


Worldsheet theories of integrable strings

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Supersymmetric Field Theories

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Worksheet theories of integrable deformations of
 $AdS_3 \times S^3 \times M^4$ strings

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Theme i

Integrability

- Integrability methods for studying superstrings in $AdS_n \times M^{10-n}$ backgrounds have had remarkable success
 - $AdS_5 \times S^5$, $AdS_4 \times \mathbb{CP}^3$ – spectral problem “solved”
 - $AdS_3 \times S^3 \times M^4$, $AdS_2 \times S^2 \times T^6$ – significant progress
 - And more ...
- All have largely the same structure controlled by Yangian symmetry
- Preserve integrability while deforming the background/symmetry in a non-trivial way?

Theme ii

q-deformation

- The symmetry algebra defining the S-matrix of the decompactified light-cone gauge $AdS_5 \times S^5$ superstring can be q-deformed

[Beisert, Koroteev '08]

- Leads to a deformation of the S-matrix

[Beisert, Koroteev '08; BH, Hollowood, Miramontes '11]

- Can consider TBA and finite size spectrum

[Arutyunov, de Leeuw, van Tongeren '12]

- Connection with the Pohlmeyer reduction (relativistic symmetry)

[Pohlmeyer '76, Grigoriev, Tseytlin '07, BH, Tseytlin '11]

- Superstring background described by $q(\eta)$ -deformation

[Delduc, Magro, Vicedo '13 '14, Arutyunov, Borsato, Frolov '13]

Theme iii

$$AdS_3 \times S^3 \times M^4$$

- $M_4 = T^4$ or $S^3 \times S^1$ – for pure RR flux GS action “partly” described by Metsaev-Tseytlin supercoset action

$$\frac{\widehat{G} \times \widehat{G}}{G_0}$$

$$\widehat{G} = PSU(1, 1|2) \text{ or } D(2, 1; \alpha)$$

[Pesando '98, Rahmfeld, Rajaraman '98, Babichenko, Sfefanski, Zarembo '09, Zarembo '10]

- Interpolations to backgrounds supported by pure NSNS flux
 - simplification through NSR description
- black holes / condensed matter / higher spins

Aim

- Some integrable deformations of these models already known
 - Addition of magnetic field (strength controlled by parameter b)

[Cagnazzo, Zarembo '12]

- Symmetric $q(\eta)$ deformation; $\mathcal{U}_q(\widehat{G} \times \widehat{G})$

[Delduc, Magro, Vicedo '13, BH, Roiban, Tseytlin '14]

- Work in progress – can we find a three-parameter deformation?

$$\mathcal{U}_{q_L}(\widehat{G}) \times \mathcal{U}_{q_R}(\widehat{G}) + bH$$

- Hope comes from fact that such a deformation of S^3 exists

[Lukyanov '12, (Fateev '96, Klimcik '08, '14)]

Outline

- The undeformed model
- q_L/q_R -deformation
- Magnetic deformation
- S-matrices
- Comments

Undeformed Lagrangian

- Group-valued field

$$f \in \widehat{G} \times \widehat{G} \quad \longrightarrow \quad \mathcal{J} = f^{-1}df \in \widehat{\mathfrak{g}} \oplus \widehat{\mathfrak{g}}$$

- \mathbb{Z}_4 decomposition of the algebra (P_k projectors)

$$\Omega(\mathfrak{g}_k) = i^k \mathfrak{g}_k \quad [\mathfrak{g}_k, \mathfrak{g}_l] \subset \mathfrak{g}_{k+l \bmod 4} \quad P_k \mathcal{J} \in \mathfrak{g}_k \quad k = 0, 1, 2, 3$$

- Action constructed from the supertrace over products of $P_{1,2,3}(\mathcal{J})$
 - G_0 gauge symmetry, bosonic diagonal subgroup of $\widehat{G} \times \widehat{G}$
- Bosonic piece is just usual coset model for

$$\frac{G \times G}{G_0} \quad (SU(2) \cong S^3 \quad SU(1,1) \cong AdS_3)$$

$$S = \frac{T}{2} \int d^2x (\sqrt{-g} g^{ab} - \epsilon^{ab}) \text{STr} [\mathcal{J}_a P \mathcal{J}_b] \quad P = P_1 + 2P_2 - P_3$$

\mathbb{Z}_4 decomposition

Take an element of the superalgebra

$$\mathcal{A} = \begin{pmatrix} \mathcal{A} & 0 \\ 0 & \tilde{\mathcal{A}} \end{pmatrix} \in \hat{\mathfrak{g}} \oplus \hat{\mathfrak{g}}$$

and decompose

$$\begin{aligned} P_0 \mathcal{A} &= \begin{pmatrix} \mathcal{A}_0 & 0 \\ 0 & \mathcal{A}_0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} P_e(\mathcal{A} + \tilde{\mathcal{A}}) & 0 \\ 0 & P_e(\tilde{\mathcal{A}} + \mathcal{A}) \end{pmatrix} \\ P_1 \mathcal{A} &= \begin{pmatrix} \mathcal{A}_1 & 0 \\ 0 & -i\mathcal{A}_1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} P_o(\mathcal{A} + i\tilde{\mathcal{A}}) & 0 \\ 0 & P_o(\tilde{\mathcal{A}} - i\mathcal{A}) \end{pmatrix} \\ P_2 \mathcal{A} &= \begin{pmatrix} \mathcal{A}_2 & 0 \\ 0 & -\mathcal{A}_2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} P_e(\mathcal{A} - \tilde{\mathcal{A}}) & 0 \\ 0 & P_e(\tilde{\mathcal{A}} - \mathcal{A}) \end{pmatrix} \\ P_3 \mathcal{A} &= \begin{pmatrix} \mathcal{A}_3 & 0 \\ 0 & i\mathcal{A}_3 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} P_o(\mathcal{A} - i\tilde{\mathcal{A}}) & 0 \\ 0 & P_o(\tilde{\mathcal{A}} + i\mathcal{A}) \end{pmatrix} \end{aligned}$$

P_e and P_o are projections onto Grassmann-even and Grassmann-odd subspaces.

[Babichenko, Stefanski, Zarembo '09]

Lax connection

- Compute equations of motion and flatness equation for \mathcal{J}
- Decompose under \mathbb{Z}_4 decomposition: $\mathcal{J} \rightarrow \mathcal{J}_{0,1,2,3}$
- Resulting equations follow from the flatness of the following Lax connection

$$\mathcal{L}_{\pm} = \mathcal{J}_{0\pm} + z^{-1}\mathcal{J}_{1\pm} + z\mathcal{J}_{3\pm} + z^{\pm 2}\mathcal{J}_{2\pm}$$

Symmetric q-deformation

$$S = \frac{T}{2} \int d^2x (\sqrt{-g} g^{ab} - \epsilon^{ab}) S \text{Tr} \left[\partial_a (P_\eta \frac{1}{1 - \frac{\eta}{1-\eta^2} R_f P_\eta} \partial_b) \right]$$

$$P_\eta = (1 - \eta^2)(P_1 - P_3) + 2P_2$$

[Delduc, Magro, Vicedo '13, '14]

- $R_f = \text{Ad}_f^{-1} R \text{Ad}_f$, where R is an antisymmetric constant solution of the (non-split) modified classical Yang-Baxter equation

$$[RM, RN] - R([RM, N] + [M, RN]) = [M, N], \quad M, N \in \hat{\mathfrak{g}} \oplus \hat{\mathfrak{g}},$$

- “Take R to be the restriction to [the real form] of the operator acting on the complexified algebra by $-i$ on generators associated with positive roots, $+i$ on generators associated with negative roots, and 0 on Cartan generators.”
- For reality $\eta \in [0, 1)$ (Pohlmeyer limit given by $\eta \rightarrow i$)

Some comments

- Originates from existence of two compatible Poisson brackets, therefore can take linear combination with arbitrary parameter

[Delduc, Magro, Vicedo '13, '14, Hollowood, Miramontes '14]

- Integrability is preserved by construction
- G_0 gauge symmetry \rightarrow same number of bosonic degrees of freedom
- κ -symmetry \rightarrow same number of fermionic degrees of freedom

**Can we add in appropriate number of flat directions
to give a string in a Type IIB supergravity background?**

- Global symmetry algebra q-deformed, $q = \exp(-\frac{\varkappa}{\Gamma})$

[Delduc, Magro, Vicedo '13, '14]

$$\mathcal{U}_q(\widehat{G} \times \widehat{G})$$

- Natural to write bosonic part of the model in terms of $\varkappa = \frac{2\eta}{1-\eta^2}$

Metric for deformed AdS_3 and deformed S^3

- Choose matrix representative of coset element
- Positive roots to correspond to upper triangular entries, negative to lower
- Invert the operator and compute metric and B-field:

$$ds_{AdS}^2 = -\frac{(1+\rho^2)}{1-\varkappa^2\rho^2} dt^2 + \frac{1}{(1+\rho^2)(1-\varkappa^2\rho^2)} d\rho^2 + \rho^2 d\psi^2$$

$$ds_S^2 = \frac{(1-r^2)}{1+\varkappa^2 r^2} d\varphi^2 + \frac{1}{(1-r^2)(1+\varkappa^2 r^2)} dr^2 + r^2 d\phi^2$$

[Arutyunov, Borsato, Frolov '13, BH, Roiban, Tseytlin '14]

- No magnetic field (total derivative)
- Manifest $U(1)^2$ symmetry in each case
 - Cartans of $SU(2)^2$ and $SU(1,1)^2$, consistent with q-deformation
- Singularity at $\rho = \frac{1}{\varkappa}$

Fermions

- Either need to invert operator including fermionic fields
or solve Type IIB supergravity equations of motion
- Both computationally difficult problems
 - Inverting large matrices with Grassmann odd entries
 - Questions of uniqueness (already for bosonic non-compact sector)
 - Solution of dilaton equation $R + 4\nabla^2\phi - 4(\nabla_m\phi)^2 - \frac{1}{12}H^2_{mnk} = 0$ is not simple
[Delduc, Magro, Vicedo '14]
[Lunin, Roiban, Tseytlin (unpublished)]
- Consider certain limits and truncations ...

Maximal deformation limit

$$\eta \rightarrow 1, \varkappa \rightarrow \infty$$

- **Method 1:** *outside the singularity*

- $\bar{\rho} \equiv \rho^{-1}$, $\bar{\psi} \equiv \varkappa\psi$, $\bar{r} \equiv r^{-1}$, $\bar{\phi} \equiv \varkappa\phi$
- $\varkappa \rightarrow \infty$
- T-duality in $\bar{\psi}$ and $\bar{\phi}$ gives dS_3 and H^3

[BH, Roiban, Tseytlin '14]

- **Method 2:** *inside the singularity*

- First rescale t , ρ , φ and r by \varkappa^{-1}
- $\varkappa \rightarrow \infty$ gives the mirror model of the light-cone gauge superstring
- T-duality in t and φ gives dS_3 and H^3

[Arutyunov, de Leeuw, van Tongeren '14]

- $dS_3 \times H^3 \times T^4$ solution of Type IIB* supergravity

[Hull '98]

Imaginary deformation for $AdS_3 \times S^3$

$$\eta \rightarrow i, \kappa \rightarrow i$$

$$\kappa^2 = -1 + \epsilon^2 \quad t = \epsilon^{-1}x^+ - \epsilon x^- \quad \varphi = \epsilon^{-1}x^+ + \epsilon x^- \quad \epsilon \rightarrow 0$$

- Gives pp-wave type background ($\rho \equiv \tan \alpha$, $r \equiv \tanh \beta$)

$$ds^2 = 4dx^+ dx^- - [\sin^2 \alpha + \sinh^2 \beta] dx^{+2} + ds_{A\perp}^2 + ds_{S\perp}^2$$

$$ds_{A\perp}^2 = d\alpha^2 + \tan^2 \alpha d\psi^2 \quad ds_{S\perp}^2 = d\beta^2 + \tanh^2 \beta d\phi^2$$

- After light-cone gauge-fixing we find the following relativistic model

$$\partial_+ \alpha \partial_- \alpha + \tan^2 \alpha \partial_+ \psi \partial_- \psi + \mu^2 \sin^2 \alpha + \partial_+ \beta \partial_- \beta + \tanh^2 \beta \partial_+ \phi \partial_- \phi + \mu^2 \sinh^2 \beta$$

- complex sine-Gordon + complex sinh-Gordon, Pohlmeyer reduction of $AdS_3 \times S^3$

Imaginary deformation – supergravity solution

- Metric on previous slide can be extended to solution of 6-d supergravity supported by RR 3-form flux

[BH, Roiban, Tseytlin '14]

$$u = \sin \alpha e^{i\psi} \quad w = \sinh \beta e^{i\phi}$$

$$\Phi = \Phi_0 - \frac{1}{2} \log(1 - |u|^2) - \frac{1}{2} \log(1 + |w|^2)$$

$$C_2 = \frac{i}{2} e^{-\Phi_0} [(1 + |w|^2)(ud\bar{u} - \bar{u}du) + (1 - |u|^2)(wd\bar{w} - \bar{w}dw)] \wedge dx^+$$

- Solution + T^4 can be extended to 10-dimensional Type IIB supergravity
- Taking GS action and fixing light-cone gauge, we recover Pohlmeyer reduction of $AdS_3 \times S^3$ superstring
- Expansion of coset still needs to be checked

[Grigoriev, Tseytlin '08]

Asymmetric q-deformation

$$S = \frac{T}{2} \int d^2x (\sqrt{-g} g^{ab} - \epsilon^{ab}) \text{STr} \left[\mathcal{J}_a (P_{\eta_{L,R}} \frac{1}{1 - I_{\eta_{L,R}} R_f P_{\eta_{L,R}}} \mathcal{J}_b) \right]$$

$$P_{\eta_{L,R}} = \sqrt{1 - \eta_L^2} \sqrt{1 - \eta_R^2} (P_1 - P_3) + 2P_2$$

$$I_{\eta_{L,R}} = \frac{1}{\sqrt{1 - \eta_L^2} \sqrt{1 - \eta_R^2}} \begin{pmatrix} \eta_L \mathbf{1} & 0 \\ 0 & \eta_R \mathbf{1} \end{pmatrix}$$

[BH (unpublished)]

- Model is classically integrable
- G_0 gauge symmetry \rightarrow same number of bosonic degrees of freedom
- κ -symmetry \rightarrow same number of fermionic degrees of freedom

Can we add in appropriate number of flat directions to give a string in a Type IIB supergravity background?

- Conjecture that the global symmetry algebra q-deformed, $q_{L,R} = \exp(-\frac{\kappa_{L,R}}{T})$

$$\mathcal{U}_{q_L}(\widehat{G}) \times \mathcal{U}_{q_R}(\widehat{G})$$

Metric for asymmetrically deformed S^3

- Bosonic model naturally written in terms of

$$\varkappa_{L,R} = \frac{\eta_{L,R}}{\sqrt{1 - \eta_L^2} \sqrt{1 - \eta_R^2}}$$

- Deformation of the three-sphere:

$$ds^2 = \frac{4}{4 + (\varkappa_L - \varkappa_R)^2 + 4\varkappa_L \varkappa_R r^2} \left[\frac{dr^2}{1 - r^2} + \frac{1}{2} r^2 (1 - r^2) (\varkappa_L^2 - \varkappa_R^2) d\varphi d\phi \right. \\ \left. + (1 - r^2) \left(1 + \frac{1}{4} (1 - r^2) (\varkappa_L - \varkappa_R)^2 \right) d\varphi^2 + r^2 \left(1 + \frac{1}{4} r^2 (\varkappa_L + \varkappa_R)^2 \right) d\phi^2 \right]$$

- No magnetic field (total derivative)
- Manifest $U(1)^2$ symmetry
 - Cartan subalgebra of $SU(2)^2$, consistent with q-deformation

Some comments

- Corresponding bosonic sigma model is known:
 - integrable deformation of the $O(4)$ sigma model preserving $U(1)^2$ symmetry, preserved under RG flow [Fateev '96]
 - $SU(2)$ case of the bi-Yang-Baxter sigma model (Poisson-Lie deformation of $SU(2)$ principal chiral model) [Klimcik '02, '08, '14]
 - vanishing magnetic field case of Lukyanov's three parameter deformation of the $O(4)$ sigma model. [Lukyanov '14]

- Limits:
 - $\varkappa_L = 0$ or $\varkappa_R = 0$ gives squashed S^3 [Cherednik '81]
 - $\varkappa_L = \pm \varkappa_R$ gives symmetric q-deformation

- $\varkappa_L = \varkappa_R = 0, \infty$ are IR and UV asymptotics, $\varkappa_L = \varkappa_R = i$ is UV fixed point

Lax connection

- Compute equations of motion and flatness equation for \mathcal{J}
- Change of variables

$$\mathcal{K}_- = \frac{1}{1 - I_{\eta_{L,R}} R_f P_{\eta_{L,R}}} \mathcal{J}_-, \quad \mathcal{K}_+ = \frac{1}{1 + I_{\eta_{L,R}} R_f \tilde{P}_{\eta_{L,R}}} \mathcal{J}_+$$

- Decompose under \mathbb{Z}_4 decomposition: $\mathcal{K} \rightarrow \mathcal{K}_{0,1,2,3}$
- Resulting equations follow from the flatness of the following Lax connection

$$\mathcal{L}_\pm = \mathcal{K}_{0\pm} + \bar{\eta} \mathcal{K}_{2\pm} + \hat{\eta} z^{\pm 2} \mathcal{K}_{2\pm} + \hat{\eta}^{\frac{1}{2}} [z^{-1} (\eta_+ \mathcal{K}_{1\pm} - \eta_- \mathcal{K}_{3\pm}) + z (\eta_+ \mathcal{K}_{3\pm} - \eta_- \mathcal{K}_{1\pm})]$$

$$\bar{\eta} = \frac{\eta_L^2 - \eta_R^2}{(1 - \eta_L^2)(1 - \eta_R^2)} \quad \hat{\eta} = \frac{1 - \eta_L^2 \eta_R^2}{(1 - \eta_L^2)(1 - \eta_R^2)} \quad \eta_\pm = \frac{\sqrt{1 - \eta_L^2} \pm \sqrt{1 - \eta_R^2}}{2}$$

- Same form as undeformed model

[BH (unpublished)]

- Key point is that we had supercoset based on product supergroup, $\widehat{G} \times \widehat{G}$

Magnetic deformation

$$\begin{aligned}
 S &= \frac{T}{2} \left[\int d^2x (\sqrt{-g} g^{ab} - \epsilon^{ab}) \text{STr} [\partial_a P_b \partial_b] \right. \\
 &\quad \left. - 2b \int d^3x \epsilon^{abc} \widetilde{\text{STr}} \left[\frac{2}{3} (P_2 \partial_a) (P_2 \partial_b) (P_2 \partial_c) + [(P_1 \partial_a), (P_3 \partial_b)] (P_2 \partial_c) \right] \right] \\
 P_b &= \sqrt{1 - b^2} (P_1 - P_3) + 2P_2
 \end{aligned}$$

- parameter b controlling strength of magnetic field [Cagnazzo, Zarembo '12]
- $b \in [0, 1]$, $b = 0$ pure RR flux, $b = 1$ pure NSNS flux
- $\widetilde{\text{STr}}[\mathcal{A}] = \text{STr}[W\mathcal{A}] \quad W = \begin{pmatrix} \mathbf{1} & 0 \\ 0 & -\mathbf{1} \end{pmatrix}$
- Integrable, G_0 gauge symmetry, κ -symmetry, SUGRA background known (S-duality)
- Global $\widehat{G} \times \widehat{G}$ symmetry is undeformed

Lax connection

- Compute equations of motion and flatness equation for \mathcal{J}
- Decompose under \mathbb{Z}_4 decomposition: $\mathcal{J} \rightarrow \mathcal{J}_{0,1,2,3}$
- Resulting equations follow from the flatness of the following Lax connection

$$\mathcal{L}_{\pm} = \mathcal{J}_{0\pm} \pm b\mathcal{J}_{2\pm} + \widehat{b}z^{\pm 2}\mathcal{J}_{2\pm} \\ + \widehat{b}^{\frac{1}{2}} [z^{-1}(b_+\mathcal{J}_{1\pm} + b_-\mathcal{J}_{3\pm}) + z(b_+\mathcal{J}_{3\pm} - b_-\mathcal{J}_{1\pm})]$$

$$\widehat{b} = \sqrt{1 - b^2} \quad b_{\pm} = \sqrt{\frac{1 \pm \sqrt{1 - b^2}}{2}}$$

[Cagnazzo, Zarembo '12]

- Same form as undeformed model
- Again key point is that we had supercoset with product supergroup, $\widehat{G} \times \widehat{G}$
- Shifts in different directions, compared to asymmetric q-deformation, which had shifts in the same direction

Lax connections

Asymmetric q-deformation

$$\mathcal{L}_{\pm} = \mathcal{K}_{0\pm} + \bar{\eta}\mathcal{K}_{2\pm} + \hat{\eta}z^{\pm 2}\mathcal{K}_{2\pm} \\ + \hat{\eta}^{\frac{1}{2}} \left[z^{-1}(\eta_+\mathcal{K}_{1\pm} - \eta_-\mathcal{K}_{3\pm}) + z(\eta_+\mathcal{K}_{3\pm} - \eta_-\mathcal{K}_{1\pm}) \right]$$

Magnetic deformation

$$\mathcal{L}_{\pm} = \mathcal{J}_{0\pm} \pm \mathbf{b}\mathcal{J}_{2\pm} + \hat{\mathbf{b}}z^{\pm 2}\mathcal{J}_{2\pm} \\ + \hat{\mathbf{b}}^{\frac{1}{2}} \left[z^{-1}(\mathbf{b}_+\mathcal{J}_{1\pm} + \mathbf{b}_-\mathcal{J}_{3\pm}) + z(\mathbf{b}_+\mathcal{J}_{3\pm} - \mathbf{b}_-\mathcal{J}_{1\pm}) \right]$$

Three-parameter deformation of Lax connection, based on Lukyanov's model?

$$\mathcal{L}_{\pm} = \mathcal{K}_{0\pm} + \delta_{\pm}\mathcal{K}_{2\pm} + \hat{\delta}z^{\pm 2}\mathcal{K}_{2\pm} \\ + \hat{\delta}^{\frac{1}{2}} \left[z^{-1}(\delta'\mathcal{K}_{1\pm} + \delta'_1\mathcal{K}_{3\pm}) + (\delta'\mathcal{K}_{3\pm} + \delta'_3\mathcal{K}_{1\pm}) \right]$$

Generalities i

Starting point: Superstring world-sheet action for $AdS_3 \times S^3 \times M^4$

$$\frac{T}{2} \int d^2x \sqrt{-g} g^{\alpha\beta} G_{\mu\nu} \partial_\alpha X^\mu \partial_\beta X^\nu + \text{fermions}$$

RR flux \rightarrow use Green-Schwarz action to include fermions

Expansion around background: GS action means we need to expand around bosonic background to consider perturbation theory (fermion kinetic terms)

Gauge-fixing: Conformal gauge leads to non-unitary world-sheet S-matrix

\rightarrow implementation of Virasoro conditions

Alternative is to consider physical “light-cone” gauge

\rightarrow introduces mass scale ($x^+ = p^+ \tau$) \rightarrow massive modes

Decompactification limit: to define world-sheet S-matrix

Generalities ii

Perturbation theory: BMN light-cone gauge-fix, take decompactification limit and compute

[Rughoonauth, Sundin, Wulff '12, '13, '14]

- ▶ 8+8 modes – some massive, some massless, everything coupled and not Lorentz invariant
- ▶ Loops using unitarity methods
- ▶ or perturbation theory (finiteness)

[Engelund, McKeown, Roiban '13, Bianchi, BH '14]

[Roiban, Sundin, Tseytlin, Wulff '14]

Integrability: Part of the GS superstring action for $AdS_3 \times S^3 \times M^4$ can be written as a classically integrable supercoset sigma model based on

$$\frac{\widehat{G} \times \widehat{G}}{G_0}$$

- ▶ Again consider BMN light-cone gauge
- ▶ Identifying residual symmetries and their action allows the S-matrix to be fixed up to phases

Undeformed model

- Light-cone gauge S-matrix for massive modes is built from R-matrices invariant under

$$u(1) \in \mathfrak{psu}(1|1)^2 \ltimes u(1) \ltimes \mathbb{R}^3$$

[Borsato, Ohlsson-Sax, Sfondrini '12, Borsato, Ohlsson-Sax, Sfondrini, Stefanski, Torrielli '13]

- Phases found from solving crossing equation for $AdS_3 \times S^3 \times T^4$
- Phases for $AdS_3 \times S^3 \times S^3 \times S^1$ should basically be the same
- Consistent with semiclassical, perturbation theory and unitarity computations

[Borsato, Ohlsson-Sax, Sfondrini, Stefanski, Torrielli '13]

[Beccaria, Levkovich-Maslyuk, Macorini, Tseytlin '12, Abbott '13]

[Rughoonauth, Sundin, Wulff '12, '13, '14, Roiban, Sundin, Wulff, Tseytlin '14]

[Engelund, Roiban, McKeown '13, Bianchi, BH '14]

Model with magnetic field

- Symmetry algebra not deformed
 - R-matrix is same, deformation parameter appears in the representation
- Related to extra $u(1)$ central element
 - does not constrain the S-matrix
- Phase more complicated, fixed to one-loop by classical integrability and unitarity methods

[BH, Tseytlin, Stepanchuk '13]

[Babichenko, Dekel, Ohlsson-Sax '14, Bianchi, BH '14]

Symmetric q-deformed model

- In the symmetric case symmetry algebra can be q-deformed and corresponding S-matrix constructed
- Still have freedom of central $u(1)$
 - could be used to include magnetic deformation parameter
- Not clear how to deform the phases, $\Gamma \rightarrow \Gamma_q$ not really an option any more


[BH (unpublished)]

State of play for $AdS_3 \times S^3 (\times S^3)$ integrable deformations

Theory	Lax	supercoset	SUGRA	S-matrix	Phases
Undeformed	✓	✓	✓	✓	✓
Magnetic (b)	✓	✓	✓	✓	1-loop
Symmetric q ($q(\eta)$)	✓	✓	(✓)	(✓)	?
Sym. q + mag. ($q(\eta)$, b)	✓	?	?	(✓/?)	?
Asymmetric q (q_L , q_R)	✓	(✓)	?	?	?
Asym. q + mag. (q_L , q_R , b)	(✓/?)	?	?	?	?

Broader open questions

- Related deformations – R can also be solution of classical YBE
 - TsT transformations, duals of non-commutative gauge theories
 - non-integrable backgrounds [Crichigno, Kawaguchi, Matsumoto, Yoshida '14]
 - Unified construction?
- Poisson-Lie dualities – generalization of non-abelian T-duality to Poisson-Lie deformed (q-deformed) symmetry [Klimcik, ...]
- Alternative deformation starting from first-order form of the Lagrangian [Sfetsos '13]
 - Appropriate setting for imaginary deformation (Pohlmeyer) [Hollowood, Miramontes, Schmidt '14]
 - What is relation to q-deformation?
- Uniqueness?
- Supergravity background?
- Dual gauge theory?



Thank you!