

# Dynamical Reconstruction of Linear Universe

Preliminary results

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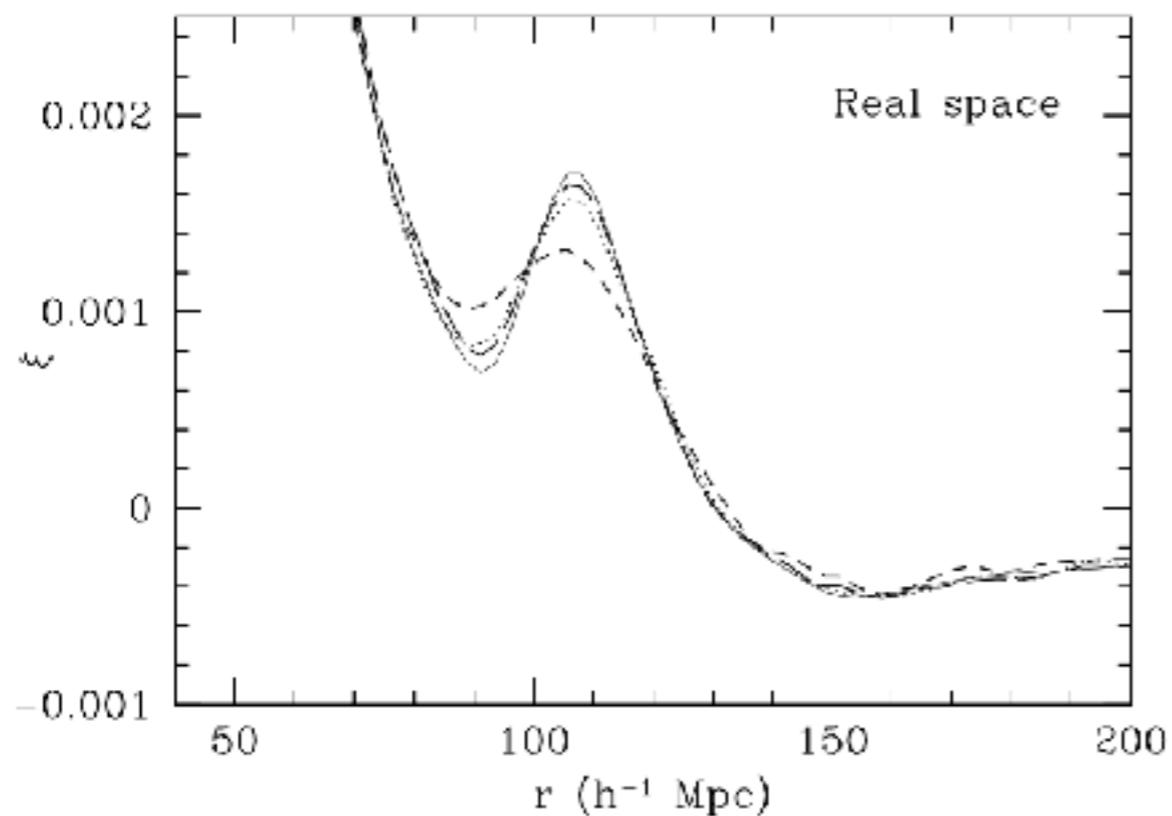
Nordita Stockholm  
07.26.2017

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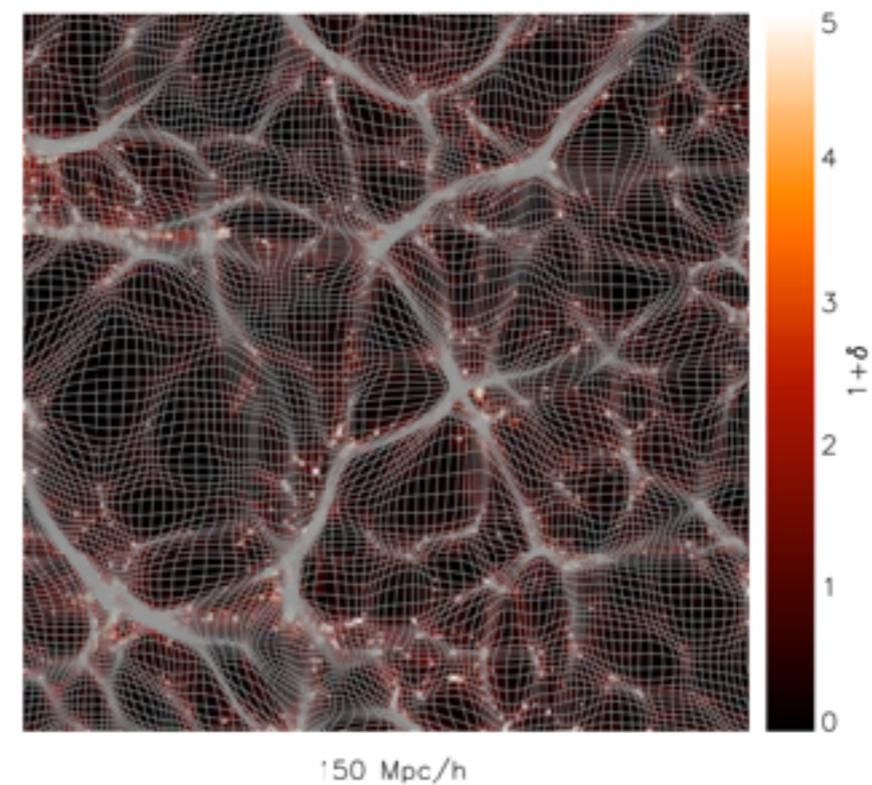


# Current Status

- Lagrangian Reconstruction Algorithm (Eisenstein, Seo et al. 2007)
- Eulerian Reconstruction Algorithm (Schmittfull et al. 2015)
- Non-linear Reconstruction Method (Zhu et al. 2017)
- ...



Eisenstein, Seo et al. *Astrophys. J.* 2007



Zhu et al. *ArXiv Eprint* 1611.09638 2017

# Dynamical Reconstruction: Theory

- Theory

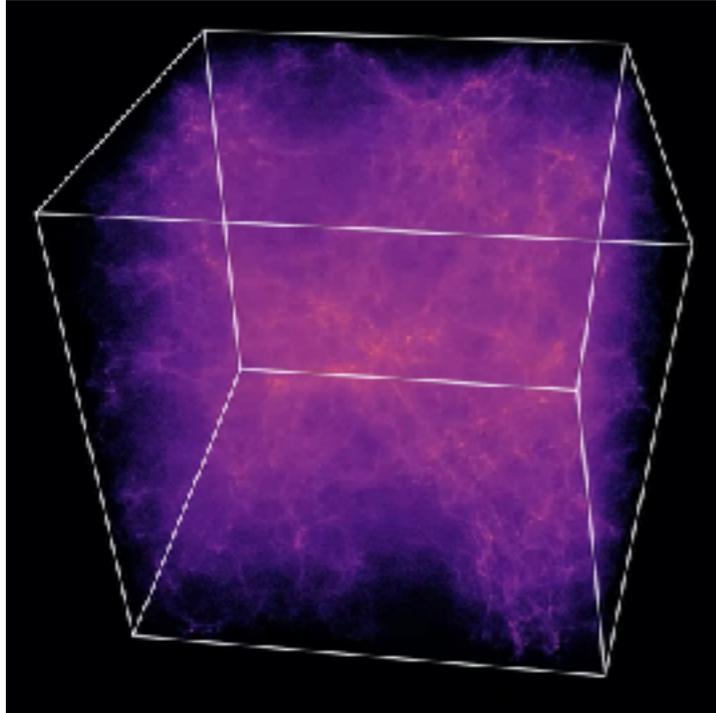
	Forward in time	Back in time
Initial condition	$\mathbf{x}_i, \mathbf{v}_i$ at early time	
Governing Equation	$\nabla^2 \phi = 4\pi G \rho$ $\frac{d\mathbf{r}}{dt} = +\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = -\nabla \phi$	
Output	$\mathbf{x}_0, \mathbf{v}_0$ at late time	

# Dynamical Reconstruction: Theory

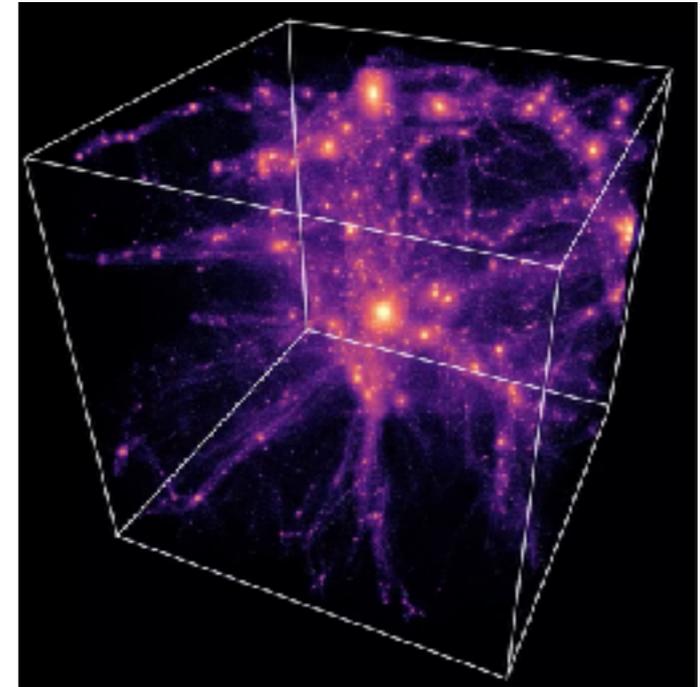
- Theory

	Forward in time	Back in time
Initial condition	$\mathbf{x}_i, \mathbf{v}_i$ at early time	$\mathbf{x}_0, -\mathbf{v}_0$ at late time
Governing Equation	$\nabla^2 \phi = 4\pi G \rho$ $\frac{d\mathbf{r}}{dt} = +\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = -\nabla \phi$	$\nabla^2 \phi = 4\pi G \rho$ $\frac{d\mathbf{r}}{dt} = -\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = +\nabla \phi$
Output	$\mathbf{x}_0, \mathbf{v}_0$ at late time	$\mathbf{x}_i, -\mathbf{v}_i$ at early time

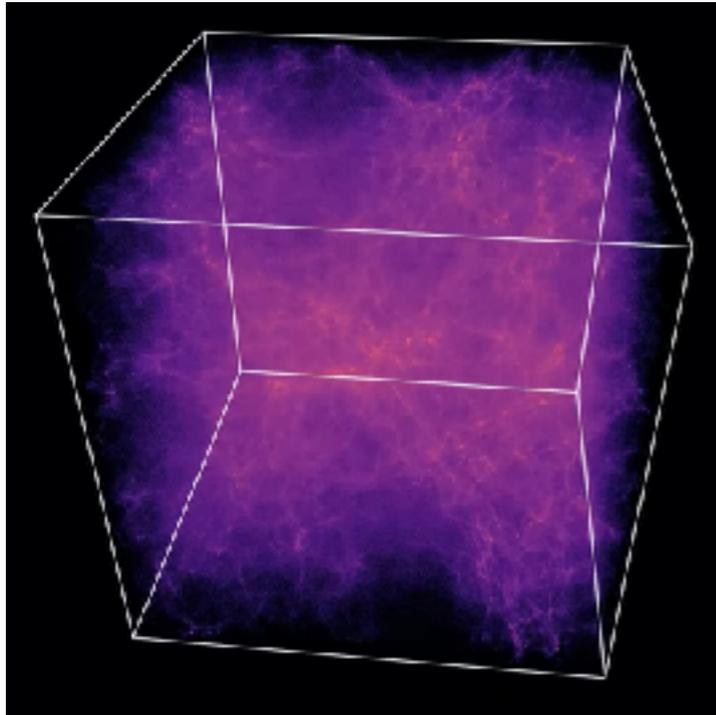
# Dynamical reconstruction in action



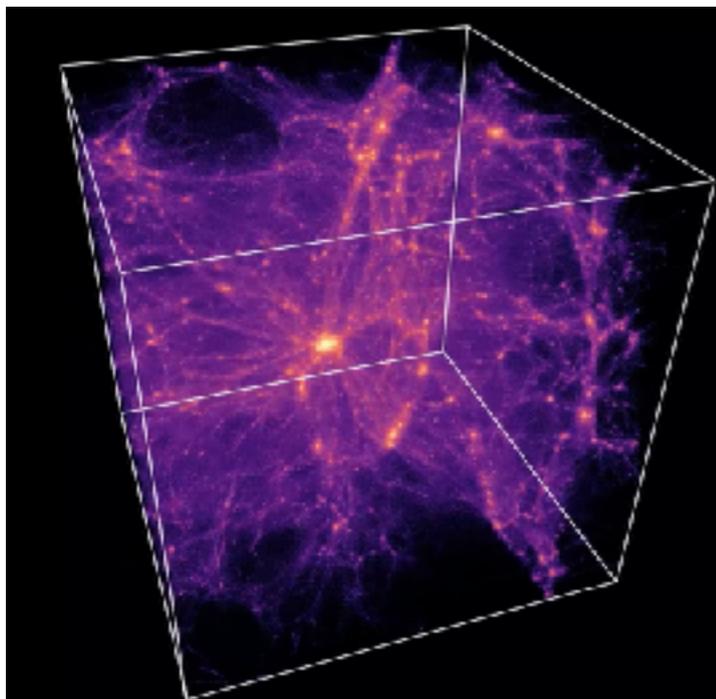
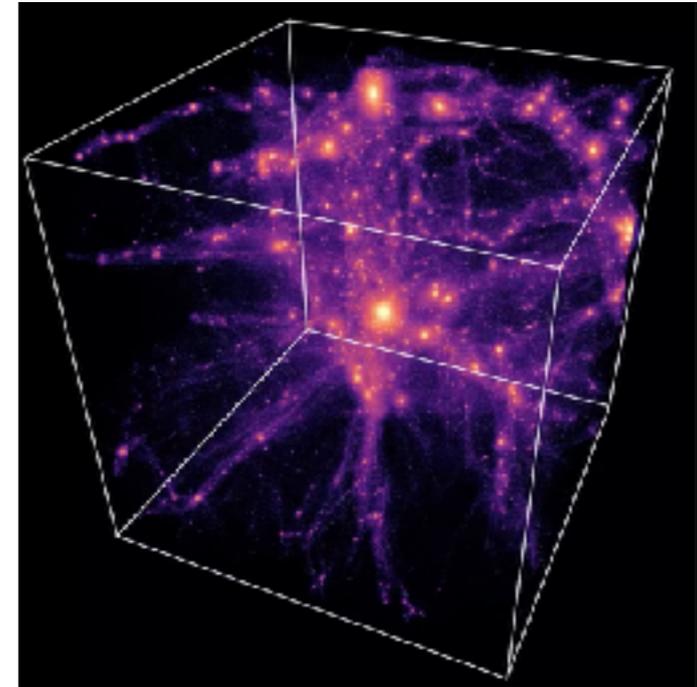
$$\nabla^2 \phi = 4\pi G \rho$$
$$\frac{d\mathbf{r}}{dt} = +\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = -\nabla \phi$$



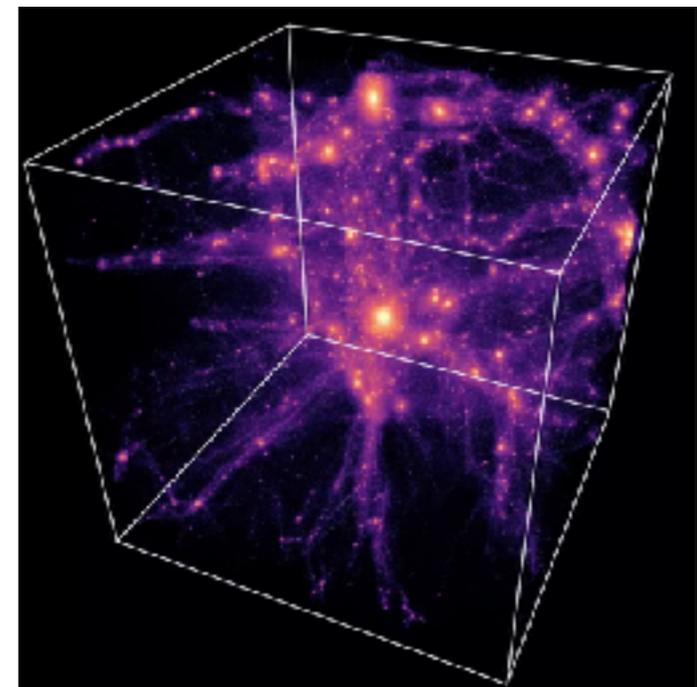
# Dynamical reconstruction in action



$$\nabla^2 \phi = 4\pi G \rho$$
$$\frac{d\mathbf{r}}{dt} = +\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = -\nabla \phi$$



$$\nabla^2 \phi = 4\pi G \rho$$
$$\frac{d\mathbf{r}}{dt} = -\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = +\nabla \phi$$



# Dynamical Reconstruction: Theory

- Theory

	Forward in time	Back in time
Initial condition	$\mathbf{x}_i, \mathbf{v}_i$ at early time	$\mathbf{x}_0, -\mathbf{v}_0$ at late time
Governing Equation	$\nabla^2 \phi = 4\pi G \rho$ $\frac{d\mathbf{r}}{dt} = +\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = -\nabla \phi$	$\nabla^2 \phi = 4\pi G \rho$ $\frac{d\mathbf{r}}{dt} = -\mathbf{u}, \quad \frac{d\mathbf{u}}{dt} = +\nabla \phi$
Output	$\mathbf{x}_0, \mathbf{v}_0$ at late time	$\mathbf{x}_i, -\mathbf{v}_i$ at early time

- What is this good for?

- Accessing more linear modes by moving the observation to earlier times
- BAO reconstruction

# Dynamical Reconstruction: Challenges

- incomplete phase space information
  - Velocity reconstruction at late time

$$\mathbf{x}(t) = \mathbf{q} + \Psi(\mathbf{q}, t) \quad \leftarrow \text{Lagrangian Point of view}$$

$$\nabla \cdot \Psi = -\delta \quad \mathbf{v} = aH f \Psi$$

Zeldovich Approximation

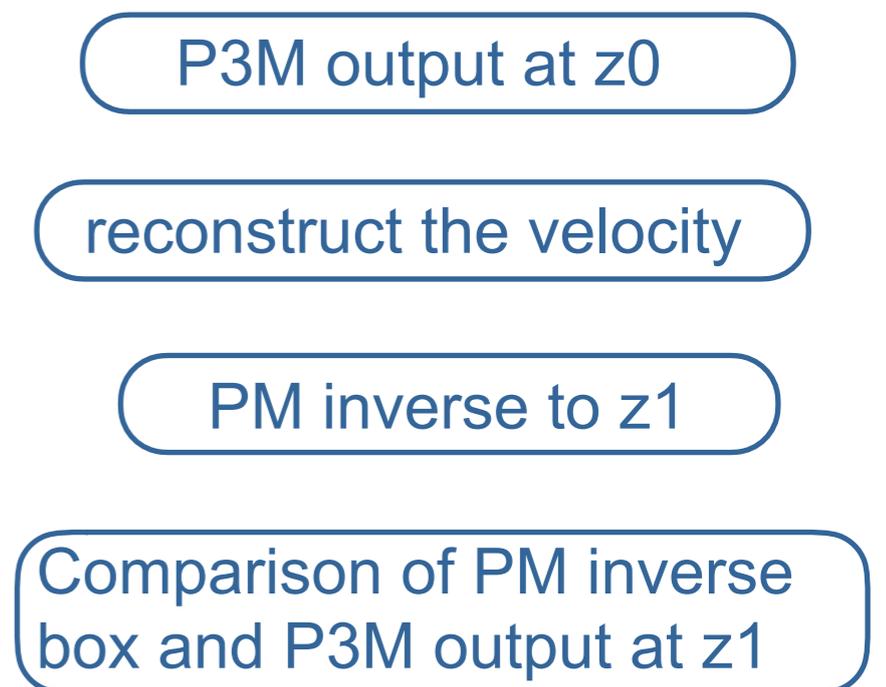
- Decaying modes

$$\delta(\mathbf{x}, t) = A(\mathbf{x}, t)D_1(t) + B(\mathbf{x}, t)D_2(t)$$

$$D_1(t) \propto t^{2/3} \propto a, \quad D_2(t) \propto t^{-1} \propto a^{-3/2} \quad (\Omega_m = 1)$$

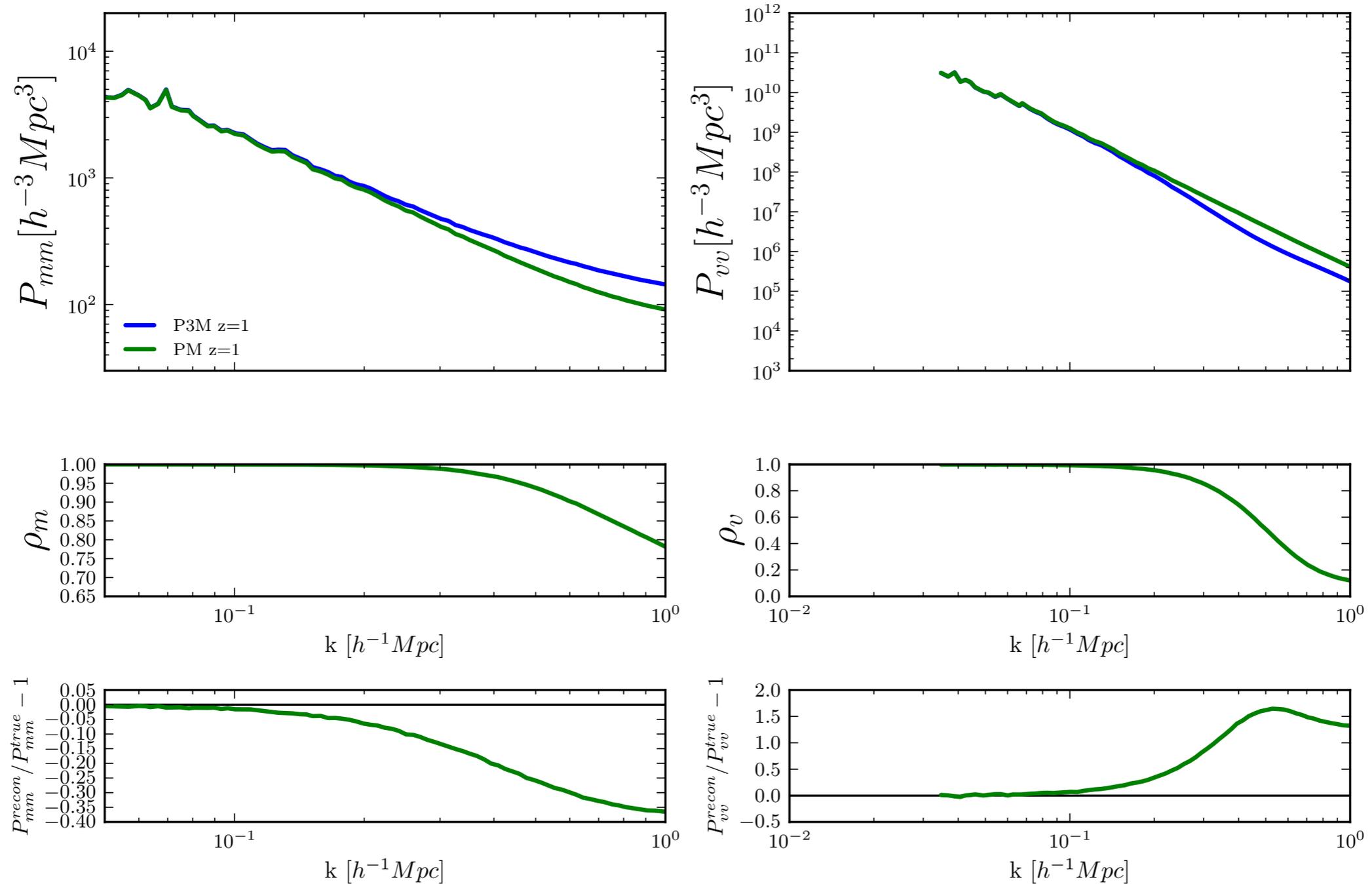
# Dynamical Reconstruction: Method

- Simulation
  - Algorithm: P3M; Parameters: Planck
  - Box size:  $512^3$  Mpc/h
  - Number of particles:  $128^3$
- Algorithm of dynamical reconstruction
  - Zeldovich reconstruction of velocity at initial redshift
  - Inverse particle mesh code
- Accuracy Checks
  - Matter (velocity) power spectrum
  - Matter (velocity) correlation coefficient



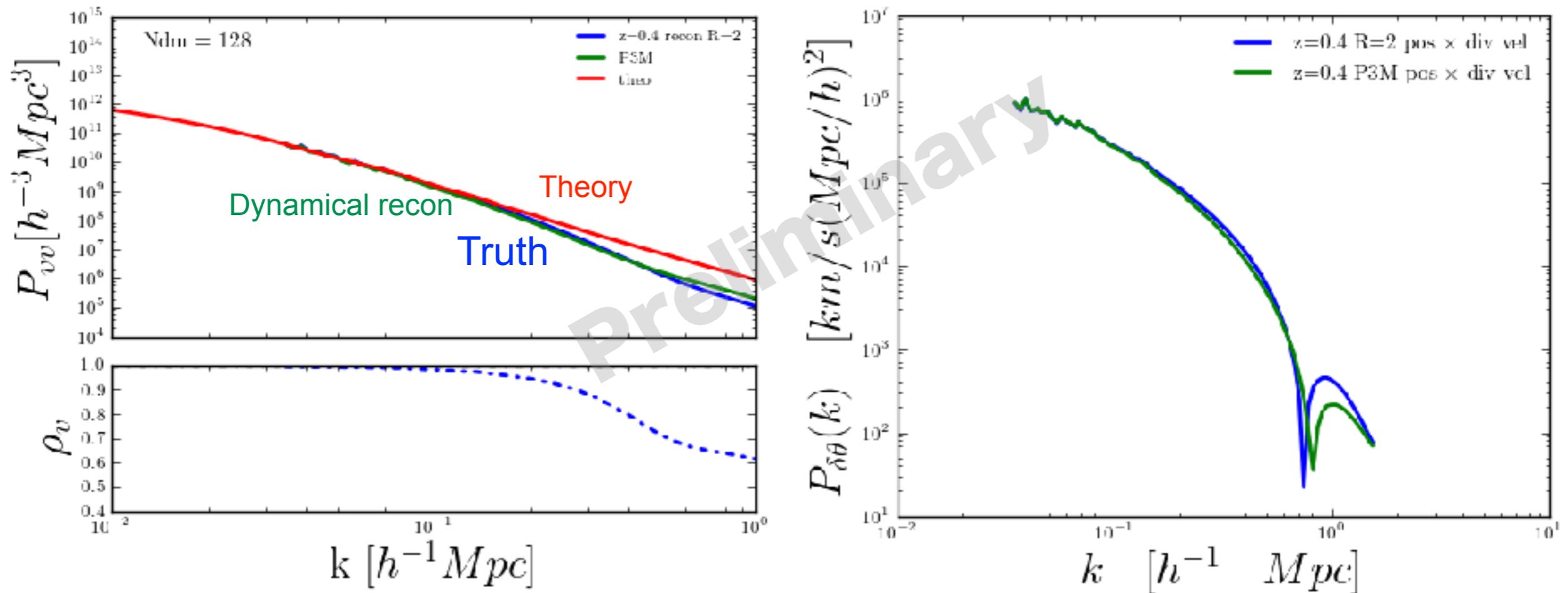
$$\rho_m = \frac{P_{mm}(k)_{true \times recon}}{\sqrt{P_{mm}(k)_{true} P_{mm}(k)_{recon}}}$$
$$\rho_v = \frac{P_{vv}(k)_{true \times recon}}{\sqrt{P_{vv}(k)_{true} P_{vv}(k)_{recon}}}$$

# Dynamical Reconstruction: simple test



# Dynamical Reconstruction Step 1: Velocity reconstruction at initial redshift

- velocity reconstruction at  $z = 0.4$



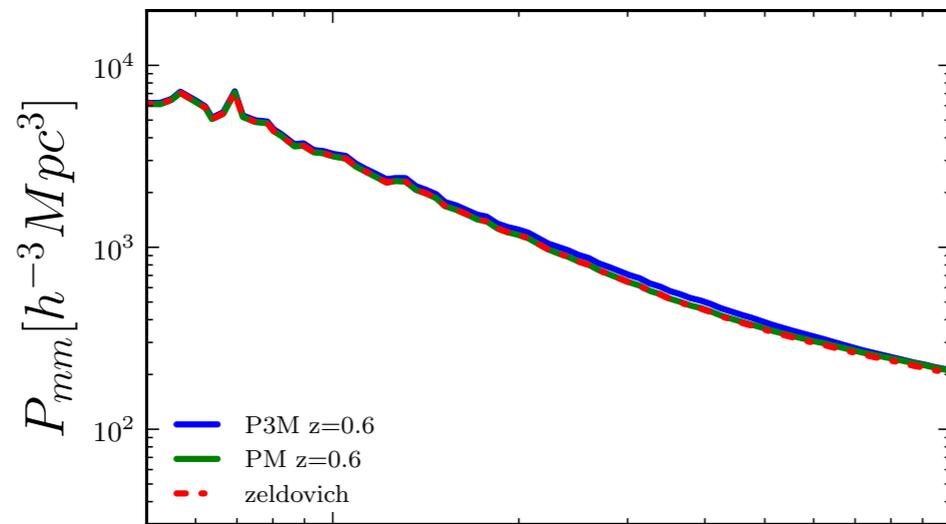
- R: smoothing scale for density

- Linear theory:  $p_{vv}(k) = a^2 H^2 f^2 P_{mm}(k) / k^2$

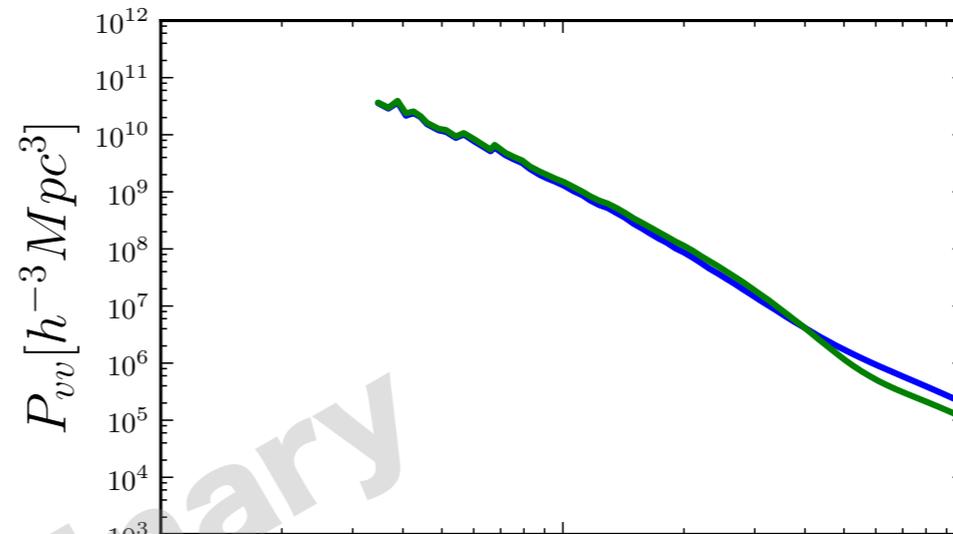
$$p_{\delta\theta}(k) = aHfP_{mm}(k) / k^2 \quad (\theta = \nabla \cdot \mathbf{v})$$

# Dynamical Reconstruction step 2: Moving from $z=0.4$ to $0.6$ (Move back 1.43 Gyr)

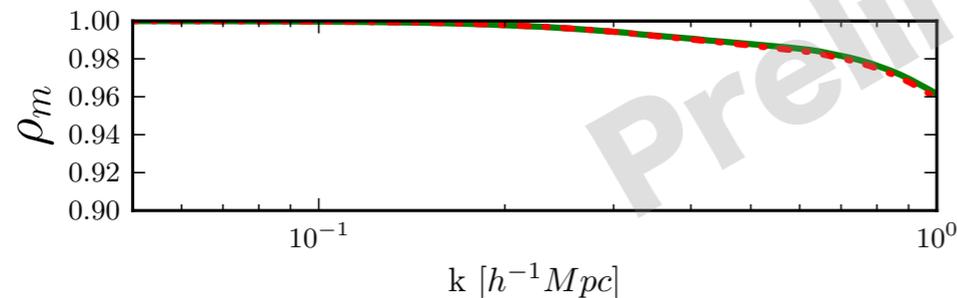
## Matter Power-spectrum



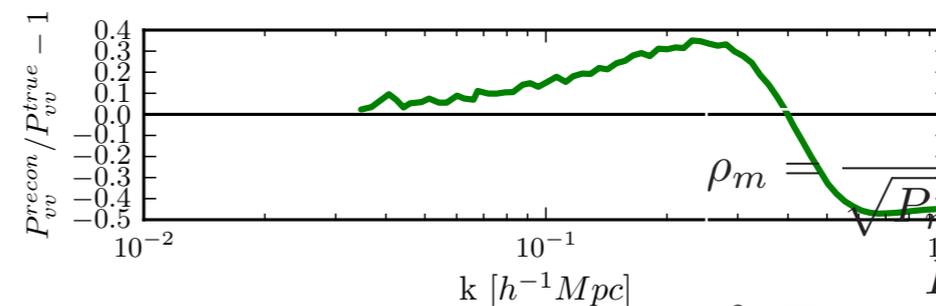
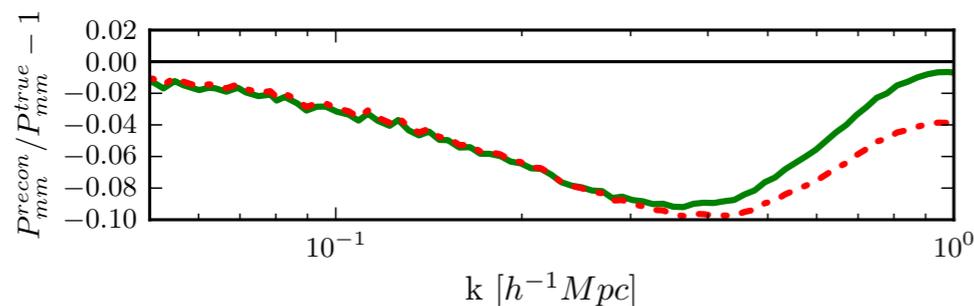
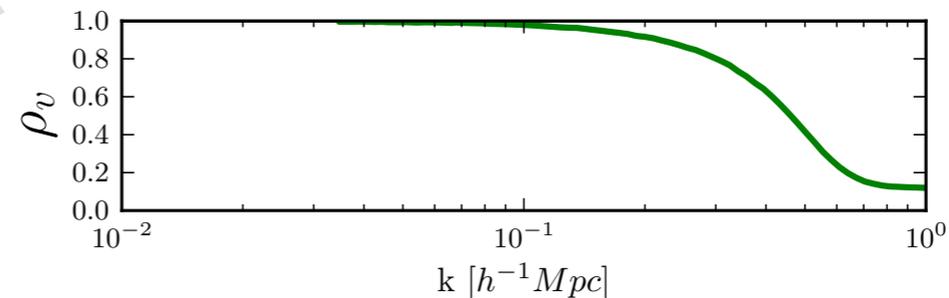
## Velocity Power-spectrum



## Matter Correlation coefficient



## Velocity Correlation coefficient



$$\rho_m = \frac{P_{mm}(k)_{true \times recon}}{\sqrt{P_{mm}(k)_{true} P_{mm}(k)_{recon}}}$$

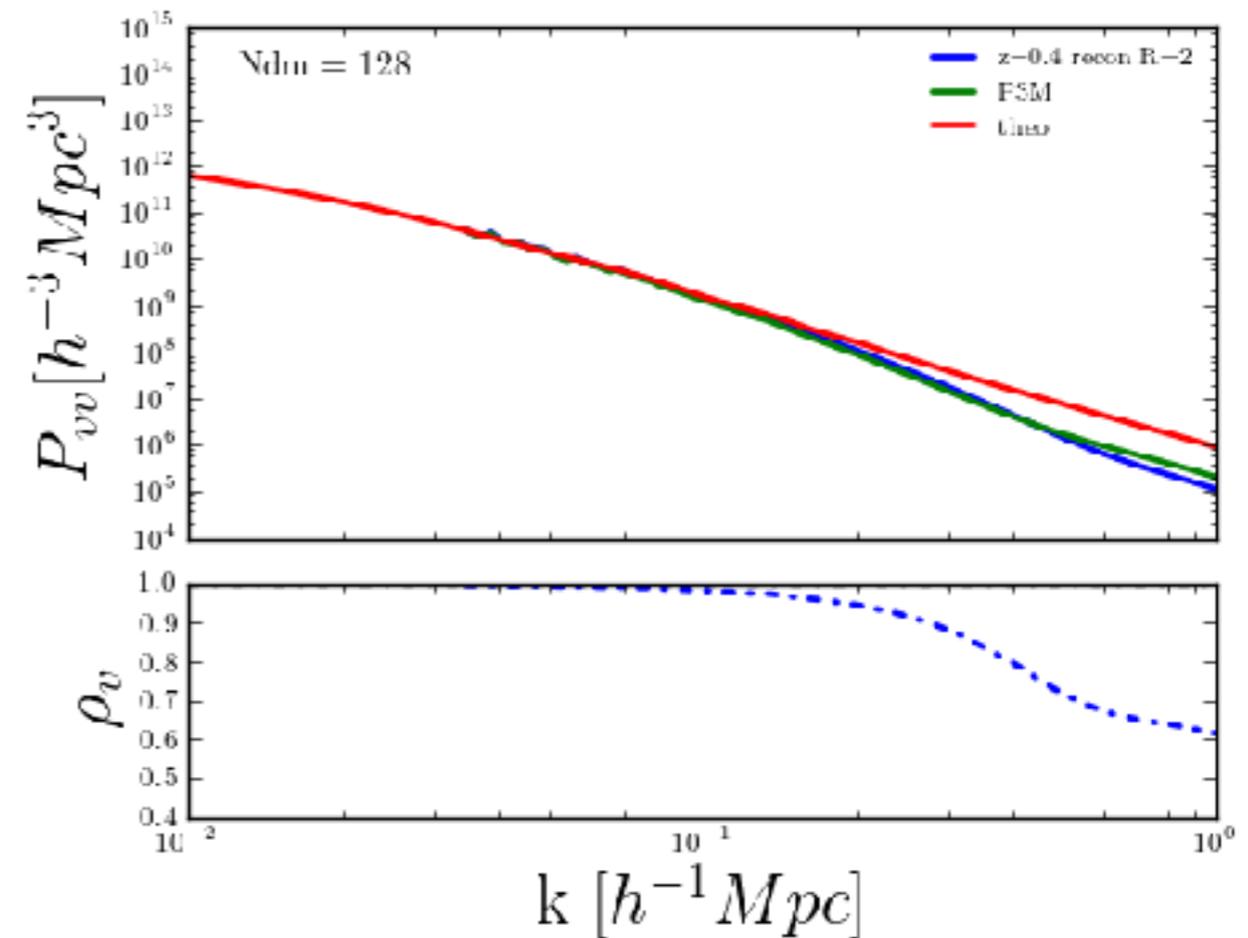
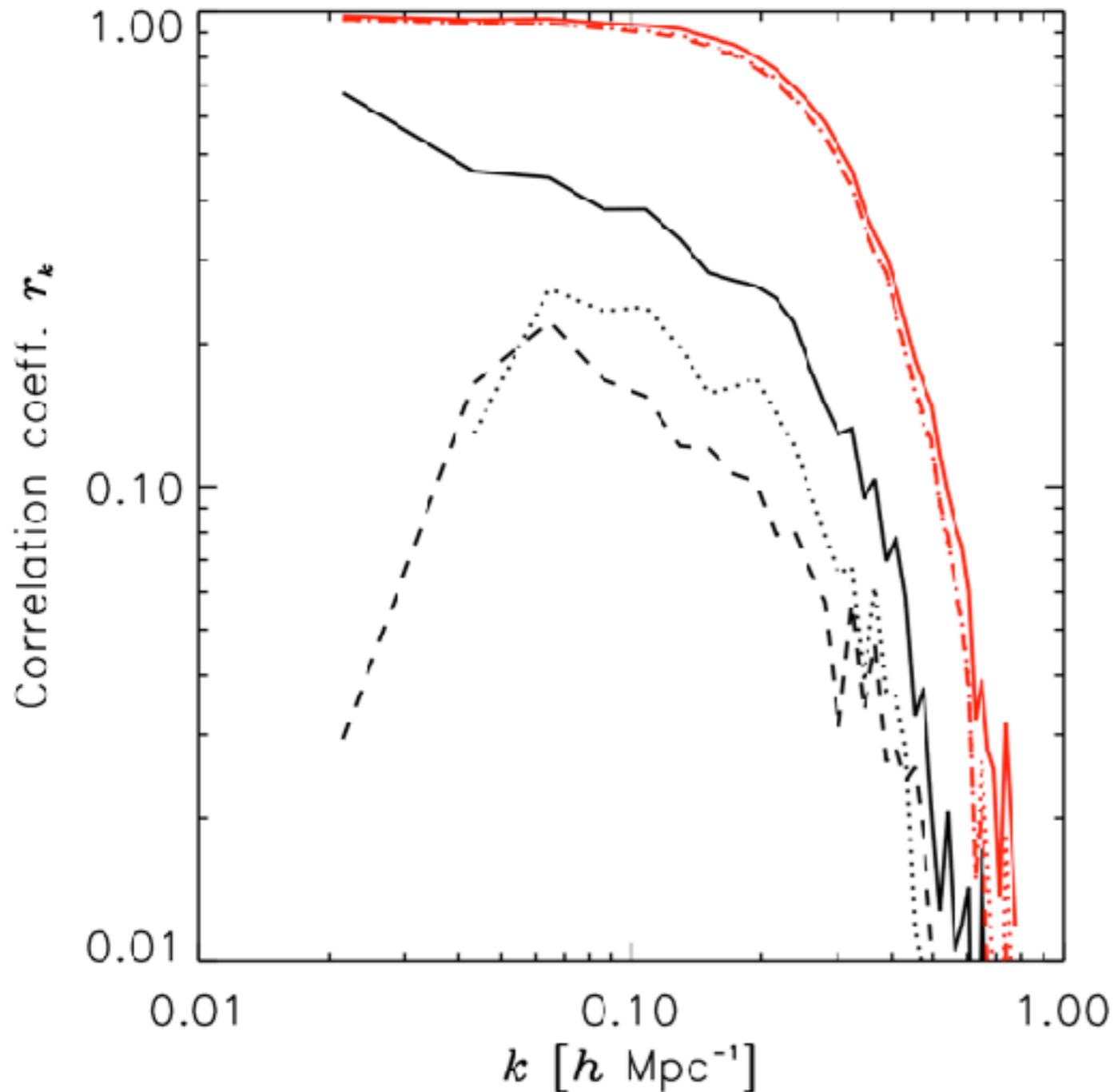
$$\rho_v = \frac{P_{vv}(k)_{true \times recon}}{\sqrt{P_{vv}(k)_{true} P_{vv}(k)_{recon}}}$$

98% reconstruction at  $k=0.5 \text{ h/Mpc}$

# Dynamical Reconstruction: how to improve?

- Smoothing scales, mesh size
- number of particles
- leap frog algorithm
- .....

# Dynamical Reconstruction: velocity construction comparison



# Future direction of dynamic reconstruction project

- theory paper
  - parameters check: smoothing scales, mesh size, number of particles
  - comparison with previous reconstruction paper
    - BAO reconstruction
    - velocity reconstruction
- data paper
  - test with galaxies
  - apply to real data
    - doing cosmology analysis with more linear fields
    - velocity reconstruction
    - BAO reconstruction
  - relative velocity between dark matter and baryons