

Forward Model Approach to LSS Analysis

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Forward Model Approach to LSS Analysis

Statistical Bayesian analysis:

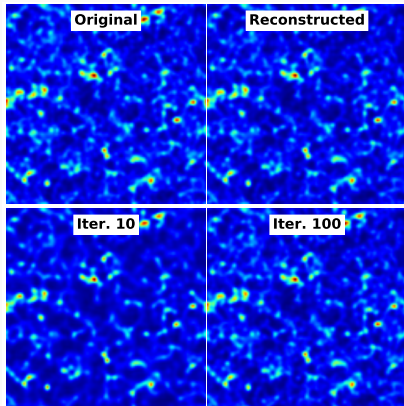
$$L(\mathbf{s}|\mathbf{d}) = (2\pi)^{\frac{-(M+N)}{2}} \det(\mathbf{S}\mathbf{N})^{\frac{-1}{2}} \exp\left(\frac{-\mathbf{s}^\dagger \mathbf{S}^{-1} \mathbf{s} - [\mathbf{d} - \mathbf{f}(\mathbf{s})]^\dagger \mathbf{N}^{-1} [\mathbf{d} - \mathbf{f}(\mathbf{s})]}{2}\right)$$

$$\chi^2(\mathbf{s}) = \mathbf{s}^\dagger \mathbf{S}^{-1} \mathbf{s} + [\mathbf{d} - \mathbf{f}(\mathbf{s})]^\dagger \mathbf{N}^{-1} [\mathbf{d} - \mathbf{f}(\mathbf{s})],$$

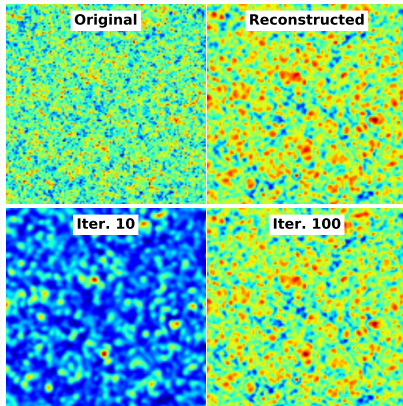
- **Prior:** Gaussian initial density Fourier modes 's' with linear power spectrum 'S'
- **Forward Model $\mathbf{f}(\mathbf{s})$:** take the initial density modes 's' and evolve them to the final observable corresponding to the data 'd'
- **High dimensional optimization problem** - (L)BFGS, HMC, Conjugate gradient \Rightarrow **Need gradients of forward model $\mathbf{f}(\mathbf{s})$**

MAP of Map

Final Conditions



Initial Conditions



Seljak et.al(arXiv:1706.06645)

Power Spectrum Reconstruction

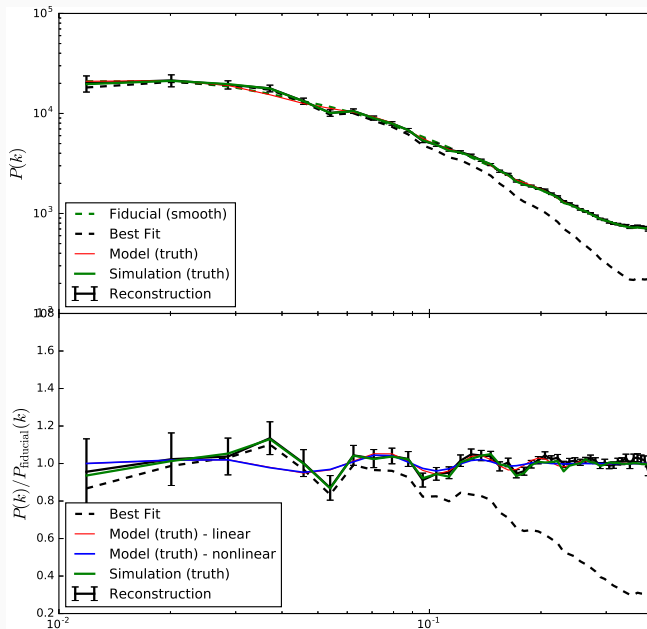
Integrate out the modes around the minimum variance map

$$\begin{aligned} P(\boldsymbol{\Theta}|d) &\propto L(d|\boldsymbol{\Theta}) = \int P(s, d|\boldsymbol{\Theta}) d^M \delta s \\ &= (2\pi)^{\frac{-(M+N)}{2}} \det(SN)^{\frac{-1}{2}} \exp\left(-\frac{1}{2} \left[\hat{s}^\dagger S^{-1} \hat{s} + (d - f(\hat{s}))^\dagger N^{-1} (d - f(\hat{s})) \right]\right) \times \\ &\quad \int \exp\left\{-\frac{1}{2} \delta s^\dagger D \delta s\right\} d^M s \\ &= (2\pi)^{-N/2} \det(SN\tilde{D})^{-1/2} \exp\left(-\frac{1}{2} \left[\hat{s}^\dagger S^{-1} \hat{s} + (d - f(\hat{s}))^\dagger N^{-1} (d - f(\hat{s})) \right]\right) \end{aligned}$$

Use Newton's Method to maximize the posterior

$$\begin{aligned} \ln L(\boldsymbol{\Theta}_{\text{fid}} + \Delta\boldsymbol{\Theta}) &= \ln L(\boldsymbol{\Theta}_{\text{fid}}) + \sum_l \left[\frac{\partial \ln L(\boldsymbol{\Theta})}{\partial \Theta_l} \right]_{\boldsymbol{\Theta}_{\text{fid}}} \Delta\Theta_l + \\ &\quad \frac{1}{2} \sum_{ll'} \left[\frac{\partial^2 \ln L(\boldsymbol{\Theta})}{\partial \Theta_l \partial \Theta_{l'}} \right]_{\boldsymbol{\Theta}_{\text{fid}}} \Delta\Theta_l \Delta\Theta_{l'} \\ (F\Delta\hat{\boldsymbol{\Theta}})_l &= \frac{1}{2} \hat{s}^\dagger S_{\text{fid}}^{-1} \mathbf{n}_l S_{\text{fid}}^{-1} \hat{s} - b_l \end{aligned}$$

Power Spectrum Reconstruction



- Redshift surveys observe galaxies
- Traditionally modeled as residing in halos
- Halo finders are complicated and not differentiable, need an analytic model
- Poisson sampling of halos

$$\delta_h(x) = b_1\delta_m(x) + b_2\delta_m^2(x)$$

Pros:

- Simple
- Well studied
- Performs quite well to model power spectra

Cons:

- Which biasing scheme?
- Mass information is marginalized over
- Negative b_2 leads to negative over-densities
- Model a discrete field with continuous field

Bias Prescription

Forward model approach requires comparing the two fields at point level.

Stochasticity

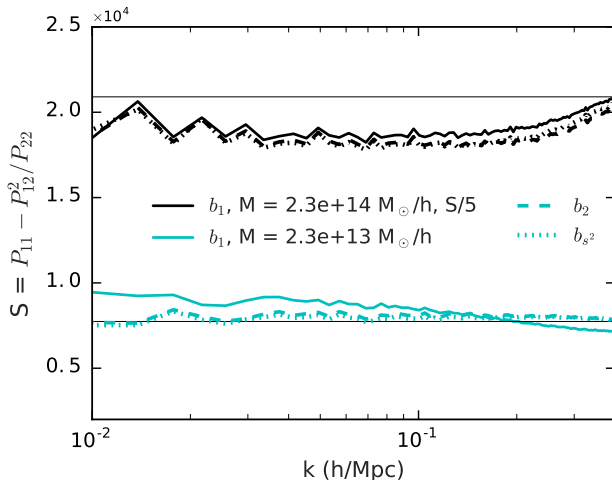
$$S_{XY} = P_{XX} - \frac{P_{XY}^2}{P_{YY}}$$

X = halo field (δ_h)

Y = model field

$$(b_1 \delta_m + \frac{b_2}{2} \delta_m^2 + b_{s^2} s^2)$$

Modi et.al (arXiv:
1612.01621)

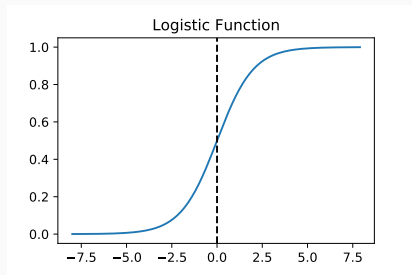


Analytic Transformations of Density Field- Sigmoid

Halos form at positions where the
over-density crosses a threshold
(δ_T)

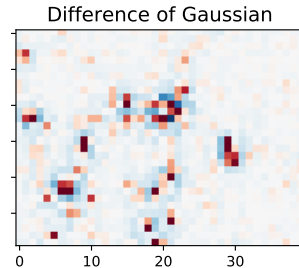
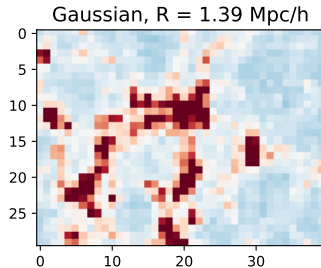
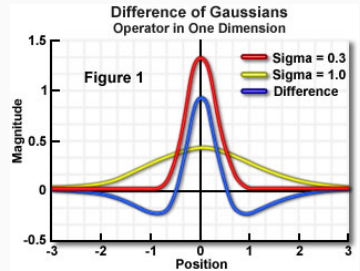
$$g(\delta) = \frac{1}{1 + e^{-z}}$$
$$z = \alpha(\delta - \delta_T)$$

In a spherical collapse universe:
 $\delta_T = 1.686 (178)$



Analytic Transformations - Difference of Gaussians

- Halos are peaks
- Blob detection in image processing - Difference of Gaussian
- Excursion set peaks in scales

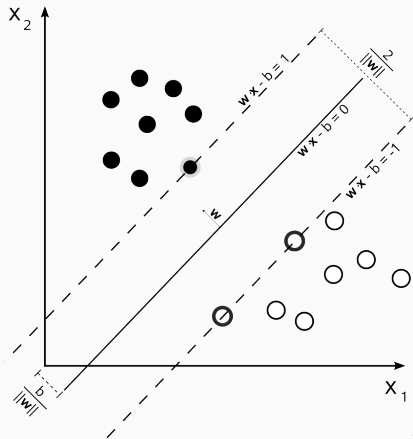


Analytic Transformations - Support Vector Machines

Given labeled training data, the support vector machines outputs an optimal hyperplane which categorizes new examples

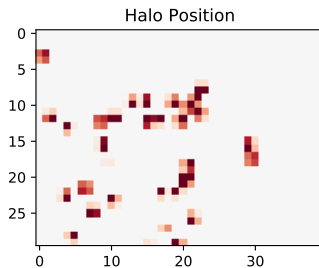
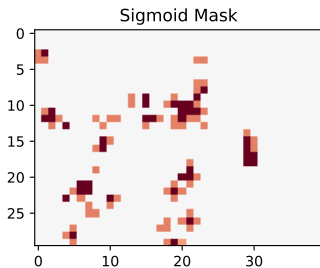
- Allows us to go beyond 2 features - shear, velocity field
- A semi-rigorous way to find the thresholds

$$\sum_i w_i \times f_i + z = 0$$



Mask of positions

How do positions look like?

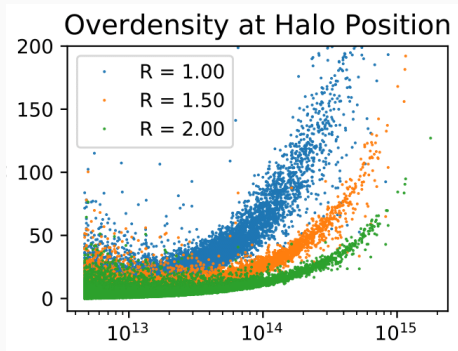


Mass Scaling

- Can use information about mass in addition to position from the data (through luminosity, number density etc.)
- From simulations, use gridded smoothed density field at multiple smoothing scales to get an estimate of mass
- Develop analytic formulation or simply use ML

$$M_h = 10^y \times (a\delta^2 + b\delta + c)$$

a, b, c, y : Free parameters that
can be fit for



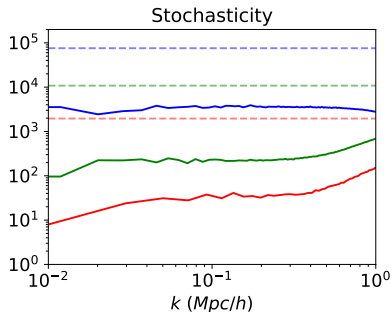
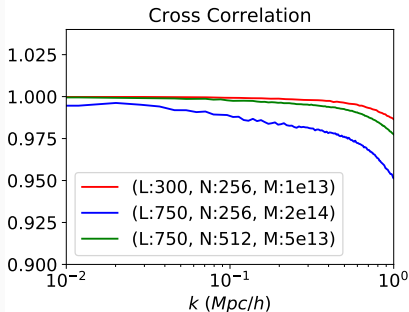
Performance: 2 Point Statistics

Cross correlation coefficient

$$C = \frac{P_{XY}}{\sqrt{P_{XX}P_{YY}}}$$

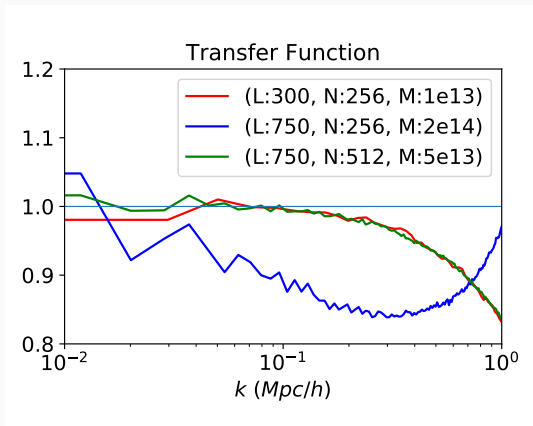
Stochasticity

$$S = P_{XX} - \frac{P_{XY}^2}{P_{YY}}$$

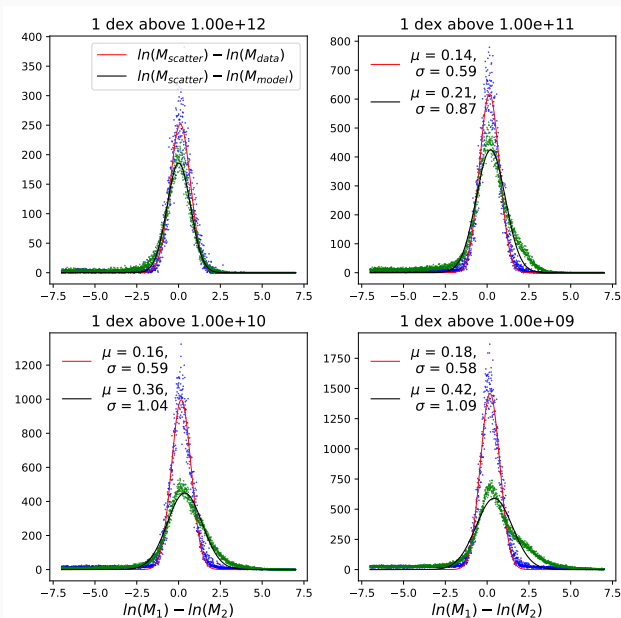


Performance: 2 Point Statistics

- Order of magnitude reduction in stochasticity
- Cross-correlation coefficient > 0.95
- Transfer function ~ 1
- Fit parameters independent of initial seed

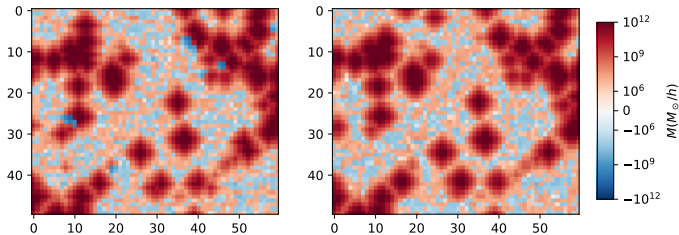


Noise Model



Picture Worth a Thousand Words?

One of these is the analytically created halo field and other shows FOF halos (both smoothed on some scale).



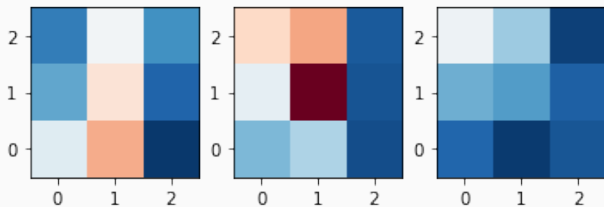
Summary

- Forward model approach to LSS in Bayesian framework
- Reconstruct initial density field and power spectrum starting from final matter field
- Need analytic methods to model galaxies and halos in order to use redshift survey data
- Bias model does not model halo field very well
- We propose modeling by using logistic function and difference of Gaussian to model halos as density threshold and peak
- This reduces stochasticity by about an order of magnitude

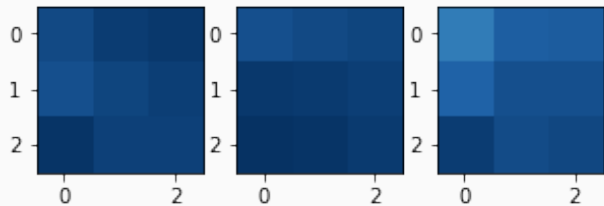
Thank You!

Neural Net Features

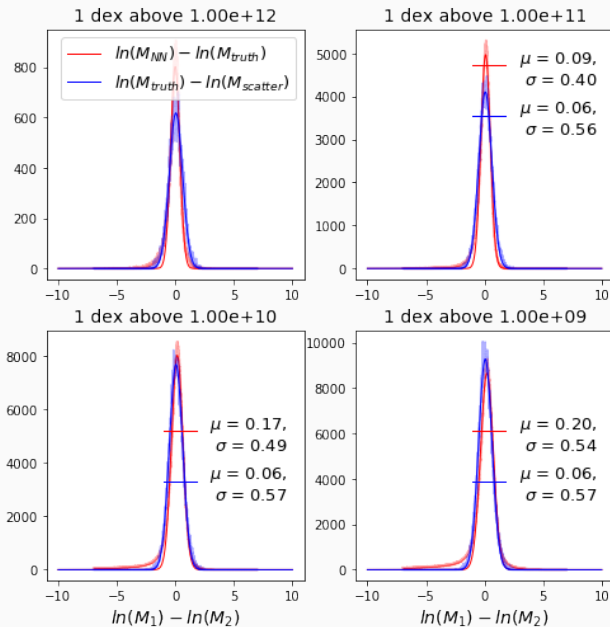
6.57e+12



[0.]



Point by point comparison - Neural Net



Noise Model - Neural Net

