stokes equation is written in terms of the Eulerian velocity \mathbf{u} at position \mathbf{x} and time t. In the Eulerian case the frame of reference is fixed with respect to the fluid;

Lagrangian :

Frame of reference fixed to a fluid *particle*; this fictitious particle moves with the flow and its path is known as a Lagrangian trajectory.

$$\mathbf{v} = \left(\frac{d\mathbf{R}}{dt}\right)_{\mathbf{r}_0};$$

Quasi-Lagrangian :

It uses the following transformation for an Eulerian field $\psi(\mathbf{r}, t)$:

$$\hat{\psi}(\mathbf{r},t) \equiv \psi[\mathbf{r} + \mathbf{R}(t;\mathbf{r_0},0),t].$$

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Time-Dependent Structure Functions



▶ The order-*p*, time-dependent longitudinal structure function:

 $\mathcal{F}_{p}(r,\{t_{1},\ldots,t_{p}\}) \equiv \langle [\delta u_{\parallel}(\vec{x},t_{1},r)\ldots\delta u_{\parallel}(\vec{x},t_{p},r)] \rangle$

For simplicity we consider $t_1 = t$ and $t_2 = \ldots = t_p = 0$.

► Given *F*(*r*, *t*), different ways of extracting time scales yield different exponents that are defined via dynamic-multiscaling ansätze:

$$\mathcal{T}_p(r) \sim r^{z_p}.$$

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The evolution equation for the GOY shell model takes the form,

$$\left[\frac{d}{dt} + \nu k_n^2\right]u_n = i(a_n u_{n+1} u_{n+2} + b_n u_{n-1} u_{n+1} + c_n u_{n-1} u_{n-2})^* + f_n.$$

► In the shell model equation,

•
$$k_n = k_0 2^n$$
, where $k_0 = 1/16$;

►
$$a_n = k_n$$
, $b_n = -\delta k_{n-1}$, $c_n = -(1 - \delta)k_{n-2}$, where $\delta = 1/2$.

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Simulation Details



- We use the slaved Adams-Bashforth scheme to integrate the GOY shell model equation with 22 shells.
- We use $\delta t = 10^{-4}$ and $\nu = 10^{-7}$.
- For statistically steady turbulence, we use external forcing to drive the system.
- We study decaying turbulence by using two kinds of initial conditions:
 - 1. a random configuration where all the energy is concentrated at large length scales;
 - 2. a configuration obtained from a statistically steady turbulent state.

Details: Forced Turbulence



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- We start from an initial condition where all the energy is concentrated in the large length scales, i.e., v_n⁰ = k_n^{-1/3}e^{iθ_n} (for n = 1,2) and v_n⁰ = 0 (for n = 3 to 22), with θ_n a random phase angle distributed uniformly between 0 and 2π.
- ► The system is then driven to a statistically steady state with a force $f_n = \delta_{n,1}(i+i) \times 5 \times 10^{-3}$.
- All measurements are made once the system reaches a statistically steady state.

Details: Decaying Turbulence



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- ► For the first initial condition we use $v_n^0 = k_n^{1/2} e^{i\theta_n}$ (for n = 1,2) and $v_n^0 = k_n^{1/2} e^{-k_n^2} e^{i\theta_n}$ (for n = 3 to 22) with θ_n a random phase angle distributed uniformly between 0 and 2π .
- ► For the second initial condition, we first achieve a forced statistically steady state, with $f_n = \delta_{n,1}(i+i) \times 5 \times 10^{-3}$. The force is then switched off at some time origin t_0 and the system is allowed to decay freely.
- Our exponents are independent of the kind of initial condition we choose.

Error Estimates (GOY)



- Static solution exhibit a 3-cycle in the shell index *n*.
- Obtain 50 different values of each of the exponents from 50 independent simulations.
- Time-averaging is done over a time T_{av} = 10⁵ × τ_L to obtain the results for statistically steady state quantities. For decaying turbulence, we average over 20000 statistically independent initial configurations.
- The means of these 50 values for each of the dynamic-multiscaling exponents are shown in figure and the standard deviation yields error.
- This averaging is another way of removing the effects of the 3-cycle mentioned above.

Principal Results: Fluid Turbulence



- ► Simple dynamic scaling for Eulerian-velocity structure functions (z^E_p = 1).
- Dynamic multiscaling is obtained for Lagrangian or Quasi-Lagrangian structure functions.
- ► Dynamic multiscaling exponents z_p depend on how T_p(r) is extracted.
- z_p is related to the equal-time exponents via bridge relations.
- Universality of dynamic exponents: the same for decaying and statistically steady turbulence.

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Integral Time Scale



From the longitudinal, time-dependent, order-p structure functions, the order-p, degree-M, integral time scale is defined as,

$$\mathcal{T}_{p,M}^{I}(r) \equiv \left[\frac{1}{\mathcal{S}_{p}(r)} \int_{0}^{\infty} \mathcal{F}_{p}(r,t) t^{(M-1)} dt\right]^{(1/M)}$$

• The integral dynamic multiscaling exponent $z_{p,M}^{l}$ is defined as

$$\mathcal{T}^{I}_{p,M}(r) \sim r^{z^{I}_{p,M}}.$$

Derivative Time Scale



 Similarly, the order-p, degree-M derivative time scale is defined as

$$\mathcal{T}_{\rho,M}^{D}(r) \equiv \left[\frac{1}{\mathcal{S}_{\rho}(r)} \frac{\partial^{M} \mathcal{F}_{\rho}(r,t)}{\partial t^{M}}\right]^{(-1/M)}$$

• The derivative dynamic multiscaling exponent $z_{p,M}^D$ is defined as τD () $z^D u$

$$\mathcal{T}^{D}_{\boldsymbol{p},\boldsymbol{M}}(\boldsymbol{r})\sim \boldsymbol{r}^{\boldsymbol{z}^{D}_{\boldsymbol{p},\boldsymbol{M}}}.$$

Theoretical Prediction



The multifractal model predicts the following bridge relations:

$$z'_{\rho,M} = 1 + \frac{[\zeta_{\rho-M} - \zeta_{\rho}]}{M};$$

$$z_{p,M}^D = 1 + \frac{[\zeta_p - \zeta_{p+M}]}{M}.$$

Extending the Frisch-Parisi Multifractal Model



Dynamic Structure Functions

$$\mathcal{F}_{p}(\ell,t) \propto \int_{\mathcal{I}} d\mu(h)(\frac{\ell}{L})^{\mathcal{Z}(h)} \mathcal{G}^{p,h}(\frac{t}{\tau_{p,h}}),$$

where $\mathcal{G}^{p,h}(\frac{t}{\tau_{p,h}})$ has a characteristic decay time $\tau_{p,h} \sim \ell/\delta v(\ell) \sim \ell^{1-h}$, and $\mathcal{G}^{p,h}(0) = 1$. If $\int_0^\infty t^{(M-1)} \mathcal{G}^{p,h} dt$ exists, then the order-p, degree-M, integral time scale is

$$\mathcal{T}^{\prime}_{
ho,\mathcal{M}}(\ell)\equiv\left[rac{1}{\mathcal{S}_{
ho}(\ell)}\int_{0}^{\infty}\mathcal{F}_{
ho}(\ell,t)t^{(M-1)}dt
ight]^{(1/M)}.$$

* V.S. L'vov, E. Podivilov, and I. Procaccia, Phys. Rev. E **55**,7030 (1997).

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Multifractal Model



$$\mathcal{T}_{p,1}^{\prime}(\ell) \equiv \left[\frac{1}{\mathcal{S}_{p}(\ell)} \int_{0}^{\infty} \mathcal{F}_{p}(\ell, t) dt\right]^{(1/M)}$$

$$\propto \left[\frac{1}{\mathcal{S}_{p}(\ell)} \int_{\mathcal{I}} d\mu(h) (\frac{\ell}{L})^{\mathcal{Z}(h)} \int_{0}^{\infty} dt \mathcal{G}^{p,h}(\frac{t}{\tau_{p,h}})\right]$$

$$\propto \left[\frac{1}{\mathcal{S}_{p}(\ell)} \int_{\mathcal{I}} d\mu(h) (\frac{\ell}{L})^{ph+3-D(h)} \ell^{1-h}\right]$$

In the last step, we have used :

$$au_{p,h} \sim \ell/\delta v(\ell) \sim \ell^{1-h}$$

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Multifractal Model



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• Corresponding Bridge Relations :

$$z_{p,1}^{I} = 1 + [\zeta_{p-1} - \zeta_{p}],$$

$$z_{p,2}^D = 1 + [\zeta_p - \zeta_{p+2}]/2.$$

Bridge relations reduce to z_p^{K41} = 2/3 if we assume K41 scaling for the equal-time structure functions.

Numerical studies of dynamic multiscaling



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- L. Biferale, G. Bofetta, A. Celani, and F. Toschi, Physica D 127 187 (1999); this study uses an exit-time method.
- Our group has concentrated on an elucidation of dynamic multiscaling by using time-dependent structure functions and (a) shell models and
 - (b) the two-dimensional Navier-Stokes equation with friction.

In the following slides we give an overview of our results without technical details.

Results





Plots of order-*p* structure functions *vs* the dimensionless time for various shells for statistically steady (left) and decaying (right) turbulence.

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Integral Time Scales





Log-log plots of integral times for statistically steady (left) and decaying (right) turbulence for order-p structure functions; the slopes of these graphs yield $z_{p,1}^{I}$. The integration is carried out over time 0 to t_u , where we choose t_u such that $F_p(n, t_u)$ (or $Q_p(n, t_u)$) = α for all n and p.

Derivative Time Scales





The analogue of the previous figure for derivative time scales yields $z_{p,1}^D$. We use a centered, sixth-order, finite-difference scheme by extending $F_p(n,t)$ (or $Q_p(n,t)$) to negative t via $F_p(n,-t)$ (or $Q_p(n,-t)$) = $F_p(n,t)$ (or $Q_p(n,t)$) to obtain the derivative time scales.

Passive Scalars



- We use two different kinds of velocity fields in the advection-diffusion equation for both statistically steady and decaying turbulence:
 - Model A : The Kraichnan ensemble where each component of u is a zero-mean, delta-correlated Gaussian random variable.

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Model B : Velocities from the GOY shell model.

Principal Results: Passive-Scalars



- Dynamic multiscaling is obtained only if the advecting velocity is intermittent.
- Simple dynamic scaling is obtained for a simple version of the passive-scalar problem (Kraichnan), in which the advecting velocity field is Gaussian, even though equal-time structure functions display multiscaling in this model.
- For intermittent velocity fields, different time scales can be extracted.
- z_p related to ζ_p through bridge relations.
- Universality: Dynamic exponents for decaying and statistically steady passive-scalar turbulence are equal.

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Model A



► The covariance of the field is

$$< u_i(\mathbf{x},t)u_j(\mathbf{x}+\mathbf{r},t') >= 2D_{ij}\delta(t-t')$$

where the Fourier Transform of D_{ij} has the form

$$ilde{D}_{ij}(\mathbf{q}) \propto ig(q^2+rac{1}{L^2}ig)^{-(d+\xi)/2}e^{-\eta q^2}ig[\delta_{ij}-rac{q_iq_j}{q^2}ig].$$

In the limits L $\Gamma\!\!\rightarrow\infty$ and η $\Gamma\!\!\rightarrow$ 0, D_{ij} in real space is

$$D_{ij}(\mathbf{r}) = D^0 \delta_{ij} - \frac{1}{2} d_{ij}(\mathbf{r}))$$

where,

$$d_{ij} = D_1 r^{\xi} \left[(d-1+\xi)\delta_{ij} - \xi \frac{r_i r_j}{r^2} \right]$$

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Passive-scalar shell models



$$\begin{bmatrix} \frac{d}{dt} + \kappa k_n^2 \end{bmatrix} \theta_n = \imath \left[a_n(\theta_{n+1}^* u_{n-1}^* - \theta_{n-1}^* u_{n+1}^*) + b_n(\theta_{n-1}^* u_{n-2}^* + \theta_{n-2}^* u_{n-1}) \right. \\ + c_n(\theta_{n+2}^* u_{n+1} + \theta_{n+1}^* u_{n+2}^*) \right] + f_n,$$

where the asterisks denote complex conjugation, $a_n = k_n/2$, $b_n = -k_{n-1}/2$, and $c_n = k_{n+1}/2$; f_n is an additive force that is used to drive the system to a steady state; the boundary conditions are $u_{-1} = u_0 = \theta_{-1} = \theta_0 = 0$; $u_{N+1} = u_{N+2} = \theta_{N+1} = \theta_{N+2} = 0$.

- For the Kraichnan model, the advecting velocity variables are taken to be zero-mean, white-in-time, Gaussian random complex variables with covariance ⟨u_n(t)u^{*}_m(t')⟩ = C₂k^{-ξ}_nδ_{mn}δ(t - t').
- ► For a "turbulent" passive-scalar field, the advecting velocity field is a solution of the GOY shell model.

Model A



This model shows multiscaling for equal-time passive-scalar structure functions for $0<\xi<2.$



Dynamic Multiscaling in Passive-Scalars



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Multifractal model predicts:

- $\blacktriangleright \ z^D_{p,M} = 1 \zeta^u_M / M$
- $\blacktriangleright z_{p,M}^{I} = 1 |\zeta_{-M}^{u}|/M$
- Breakdown of simple scaling.
- Does structure functions with negative exponents exists?

Analytical and Numerical Results





A comparison of our numerical and analytical results for model A second-order structure function in decaying turbulence.

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- Analytical work shows that for Model A the time-dependent structure functions decay exponentially.
- ► A log-log plot of the characteristic decay time vs the wave vectors yield the dynamic exponent z_p.
- ► It is shown analytically that for all order-*p* time-dependent structure functions, $z_p = 2 \xi$.
- Our numerics support this prediction for decaying passive-scalar fields.

Model A: Numerical Results





A plot of the fourth-order structure function ($\xi = 0.6$) vs time for statistically steady turbulence. The scaling exponent is extracted from the decay constant of the curves.

Model A: Numerical Results





The slope of a log-log plot of the decay constant *vs* the wave-vector yields the dynamic scaling exponent for the fourth-order structure function.



Model A: Numerical Results





A plot of the second-order dynamic structure function for decaying turbulence. The slope of a log-log plot (inset) of the decay time vs the wave-vector yields the dynamic exponent .

Model B: Numerical Results





Plots of the second-order time-dependent structure function vs the dimensionless time for statistically steady (left) and decaying turbulence (right).

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Cumulative pdf for u_m





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Negative Exponents



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- For small $|u_m|$, $P^{cum}[|u_m|] \sim |u_m|^{1.8}$.
- $P[|u_m|] \sim |u_m|^{0.8}$.
- $S_{-1}(m) \equiv \int P[x] \frac{1}{x} dx \sim \int x^{-0.2} dx$ exists.
- But $S_p(m)$ for $p \approx -1.8$ does not.
- $T_{p,M}^{I}$ for M > 2 does not exist.
- Measurement of a static quantity (P(x)) gives us information about existence of a dynamic quantity T^I_{p,M}.

Model B: Integral Time Scale





A log-log plot of the integral time scale vs the wave-vector in decaying turbulence. The linear fit gives us the scaling exponent $z_{p,M}^{l}$.

Derivative Time Scale





A log-log plot of the derivative time scale vs the wave-vector in decaying turbulence. The linear fit gives us the scaling exponent $Z_{p,M}^D$.

Exponents for dynamic multiscaling in shell models



order(<i>p</i>)	ζ_p^u	$z_{p,1}^{I,u}$ [Theory]	$z_{p,1}^{l,u}$	$z_{p,2}^{D,u}$ [Theory]	$z_{p,2}^{D,u}$
1	0.379 ± 0.008	0.621 ± 0.008	0.61 ± 0.03	0.68 ± 0.01	0.699 ± 0.008
2	0.711 ± 0.002	0.66 ± 0.01	0.68 ± 0.01	0.716 ± 0.008	0.723 ± 0.006
3	1.007 ± 0.003	0.704 ± 0.005	0.711 ± 0.001	0.74 ± 0.01	0.752 ± 0.005
4	1.279 ± 0.006	0.728 ± 0.009	0.734 ± 0.002	0.76 ± 0.02	0.76 ± 0.01
5	1.525 ± 0.009	0.75 ± 0.02	0.755 ± 0.002	0.77 ± 0.02	0.77 ± 0.02
6	1.74 ± 0.01	0.78 ± 0.02	0.78 ± 0.03	0.77 ± 0.03	0.78 ± 0.02

order(p)	ζ_p^{Θ}	$z_{p,1}^{I,\theta}$	$z_{p,2}^{D,\theta}$
1	0.342 ± 0.002	0.522 ± 0.002	0.632 ± 0.003
2	0.634 ± 0.003	0.531 ± 0.004	0.647 ± 0.003
3	0.873 ± 0.003	0.553 ± 0.006	0.646 ± 0.003
4	1.072 ± 0.004	0.563 ± 0.003	0.642 ± 0.005
5	1.245 ± 0.004	0.562 ± 0.006	0.643 ± 0.006
6	1.370 ± 0.006	0.576 ± 0.006	0.640 ± 0.005

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Multiscaling and quasi-Lagrangian Structure Functions 2D flows

- Multiscaling in equal-time, Eulerian vorticity structure functions.
- Investigating dynamic-multiscaling in time-dependent, quasi-Lagrangian vorticity structure functions.
- Tracking a single particle in a 2D flow with friction to generate quasi-Lagrangian fields.

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Movie

Steady State quasi-Lagrangian Vorticity Field





A pseudocolor plot of the quasi-Lagrangian vorticity field in the statistically steady state.

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Equal-time Structure Functions





- Left : S₃^ω(**R**) for the quasi-Lagrangian field, obtained by averaging over the centers r_c.
- Right : Scaling exponents for equal-time, vorticity structure functions, for both the Eulerian and quasi-Lagrangian fields.

Time-dependent Structure Functions





A loglog plot of $T'_{2,1}$ versus the separation r; the data points are shown by open red circles and the straight black line shows the line of best fit in the inertial range.

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Effect of Friction





A log-log plot of the energy spectrum versus the wavevector k for various values of μ .

Time-dependent multiscaling exponents





Plots of the vorticity, dynamic-multiscaling, quasi-Lagrangian exponents $z_{p,1}^{I,\mathrm{QL}}$ (open red circles) and $z_{p,2}^{D,\mathrm{QL}}$ (full blue circles) versus p with the error bars

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Exponents from 2D DNS



order(p)	ζ_p^{qL}	$z_{p,1}^{I,qL}$ [Theory]	$z_{p,1}^{I,qL}$	$z_{p,2}^{D, qL}$ [Theory]	$z_{p,2}^{D,qL}$
1	0.625 ± 0.003	0.375 ± 0.007	0.37 ± 0.02	0.541 ± 0.008	0.53 ± 0.02
2	1.131 ± 0.005	0.49 ± 0.02	0.48 ± 0.01	0.618 ± 0.009	0.62 ± 0.2
3	1.541 ± 0.005	0.58 ± 0.01	0.57 ± 0.01	0.66 ± 0.01	0.67 ± 0.01
4	1.895 ± 0.004	0.65 ± 0.01	0.65 ± 0.01	0.675 ± 0.008	0.66 ± 0.03
5	2.222 ± 0.008	0.67 ± 0.01	0.65 ± 0.02	0.70 ± 0.01	0.70 ± 0.02
6	2.544 ± 0.004	0.68 ± 0.01	0.66 ± 0.02	0.71 ± 0.02	0.71 ± 0.03

Conclusions



- ► The calculation of dynamic-multiscaling exponents has been limited so far to shell models for 3D, homogeneous, isotropic fluid and passive-scalar turbulence.
- We have presented the first study of such dynamic multiscaling in the direct-cascade régime of 2D fluid turbulence with friction by calculating both quasi-Lagrangian and Eulerian structure functions.
- Our work brings out clearly the need for an infinity of time scales and associated exponents to characterize such multiscaling; and it verifies, within the accuracy of our numerical calculations, the linear bridge relations for a representative value of µ.
- We find that friction also suppresses sweeping effects so, with such friction, even Eulerian vorticity structure functions exhibit dynamic multiscaling with exponents that are consistent with their quasi-Lagrangian counterparts.