Fragmentation of Filamentary Molecular Clouds Threaded by Perpendicular Magnetic Field



Taurus Palmeirim+ 13 250 cont. + Magnetic Field (Polarization)

## **B** direction matters.

submitted to ApJ

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## Magnetic Field is Perpendicular to the Main Filaments. Striations (sub filaments) are parallel to B.





Serpens South (K-band) Sugitani+11

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Cloud cores are formed through fragmentation of the main filament.





5E+21 1E+22 1.5E+22 2E+22 2.5E+22 3E+22 3.5E+22 4E+22 4.5E+22



#### Vela C Kusune+16

#### Fragmentation of a Filamentary Cloud is a *Classic* Problem.

ACTA ASTRONOMICA Vol. 13, (1963) No 1

## 1963

a half century ago!

#### On the Gravitational Instability of Some Magneto-hydrodynamical Systems of Astrophysical Interest

Part III

by

#### J. S. Stodółkiewicz

Stodolkiewcz 63, Ostriker 64, Nagasawa 87, Nakamura+93, 95, Hanawa+93, Matsumoto+94, Fiege & Pudritz 00

Equilibrium model: Longitudinal Magnetic Field

cf. Nagasawa 87 Nakamura+ 93, 95

1**D** 

#### symmetric around the axis

$$\rho(r) = \rho_0 \left( 1 + \frac{r^2}{8H^2} \right)^{-2}$$
$$B_z(r) = B_0 \left( 1 + \frac{r^2}{8H^2} \right)^{-1}$$
$$4\pi G \rho_0 H^2 = c_s^2 + \frac{B_0^2}{8\pi\rho_0}$$

supported in part by magnetic fields. Stodolkiewicz 63

 $B_{\phi}$ : hoop stress cf. Fiege & Pudritz 00



Unstable against fragmentation Jeans wavelength several times of the filament diameter Stability of Magnetized Sheet Cloud (Nakano & Nakamura 78, Nakamura+ 91, Nagai+98)

 $B > 2\pi \sqrt{G}\Sigma$  stable



B suppresses fragmentation

always unstable (supercritical)



fragmentation no magnetic force parallel to B

## **B** direction matters.

displacement

X

B is bent.

may be subcritical

1. Magnetic Force is Perpendicular to **B**.

2. Critical Mass,  $B_{\rm cr} = 2\pi \sqrt{G \Sigma}$ 

displacement ξ  $B_{\parallel}$  unchanged

always supercritical

## Idealized Equilibrium Model









Equilibrium  

$$\rho_0 = \rho_c \left( 1 + \frac{x^2 + y^2}{8H^2} \right)^{-2},$$

$$H^2 = \frac{c_s^2}{4\pi G\rho_c},$$

$$\boldsymbol{B}_0 = B_0 \boldsymbol{e}_x,$$

$$\begin{split} \text{Ideal MHD Eq.} \\ \frac{\partial \rho}{\partial t} &= -\boldsymbol{\nabla} \cdot (\rho \boldsymbol{v}) \,, \\ \frac{\partial \boldsymbol{v}}{\partial t} &= -c_s^2 \boldsymbol{\nabla} \ln \rho - \boldsymbol{\nabla} \psi + \boldsymbol{j} \times \boldsymbol{B}, \\ \frac{\partial \boldsymbol{B}}{\partial t} &= \boldsymbol{\nabla} \left( \boldsymbol{v} \times \boldsymbol{B} \right), \\ \boldsymbol{j} &= \frac{\boldsymbol{\nabla} \times \boldsymbol{B}}{4\pi}, \\ \Delta \psi &= 4\pi G \rho. \end{split}$$

*x*: magnetic field, *z*: filament axis  $c_s$ : sound speed

$$\begin{split} \rho &= \rho_0 + \delta \varrho(x, y) e^{\sigma t} \cos kz, \\ \boldsymbol{\xi} &= e^{\sigma t} \left[ \xi_x(x, y) \cos kz \boldsymbol{e}_x + \xi_y(x, y) \cos kz \boldsymbol{e}_y + \xi_z(x, y) \sin kz \boldsymbol{e}_z \right], \\ \boldsymbol{B} &= B_0 \boldsymbol{e}_x + e^{\sigma t} \left[ b_x(x, y) \cos kz \boldsymbol{e}_x + b_y(x, y) \cos kz \boldsymbol{e}_y + b_z(x, y) \sin kz \boldsymbol{e}_z \right], \\ \boldsymbol{j} &= e^{\sigma t} \left[ j_x(x, y) \sin kz \boldsymbol{e}_x + j_y(x, y) \sin kz \boldsymbol{e}_y + j_z(x, y) \cos kz \boldsymbol{e}_z \right], \\ \psi &= \psi_0 + e^{\sigma t} \delta \psi(x, y) \cos kz, \end{split}$$

## Numerical Methods

#### Displacement vector

$$\begin{split} \delta\varrho &= -\frac{\partial}{\partial x} \left(\rho_0 \xi_x\right) - \frac{\partial}{\partial y} \left(\rho_0 \xi_y\right) - k\rho_0 \xi_z, \\ b_x &= -B_0 \left[\frac{\partial}{\partial y} \xi_y(x,y) + k\xi_z\right], \\ b_y &= B_0 \frac{\partial \xi_y}{\partial x}, \\ b_z &= -B_0 \frac{\partial \xi_z}{\partial x}, \\ j_x &= \frac{1}{4\pi} \left(\frac{\partial b_z}{\partial y} + kb_y\right), \\ j_y &= -\frac{1}{4\pi} \left(k\delta b_x + \frac{\partial b_z}{\partial x}\right), \\ j_z &= \frac{1}{4\pi} \left(\frac{\partial b_y}{\partial x} - \frac{\partial b_x}{\partial y}\right). \\ \delta\psi(\mathbf{r}) &= \int \mathbf{G}(\mathbf{r}, \mathbf{r}')\varrho(\mathbf{r}')d\mathbf{r}' \end{split}$$

$$\boldsymbol{\xi} = \int \boldsymbol{v} dt$$

$$\rho_0 \frac{d^2 \boldsymbol{\xi}}{dt^2} = \boldsymbol{F} \left( \boldsymbol{\xi} \right),$$
$$\rho_0 \sigma^2 \boldsymbol{\xi} = \left( \boldsymbol{A} + \frac{B_0^2}{4\pi} \boldsymbol{C} \right) \boldsymbol{\xi}.$$

Force is proportional to  $\xi$ .

generalized eigenvalue problem

$$\boldsymbol{A} + \frac{B_0^2}{4\pi} \boldsymbol{C} - \rho_0 \boldsymbol{I} \bigg| = 0$$

LAPACK Numerical Library

A perturbed quantity is expressed as a function of  $\xi$ .



Boundary (1) Fixed  $\xi_x, \xi_y, \xi_z = 0$ (2) Free  $\frac{\partial \xi}{\partial x} = 0$  $\frac{\partial \xi}{\partial \xi} = 0$ 

for 
$$x > n_x \Delta x$$
 or  $y > n_y \Delta y$ 

$$= 0 \quad \text{for } x > n_x \Delta x$$
$$\frac{\partial \boldsymbol{\xi}}{\partial y} = 0 \quad \text{for } y > n_y \Delta y$$

### **Boundary Condition**



1) Fixed  $\xi = 0$ 2) Free  $\partial \xi / \partial x = 0$ keep straight





 $kH = 0.3 \rightarrow \lambda = 5.8 d_{\text{FWHM}}$ 

## Eigen function kH = 0.2 normalization $\xi_z(0, 0) = -H$





Change in *B* 

kH = 0.2

#### $\xi_{z}\left(0,0\right)=-H$





## Further strong magnetic field (kH = 0.2) $1/\beta = 0.375$



## Enlargement

 $1/\beta = 0.375, kH = 0.2$ 



Flow in the *yz*-plane (x = 0)

 $kH = 0.2, 1/\beta = 0.0$ 

 $kH = 0.2, 1/\beta = 0.125$ 







x

x

### Free boundary

![](_page_21_Figure_1.jpeg)

incompressible mode (cf. Nagai+98, Fiege & Pudritz 00)

# Free boundary $kH = 0.2, \beta = 0.5$

![](_page_22_Figure_1.jpeg)

![](_page_22_Figure_2.jpeg)

## Similarity to truncated filament model.

## Fiege & Pudritz 00

truncated filament

![](_page_23_Picture_3.jpeg)

#### compression

![](_page_23_Figure_5.jpeg)

circulation

## low β plasma $\rightleftharpoons$ high T

# Free boundary $kH = 0.05, \beta = 2$

![](_page_24_Figure_1.jpeg)

Why the growth rate depends on the boundary?

Alfvén transit time

$$\tau_{\rm A} = \int \frac{ds}{v_{\rm A}} = \int \frac{\sqrt{4\pi\rho}}{B} ds$$

Magnetic tension propagates at  $v_A$ .

![](_page_25_Figure_4.jpeg)

 $\tau_A$  is finite in our simple model, since B = const and  $\rho \propto r^{-4}$ .

How about in reality?

## Empirical EOS

$$\begin{split} \rho &= \rho_c \left( 1 + \frac{r^2}{4H^2} \right)^{-1}, \\ \lambda_r &= \int_0^r 2\pi r' \rho(r') dr' \\ &= 4\pi \rho_c H^2 \ln \left( 1 + \frac{r^2}{4H^2} \right)^{-1}, \\ g_r &= -\frac{2G\lambda_r}{r} \\ &= -\frac{8\pi G\rho_c H^2}{r} \ln \left( 1 + \frac{r^2}{4H^2} \right), \\ \frac{dP}{dr} &= \rho g_r \\ &= -\frac{8\pi G\rho_c H^2}{r} \ln \left( 1 + \frac{r^2}{4H^2} \right), \\ \frac{d\rho}{dr} &= -\frac{r\rho_c}{2H^2} \left( 1 + \frac{r^2}{4H^2} \right)^{-2}, \end{split}$$

$$\begin{aligned} \frac{dP}{d\rho} &= \frac{dP/dr}{d\rho/dr} \\ &= \frac{4\pi G\rho_c H^2}{r^2} \left(1 + \frac{r^2}{4H^2}\right) \ln\left(1 + \frac{r^2}{4H^2}\right) \\ &= -4\pi G\rho_c \left(1 - \frac{\rho}{\rho_c}\right) \ln\left(\frac{\rho}{\rho_c}\right) \end{aligned}$$

![](_page_26_Figure_3.jpeg)

## Stability Analysis $\rho = \rho_0 + \varrho(x, y)e^{\sigma t} \cos kz$

![](_page_27_Figure_1.jpeg)

 $dx = 0.6H, n_x = n_y = 100$ 

## **Dispersion Relation**

$$\rho = \rho_0 + \varrho(x, y) e^{\sigma t} \cos kz$$

 $\rho_0 = \rho_c \left( 1 + \frac{r^2}{4H^2} \right)^{-1}$ 

![](_page_28_Figure_3.jpeg)

![](_page_28_Figure_4.jpeg)

unstable for radial collapse

## Summary

- Vertical (uniform) magnetic field works against fragmentation.
- Compressible mode is suppressed by rather weak magnetic field.
- Incompressible mode survives even when B is extremely strong, if the magnetic field is not fixed on the boundary.
- Weak magnetic field affects flow in the low density region.