



Dependence of magnetic dissipation on magnetic Prandtl number

1. What gets in, will get out
2. Even for vanishing viscosity
3. What if magnetic fields
4. contribute?

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Finite dissipation at vanishing viscosity

$$\frac{d}{dt} \left\langle \rho \mathbf{u}^2 / 2 \right\rangle = \left\langle \rho \mathbf{u} \cdot \mathbf{f} \right\rangle - \left\langle \rho \nu \omega^2 \right\rangle$$

if $\nu \rightarrow 0$ then $\omega^2 \rightarrow \infty$


$$\left\langle 2\rho \nu \mathbf{S}^2 \right\rangle$$

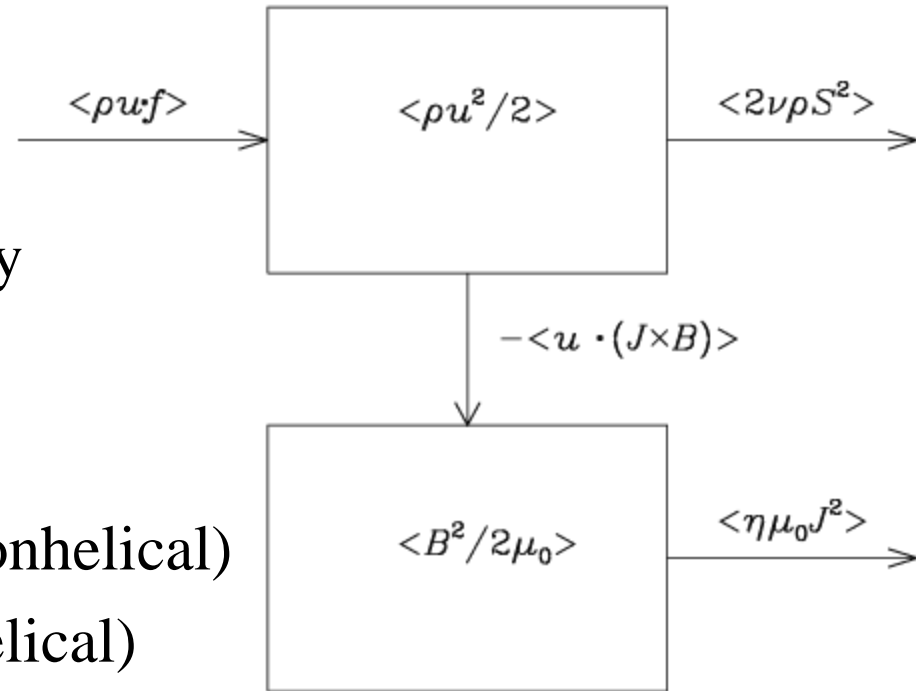
Traceless rate-of-strain tensor $S_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i}) - \frac{1}{3} \delta_{ij} u_{k,k}$

How is this modified by magnetic fields?

- Smaller η , more J, same dissipation
- Or: dynamo stronger, more dissipation
- Or: less dissipation ←

Couple to B -field

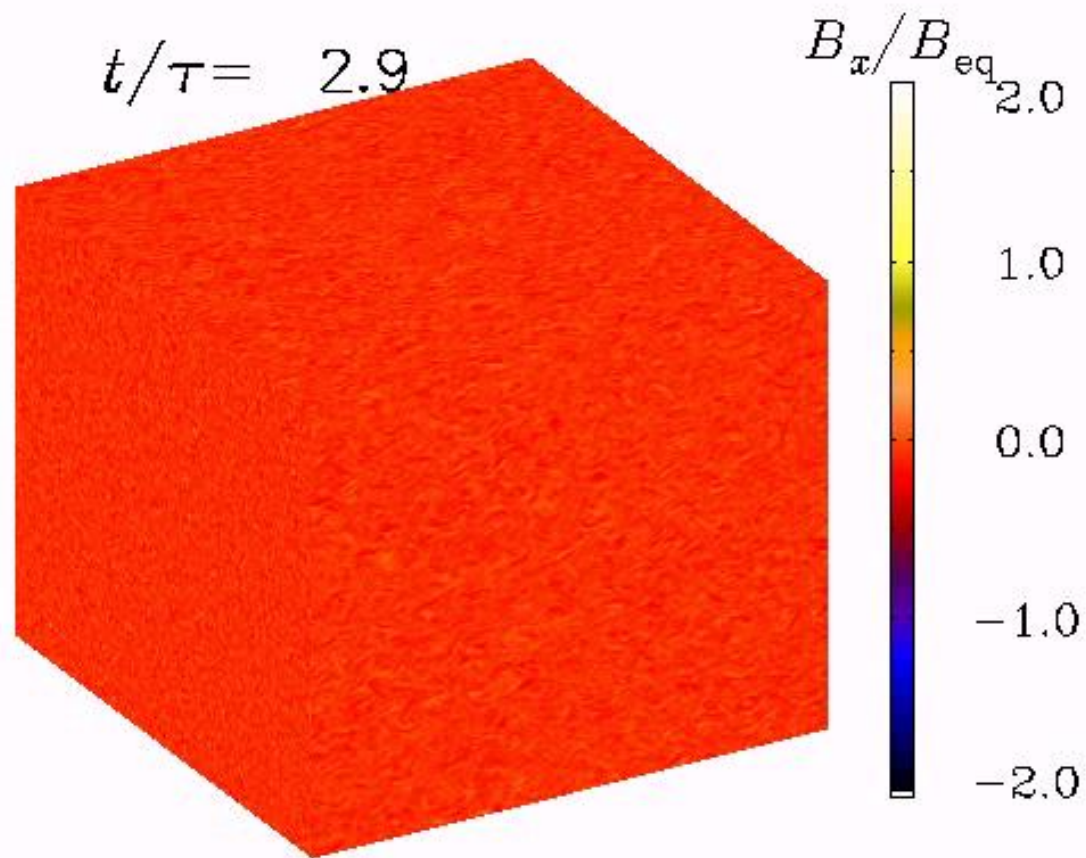
- $\langle \mathbf{u} \cdot (\mathbf{J} \times \mathbf{B}) \rangle$ taps energy
 - Dynamo if negative
 - Self-excited if instability
 - Requires 3-D \mathbf{B} -field
- Isotropic turbulence
 - Small-scale dynamo (nonhelical)
 - Large-scale dynamo (helical)



$$\frac{d}{dt} \langle \rho \mathbf{u}^2 / 2 \rangle = \langle p \nabla \cdot \mathbf{u} \rangle + \langle \mathbf{u} \cdot (\mathbf{J} \times \mathbf{B}) \rangle + \langle \rho \mathbf{u} \cdot \mathbf{f} \rangle - \langle 2\rho \nu \mathbf{S}^2 \rangle, \quad (6)$$

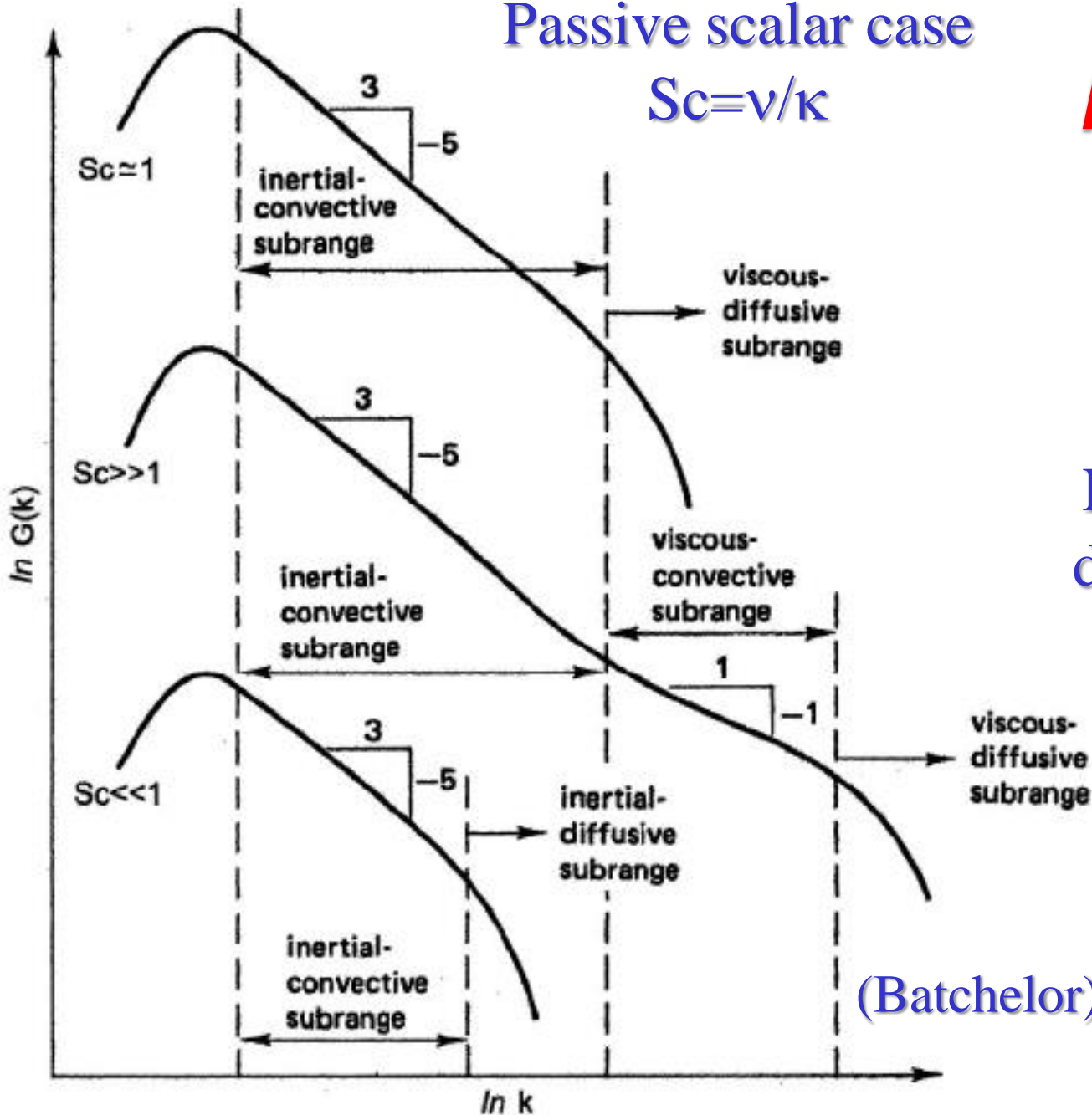
$$\frac{d}{dt} \langle B^2 / 2\mu_0 \rangle = -\langle \mathbf{u} \cdot (\mathbf{J} \times \mathbf{B}) \rangle - \langle \eta \mu_0 \mathbf{J}^2 \rangle, \quad (7)$$

Inverse cascade



Passive scalar case
 $Sc = \nu/\kappa$

Motivation of LES modeling



Location of cutoff
does not matter for
inertial range

Order of limits

$$\nu \rightarrow 0$$

$$\eta \rightarrow 0$$

unimportant

(Batchelor)

Coupling to B-field

- Magnetic dissipation depends on work term
 - Independent of microphysics?
 - Basic assumption of LES and iLES
 - e.g., hyperdiffusion (Galsgaard & Nordlund 1996)
- Not confirmed by DNS
 - Ratio scales with ν/η
 - Either ν or η fixed
 - What if replace Spitzer by Hall?

Inverse cascades and α effect at a low magnetic Prandtl number

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Dynamo action in a fully helical Arnold-Beltrami-Childress flow is studied using both direct numerical simulations and subgrid modeling. Sufficient scale separation is given in order to allow for large-scale magnetic energy buildup. Growth of magnetic energy obtains down to a magnetic Prandtl number $P_M = R$ close to 0.005, where R_V and R_M are the kinetic and magnetic Reynolds numbers. The critical magnetic Reynolds number for dynamo action R_M^c seems to saturate at values close to 20. Detailed studies of the dependence of the amplitude of the saturated magnetic energy with P_M are presented. When P_M is decreased numerical experiments are conducted with either R_V or R_M kept constant. In the former case, the ratio of magnetic to kinetic energy saturates to a value slightly below unity as P_M decreases. Examination of the spectra and structures in real space reveals that quenching of the velocity by a large-scale magnetic field takes place, with an inverse cascade of magnetic helicity and a force-free field at large scale in the saturated regime.

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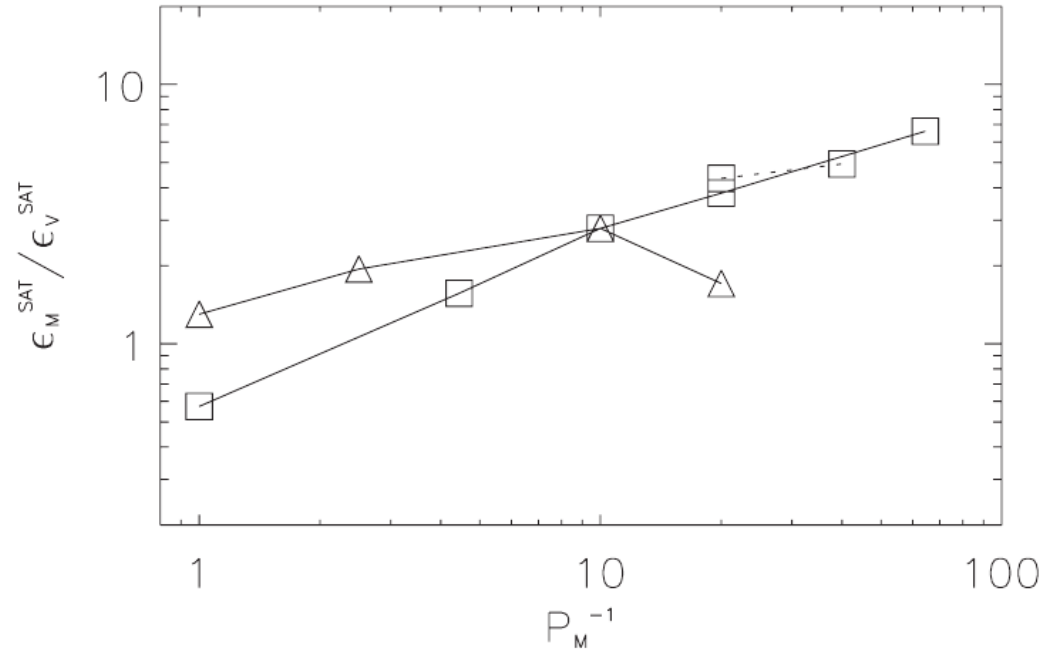


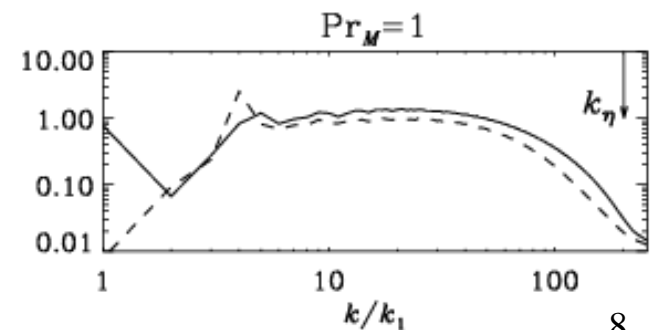
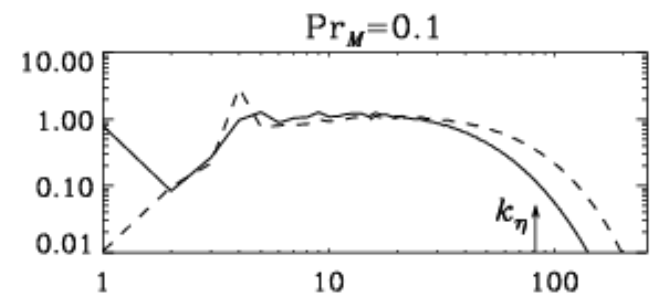
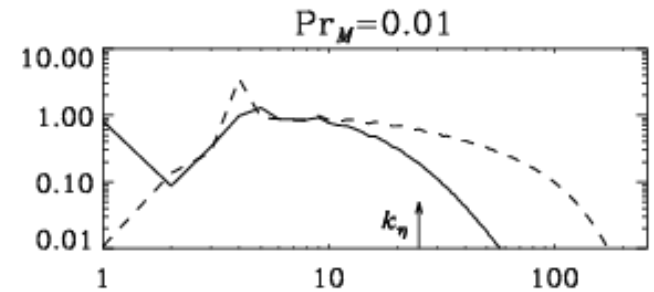
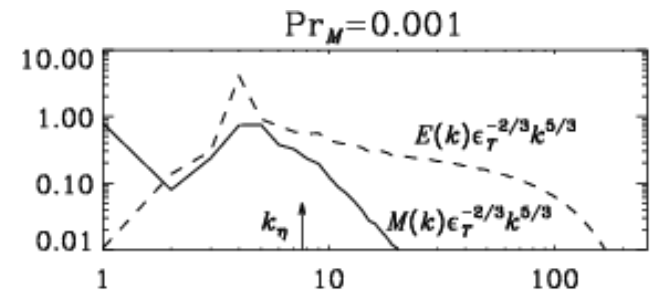
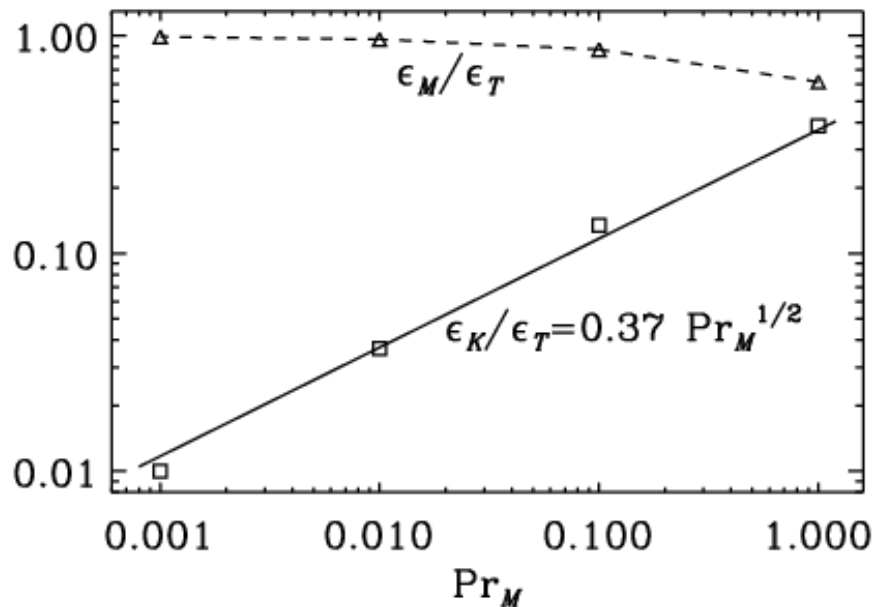
Figure 8 shows the ratio of the magnetic energy dissipation rate ϵ_M to the kinetic energy dissipation rate ϵ_V in the saturated state for the same runs as in Fig. 7. At constant R_V , for small values of P_M , a drop in the ratio is observed as the value of R_M gets closer to the threshold. On the other hand, at constant R_M , more and more energy is dissipated by Ohmic dissipation as P_M is decreased.

v smaller, $v\omega^2$ smaller, $\eta\mathbf{J}^2$ larger

Numerically difficult?

- Energy dissipation via Joule
 - Viscous dissipation weak
- Can increase Re *substantially*!

$$\text{Pr}_M = \nu/\eta$$



Isothermal MHD

$$\frac{D \ln \rho}{Dt} = -\nabla \cdot \mathbf{u},$$

$$\begin{aligned} \frac{D\mathbf{u}}{Dt} = & -c_s^2 \nabla \ln \rho - 2\boldsymbol{\Omega} \times \mathbf{u} + \mathbf{f} \\ & + \rho^{-1} [\mathbf{J} \times \mathbf{B} + \nabla \cdot (2\nu\rho\mathbf{S})], \end{aligned}$$

Forcing:
helical or
nonhelical

$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{u} \times \mathbf{B} - \eta\mu_0\mathbf{J},$$

where $D/Dt = \partial/\partial t + \mathbf{u} \cdot \nabla$ is the advective derivative, \mathbf{u} is the velocity, $\mathbf{B} = \nabla \times \mathbf{A}$ is the magnetic field, \mathbf{A} is the magnetic vector potential, $\mathbf{J} = \nabla \times \mathbf{B}/\mu_0$ is the current density, μ_0 is the vacuum permeability, and

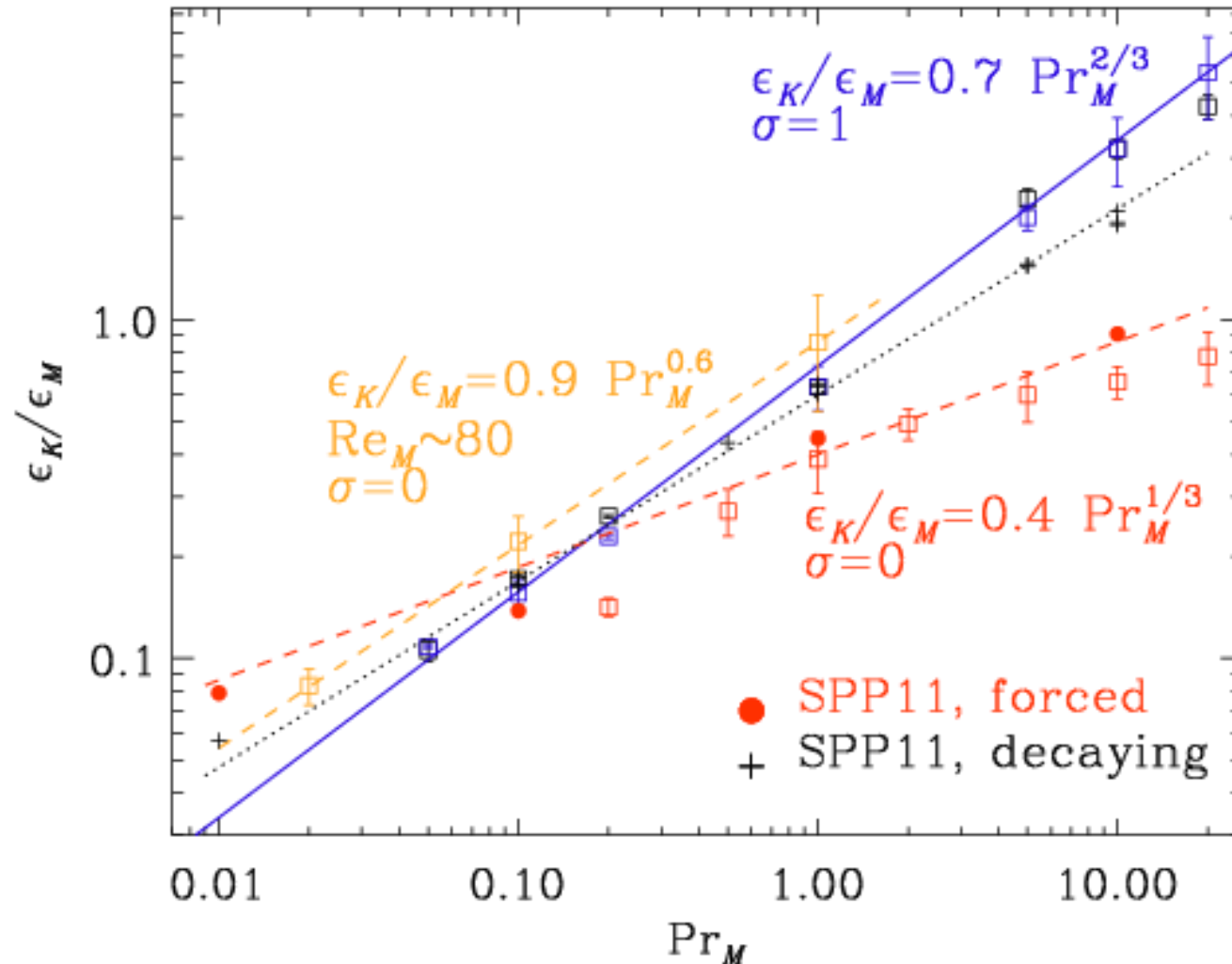
$$S_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) - \frac{1}{3}\delta_{ij} \nabla \cdot \mathbf{u} \quad (4)$$

is the traceless rate of strain tensor. It is useful to note that

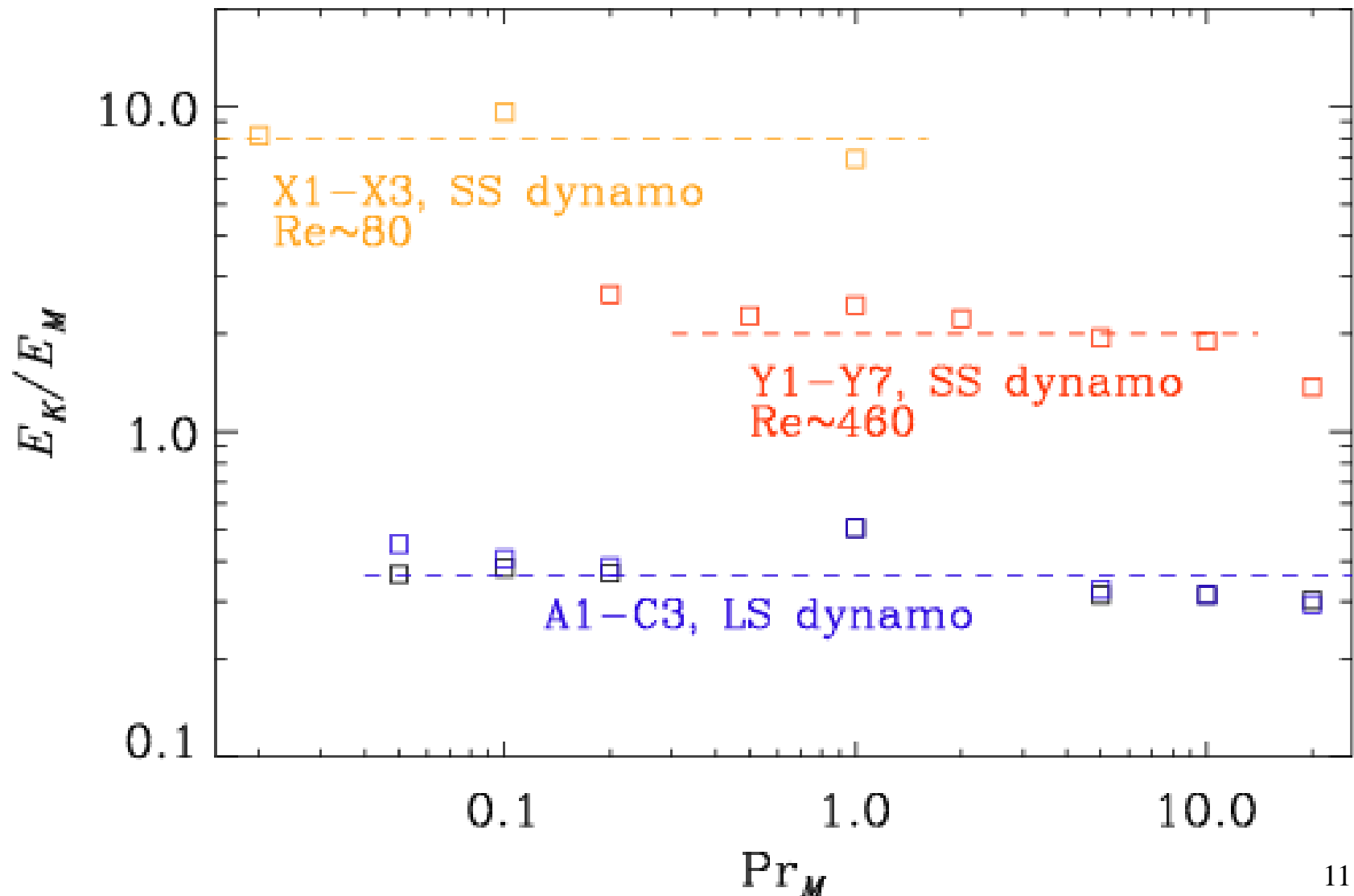
$$\rho^{-1} \nabla \cdot (2\rho\mathbf{S}) = \frac{4}{3} \nabla \nabla \cdot \mathbf{u} - \nabla \times \nabla \times \mathbf{u} + \mathbf{S} \cdot \nabla \ln \rho, \quad (5)$$

where we call attention to the presence of the 4/3 factor that

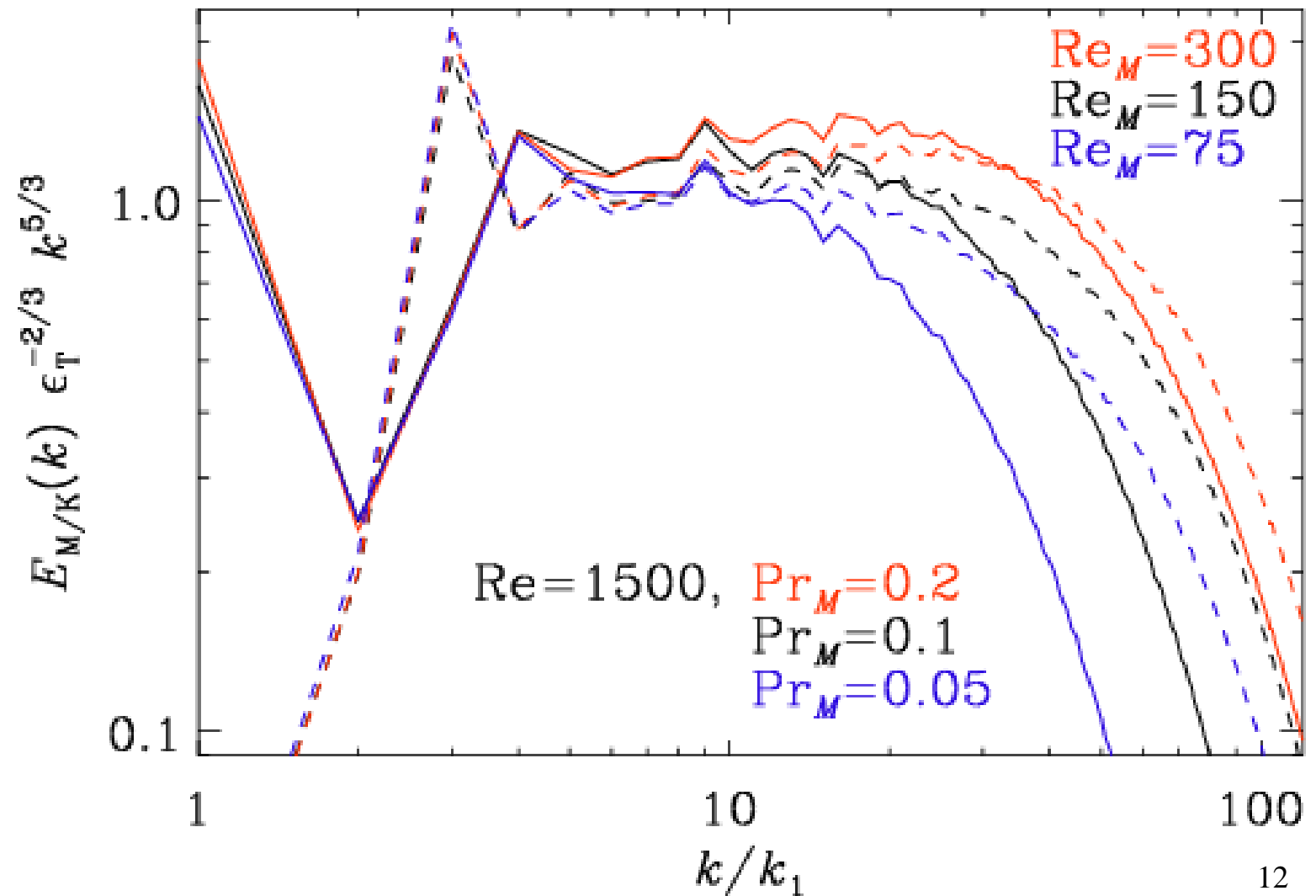
Pr_M dependence of dissipation ratio



Energy ratio nearly unchanged



Inertial range \rightarrow compensated spectra



2-D MHD (Tran et al, JFM 2013)

this linear behaviour turns out to be fully accessible to numerical simulations. Indeed, the results reported in §4 show a nearly linear decrease of $\nu \|\omega\|^2$ with ν even for moderately small Pm . Second, we have

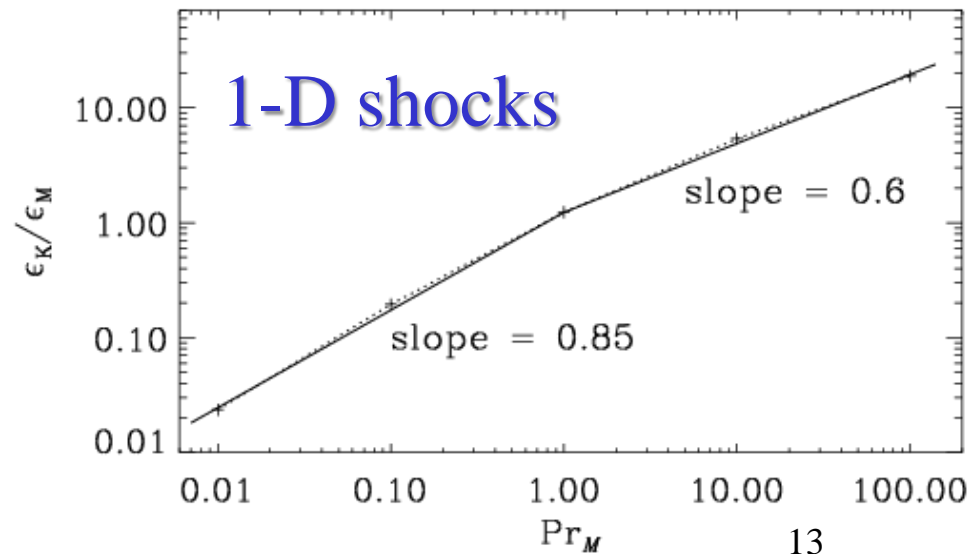
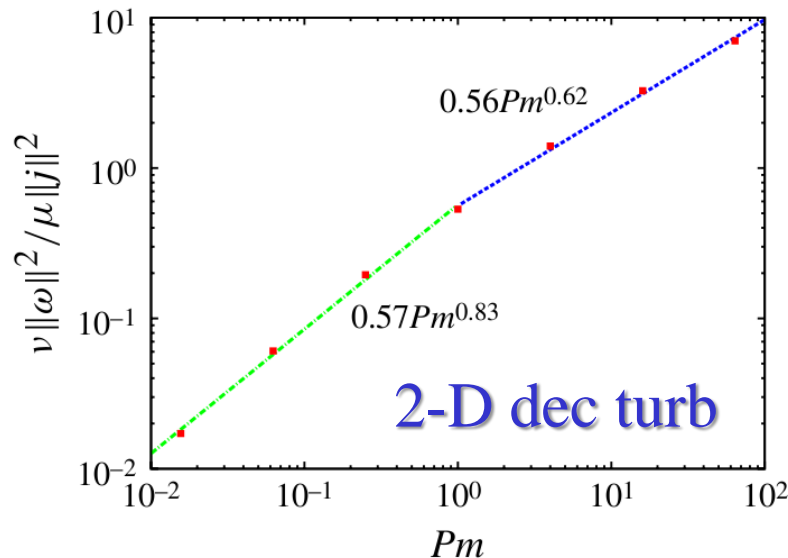
$$\int_0^t \|\nabla j\|^2 d\tau < \infty. \quad (3.10)$$

In conclusion, we see that for solution regularity beyond $t = T$ of the 2D MHD system with $Pm = \infty$, it is sufficient to require either

$$\frac{\|j\|_\infty}{\|j\|} \leq C(T-t)^{-\alpha} \quad \text{or} \quad \frac{\|\nabla u\|_\infty}{\|\omega\|} \leq C(T-t)^{-\alpha} \quad (3.39)$$

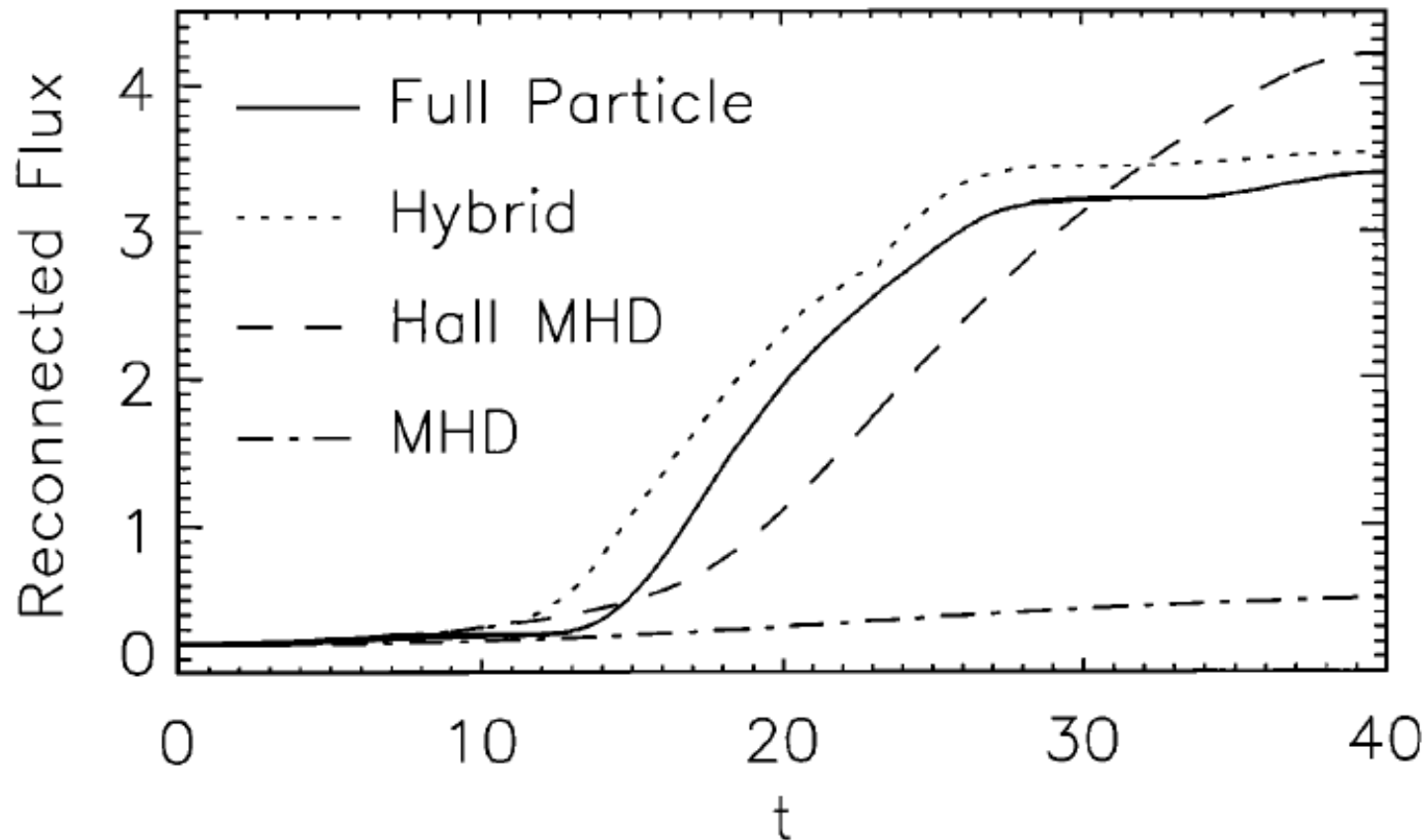
for $\alpha < 1/2$.

η smaller,
 ν/η larger,
 J^2 finite,
 $\eta J^2 \rightarrow 0$
 $\nu \omega^2 / \eta J^2$
 keeps incr.



Geospace Environmental Modeling (GEM) Magnetic Reconnection Challenge

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M. Kuznetsova,³ Z. W. Ma,⁴ A. Bhattacharjee,⁴ A. Otto,⁵
and P. L. Pritchett,⁶



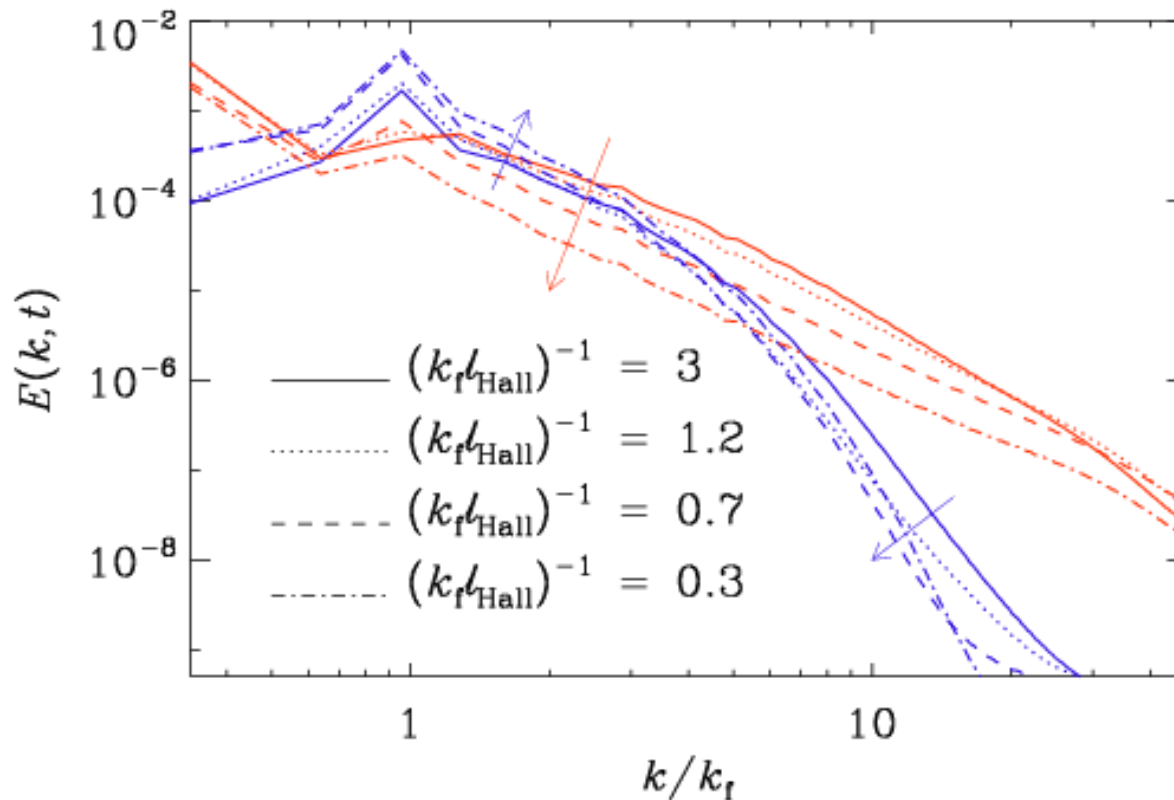
The key conclusion of this project is that the Hall effect is the critical factor which must be included to model collisionless magnetic reconnection. When the

Hall MHD

- How does it affect dissipation ratio?
- Does it “replace” ohmic diffusion somehow
- Does it affect the dynamo
 - Backscatter from magnetic to kinetic energy (Mininni, Alexakis, Pouquet 2006)
 - Nature of MHD Alfvén waves changed

Hall MHD simulations

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B} - \ell_{\text{Hall}} \mathbf{J} \times \mathbf{B} - \eta \mu_0 \mathbf{J})$$

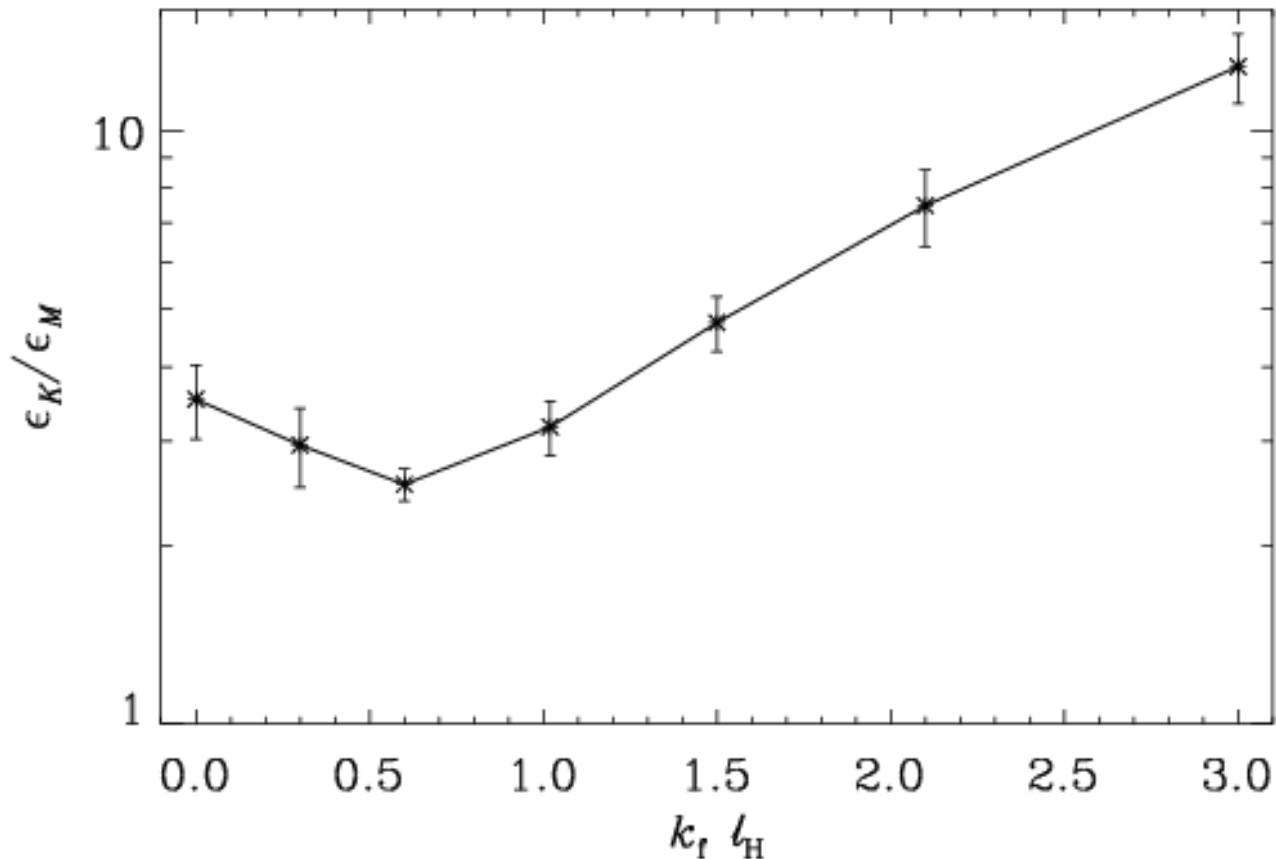


288³
resol.

Makes dynamo weaker → less magnetic dissipation

Hall MHD simulations

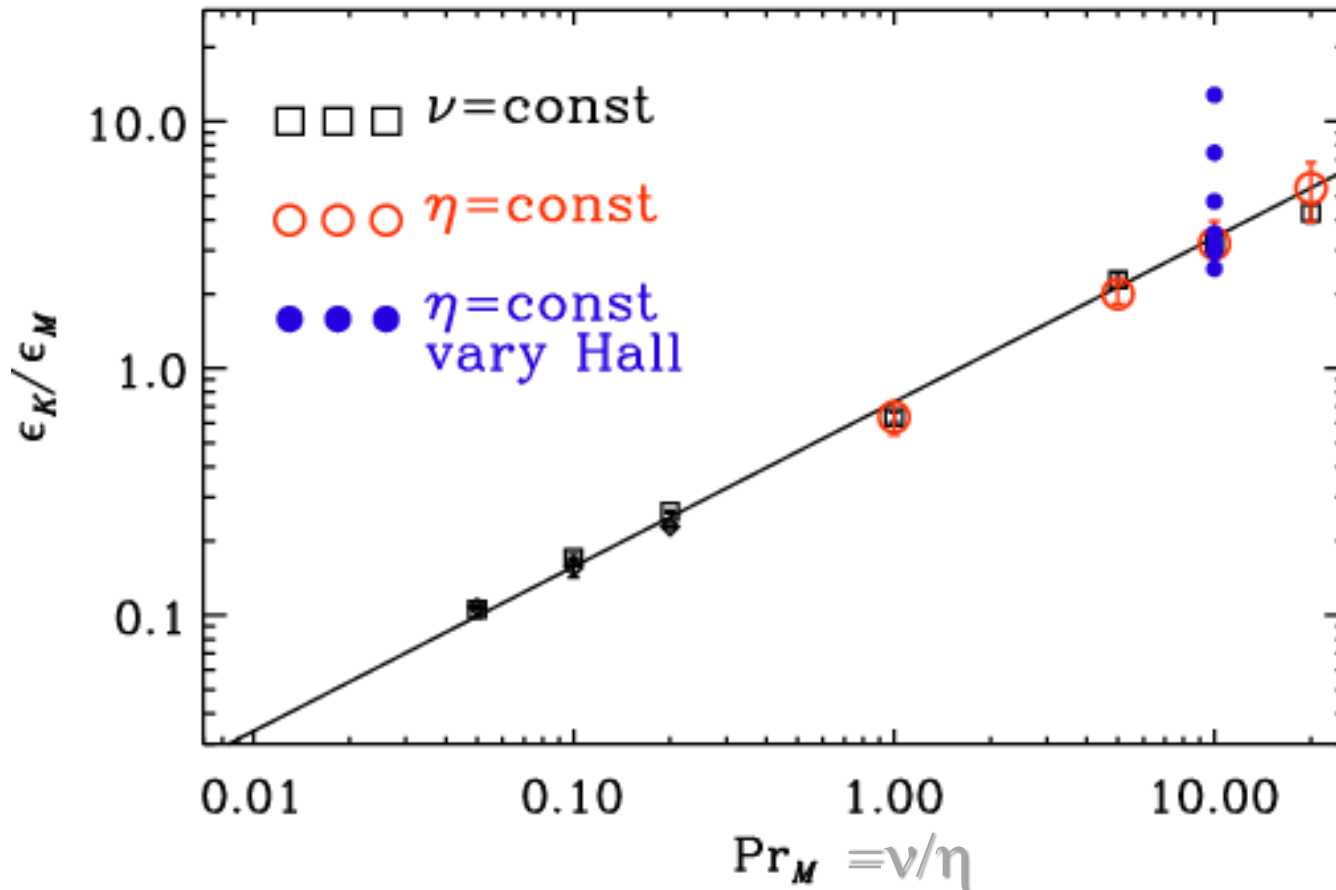
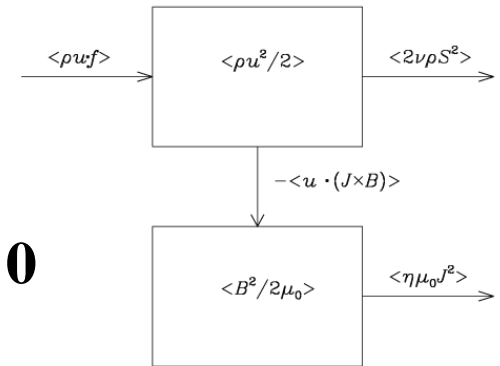
$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B} - \ell_{\text{Hall}} \mathbf{J} \times \mathbf{B} - \eta \mu_0 \mathbf{J})$$



E_M weaker, ϵ_M weaker, ϵ_K / ϵ_M larger

Hall effect

Makes dynamo weaker $\mathbf{J} \cdot (\ell_{\text{Hall}} \mathbf{J} \times \mathbf{B}) = 0$



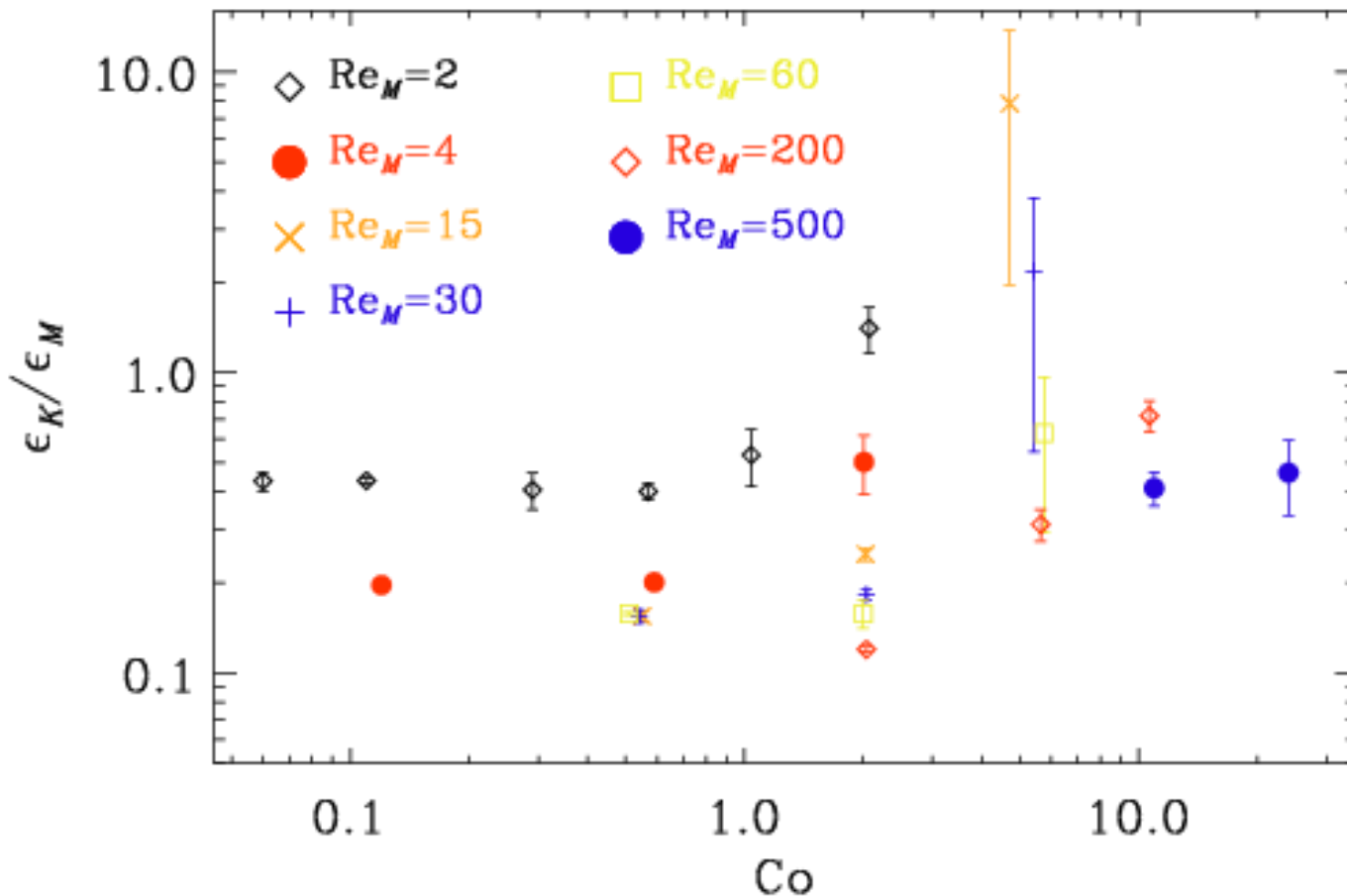
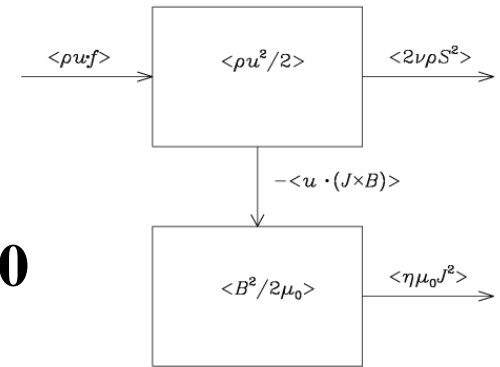
Conclusions

- Dissipation ratio scales with Pr_M
 - Both for $\text{Pr}_M > 1$ and < 1
 - SS dynamo scaling shallower (nonuniversal)
- Qualitatively reproduced with MHD shocks
- $\langle \mathbf{u} \cdot (\mathbf{J} \times \mathbf{B}) \rangle$ determined by microphysics!?
 - Hall does affect dynamo, if $1/\ell_{\text{Hall}}$ subinertial
 - Questions about LES or iLES

Run	$\nu k_1/c_s$	$\eta k_1/c_s$	Re	Re_M	Co	u_{rms}/c_s	b_{rms}/c_s	ϵ_K/ϵ_T	ϵ_M/ϵ_T	C_ϵ	k_ν/k_1	k_η/k_1	res.
RA1	1×10^{-3}	1×10^{-2}	30	3	0.1	0.090	0.066	0.30	0.70	1.71	17	4	16^3
RA2	1×10^{-3}	1×10^{-2}	30	3	0.1	0.089	0.064	0.30	0.70	1.68	17	4	16^3
RA3	1×10^{-3}	1×10^{-2}	29	3	0.3	0.088	0.065	0.29	0.71	1.66	17	4	16^3
RA4	1×10^{-3}	1×10^{-2}	29	3	0.6	0.088	0.065	0.29	0.71	1.63	17	4	16^3
RA5	1×10^{-3}	1×10^{-2}	32	3	1.0	0.096	0.063	0.35	0.65	1.31	18	4	16^3
RA6	1×10^{-3}	1×10^{-2}	40	4	2.1	0.121	0.053	0.58	0.42	0.77	21	3	16^3
RB1	5×10^{-4}	5×10^{-3}	56	6	0.1	0.084	0.092	0.16	0.84	2.10	25	7	32^3
RB2	5×10^{-4}	5×10^{-3}	57	6	0.6	0.085	0.094	0.17	0.83	2.03	25	7	32^3
RB3	5×10^{-4}	5×10^{-3}	83	8	2.0	0.124	0.073	0.34	0.67	0.62	30	6	32^3
RC1	2×10^{-4}	2×10^{-3}	150	15	0.6	0.090	0.117	0.13	0.87	1.74	48	14	64^3
RC2	2×10^{-4}	2×10^{-3}	205	21	2.0	0.123	0.100	0.20	0.80	0.66	52	13	64^3
RC3	2×10^{-4}	2×10^{-3}	353	35	4.7	0.212	0.019	0.89	0.11	0.07	65	7	64^3
RD1	1×10^{-4}	1×10^{-3}	310	31	0.5	0.093	0.119	0.13	0.87	1.56	80	23	128^3
RD2	1×10^{-4}	1×10^{-3}	410	41	2.0	0.123	0.127	0.15	0.85	0.69	83	23	128^3
RD3	1×10^{-4}	1×10^{-3}	613	61	5.4	0.184	0.037	0.69	0.31	0.12	105	16	128^3
RE1	5×10^{-5}	5×10^{-4}	647	65	0.5	0.097	0.123	0.14	0.86	1.44	137	39	256^3
RE2	5×10^{-5}	5×10^{-4}	833	83	2.0	0.125	0.134	0.14	0.86	0.69	138	39	256^3
RE3	5×10^{-5}	5×10^{-4}	1160	116	5.8	0.174	0.099	0.39	0.61	0.17	160	32	256^3
RF1	2×10^{-5}	2×10^{-4}	2033	203	2.0	0.122	0.116	0.11	0.89	0.59	243	74	256^3
RF2	2×10^{-5}	2×10^{-4}	2950	295	5.6	0.177	0.106	0.24	0.76	0.14	272	65	256^3
RF3	2×10^{-5}	2×10^{-4}	3917	392	10.6	0.235	0.084	0.42	0.58	0.06	318	62	256^3
RG1	1×10^{-5}	1×10^{-4}	7600	760	10.9	0.228	0.091	0.29	0.71	0.07	501	111	512^3
RG2	1×10^{-5}	1×10^{-4}	6933	693	24.0	0.208	0.089	0.32	0.68	0.09	496	107	512^3

Effect of rotation

No effect if supercritical $\mathbf{u} \cdot (2\mathbf{\Omega} \times \mathbf{u}) = 0$



Passive scalar

Specifically, the equations considered by Ohkitani & Dowker (2010) are

$$\partial u / \partial t = -u u' + \tilde{\nu} u'', \quad (22)$$

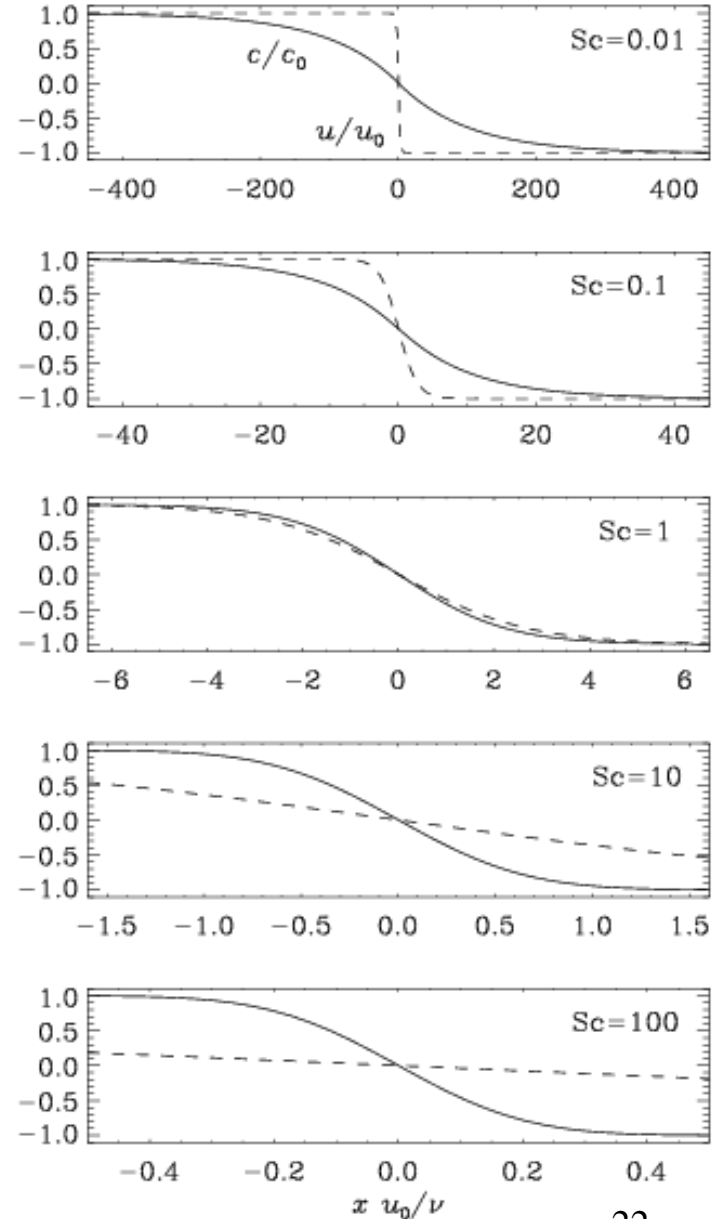
$$\partial c / \partial t = -u c' + \kappa c'', \quad (23)$$

where primes denotes differentiation with respect to x . The solution to Equation (22) decouples and possesses a shock. In a frame of reference moving with the shock, the solution is stationary and given by

$$u(x) = -u_0 \tanh x/w, \quad (24)$$

where u_0 is the velocity jump and $w_u = 2\tilde{\nu}/u_0$ is the width of the shock with $\tilde{\nu} = 4\nu/3$ being a rescaled viscosity. These equations can be obtained from the hydrodynamic version (i.e., $B = 0$) of Equation (2) after setting $c_s = 0$, so the density gradient does not enter, so we can ignore Equation (1) and put $\rho = 1$. The $4/3$ factor in the expression for $\tilde{\nu}$ comes from the fact that, owing to compressibility, the viscous acceleration term includes a $\frac{1}{3} \nabla \nabla \cdot \mathbf{u}$ term in addition to the usual $\nu \nabla^2 \mathbf{u}$ term; see Equation (5) for a corresponding reformulation of the dissipation terms. The viscous dissipation $\epsilon_K = \tilde{\nu} \int (u')^2 dx/L$ is then, using $\partial u / \partial x \propto 1/\cosh^2(x/w)$,

$$\epsilon_K = \tilde{\nu} \frac{w}{L} \int \frac{dx/w}{\cosh^4(x/w)} = \frac{4}{3} \frac{\tilde{\nu} u_0^2}{wL} = \frac{2}{3} \frac{u_0^3}{L}, \quad (25)$$



Ohkitani & Dowker (2010)

III. DISSIPATION RATE OF A PASSIVE SCALAR

By (5), the dissipation rate of passive scalar variance ϵ_θ is evaluated as follows:

$$\epsilon_\theta = \kappa \int_{-\infty}^{\infty} \left(\frac{\partial \theta}{\partial x} \right)^2 dx = \kappa \tilde{c}'^2 \int_{-\infty}^{\infty} \left[\cosh \frac{u_1}{2\nu} (X+c) \right]^{-4P_r} dX = \kappa \frac{(u_1 \theta_1)^2}{4\nu^2 I_{P_r}(\infty)^2 u_1} \int_{-\infty}^{\infty} \cosh^{-4P_r}(\xi) d\xi$$

For $P_r = n$, we obtain an exact expression

$$\epsilon_\theta = u_1 \theta_1^2 \frac{\{(2n)!\}^4}{(4n)!(n!)^4}.$$

[For more general real-valued $P_r = \alpha$, we have $I_\alpha(\infty) = \sqrt{\pi}/2\Gamma(\alpha)/\Gamma(1/2+\alpha)$ and thus $\epsilon_\theta = u_1 \theta_1^2 2/\sqrt{\pi} \Gamma(2\alpha) \Gamma(1/2+\alpha)^2 / \alpha \Gamma(\alpha)^2 \Gamma(1/2+2\alpha)$, where $\Gamma(\alpha)$ is the gamma function.]

By Stirling's formula $n! \simeq \sqrt{2\pi n} n^n e^{-n}$ for $n \gg 1$, we deduce that

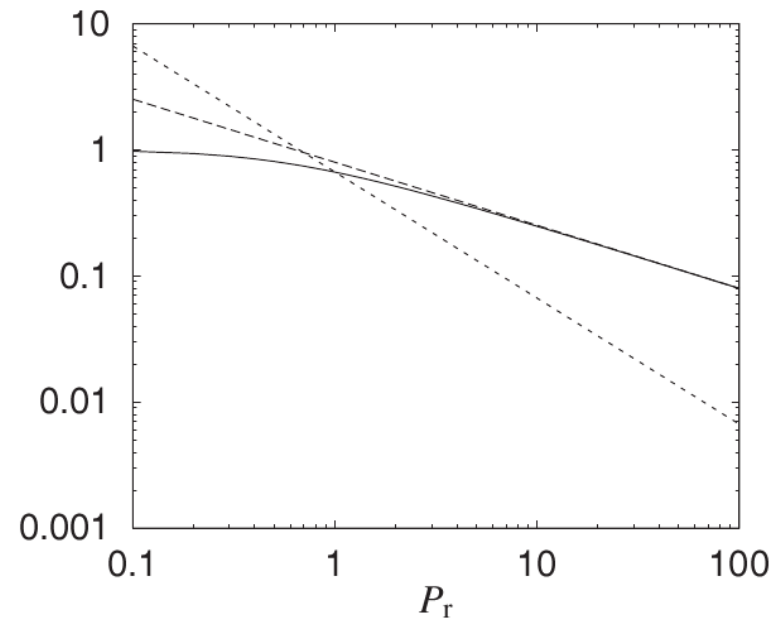
$$I_{n+1}(\infty) \simeq \frac{1}{2} \sqrt{\frac{\pi}{n}}.$$

Therefore, the dissipation rate of θ in the limit of large P_r is

$$\epsilon_\theta \simeq u_1 \theta_1^2 \sqrt{\frac{2}{\pi P_r}} \quad \text{as } P_r \rightarrow \infty, \quad (9)$$

which decays as $P_r^{-1/2}$ with P_r . Even in this simple one-dimensional (1D) model, the problem of dissipation anomaly is subtle in that ϵ_θ does depend on P_r in a nontrivial fashion.

$\epsilon_\theta(P_r)/(u_1 \theta_1^2)$



MHD model

$$\partial u / \partial t = -uu' - bb' + \tilde{\nu} u'',$$

$$\partial b / \partial t = -ub' - bu' + \eta b'',$$

$$\partial u / \partial x = (u^2 + b^2 - u_0^2) / 2\tilde{\nu},$$

$$\partial b / \partial x = ub / \eta.$$

