

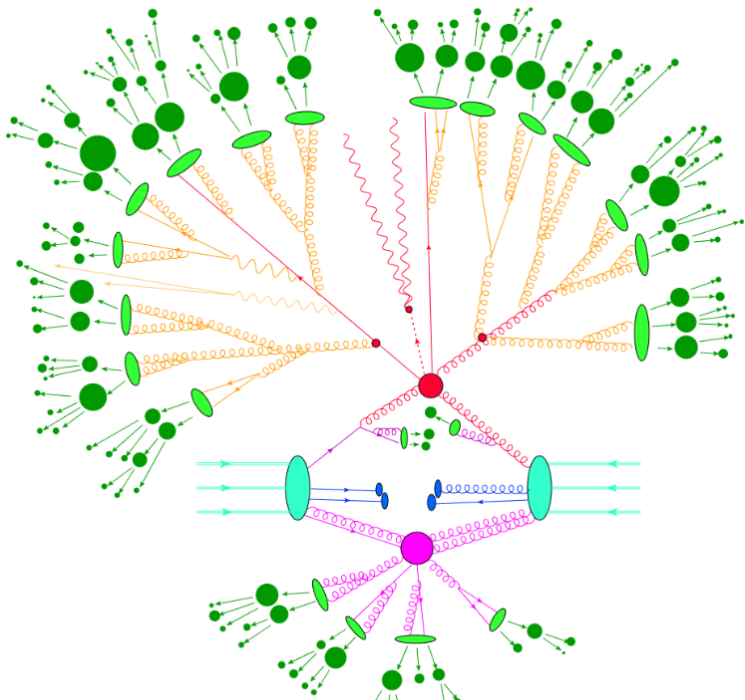
Tropical Feynman integration in the physical region

Felix Tellander

June 15, 2023

Based on [\[2302.08955\]](#) with
M. Borinsky and H. J. Munch



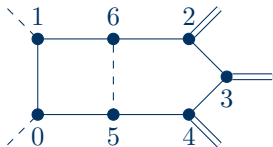
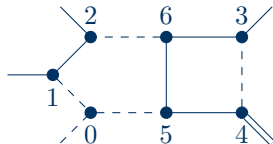


Two-loop box and pentagon integrals

indep. kinem. scales	massive/off-shell legs	internal masses	process	full σ
$2 \rightarrow 2$				
2	0	0	$\gamma\gamma$	2011
2	0	0	jj (lc)	2017
2	0	0	$\gamma + j$	2017
3	2	1	$t\bar{t}$	2013
3	2	0	VV	2014
4	2	0	VV'	2015
3	1	0	$V + j$	2015
3	1	0	$H + j$ (HTL)	2015
4	2	1	HH	2016
4	1	1	$H + j$	2018
3	0	1	$gg \rightarrow \gamma\gamma$	2019
4	2	1	$gg \rightarrow ZZ$	2020
4	2	1	$gg \rightarrow WW$	2020
5	2	1	$gg \rightarrow ZH$	2021
4	2	1	QCD-EW DY	2022
$2 \rightarrow 3$				
4	0	0	3γ	2019
4	0	0	$\gamma\gamma j$	2021
4	0	0	$3j$	2021
5	1	0	$Wb\bar{b}$	2022

Analytic results: one off-shell leg [\[2005.04195,2107.14180\]](#)

Today:



Why not NIntegrate?

Why not NIntegrate?

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

Why not NIntegrate?

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

```
In[] NIntegrate[1/(x+y), {x,0,1}, {y,0,1},  
Method->{"MonteCarlo", "RandomSeed"->19950309}]
```

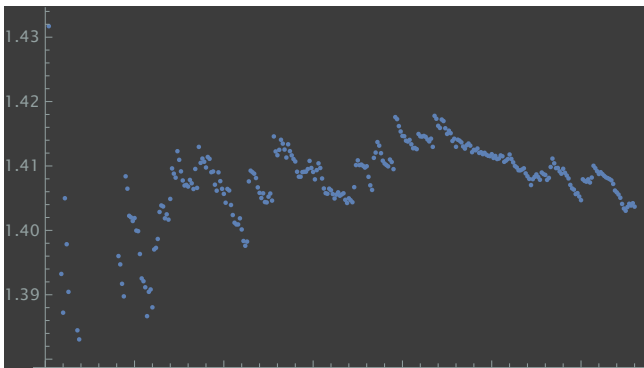
```
Out[] 0.998259
```

Why not NIntegrate?

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

```
In[] NIntegrate[1/(x+y), {x,0,1}, {y,0,1},  
Method->{"MonteCarlo", "RandomSeed"->19950309}]
```

```
Out[] 0.998259
```



Reason?

Even though

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

is convergent.

Reason?

Even though

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

is convergent. The integral

$$\int_0^1 \int_0^1 \frac{1}{(x+y)^2} dx dy = \infty$$

is divergent, so

$$\text{Var} \left(\frac{1}{x+y} dx_{[0,1]} dy_{[0,1]} \right) = \infty$$

Reason?

Even though

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

is convergent. The integral

$$\int_0^1 \int_0^1 \frac{1}{(x+y)^2} dx dy = \infty$$

is divergent, so

$$\text{Var} \left(\frac{1}{x+y} dx_{[0,1]} dy_{[0,1]} \right) = \infty$$

The Monte Carlo estimate is

$$\frac{1}{N} \sum_{i=1}^N \frac{1}{x_i + y_i} + \mathcal{O} \left(\sqrt{\frac{\infty}{N}} \right)$$

Reason?

Even though

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \log 2 \approx 1.3863$$

is convergent. The integral

$$\int_0^1 \int_0^1 \frac{1}{(x+y)^2} dx dy = \infty$$

is divergent, so

$$\text{Var} \left(\frac{1}{x+y} dx_{[0,1]} dy_{[0,1]} \right) = \infty$$

The Monte Carlo estimate is

$$\frac{1}{N} \sum_{i=1}^N \frac{1}{x_i + y_i} + \mathcal{O} \left(\sqrt{\frac{\infty}{N}} \right)$$

This type of integrable boundary singularities are ubiquitous in Feynman integrals.

Feynman integration software

- `pySecDec` [Borowka et al.]
 - `FIESTA` [Smirnov]
 - `DiffExp` [Hidding]
 - `AMFlow` [Liu, Ma]
 - `SeaSyde` [Armadillo et al.]
 - `HyperInt` [Panzer]
-

Feynman integration software

- `pySecDec` [Borowka et al.]
- `FIESTA` [Smirnov]
- `DiffExp` [Hidding]
- `AMFlow` [Liu, Ma]
- `SeaSyde` [Armadillo et al.]
- `HyperInt` [Panzer]

-
- `feyntrop` [Borinsky, Munch and FT]

Uses *tropical Monte Carlo integration* and can be applied to Euclidean as well as Minkowski kinematics.

True power: On your laptop you can evaluate high-loop multi-scale integrals in *minutes to reasonable error*.

The Feynman Integral

$$\mathcal{I} = \lim_{\varepsilon \rightarrow 0^+} \Gamma(\omega) \int_{\mathbb{R}_+^E} \prod_{e \in E} \left(\frac{x^{\nu_e} dx_e}{\Gamma(\nu_e) x_e} \right) \mathcal{U}^{-D/2} \frac{\delta(1 - x_1 - \dots - x_E)}{(\mathcal{V} - i\varepsilon \sum_{e \in E} x_e)^\omega}$$

with the superficial degree of divergence

$$\omega := \sum_{e \in E} \nu_e - LD/2$$

where ν_e are propagator powers and $\mathcal{V} = \mathcal{F}/\mathcal{U}$ with homogeneous graph/Symanzik polynomials

$$\mathcal{U} = \sum_{T \text{ a spanning tree of } G} \prod_{e \notin T} x_e, \quad \deg(\mathcal{U}) = L$$

$$\mathcal{F} = \mathcal{F}_m + \mathcal{F}_0 = \mathcal{U} \sum_{e \in E} m_e^2 x_e - \sum_{F \text{ a spanning 2-forest of } G} \rho(F)^2 \prod_{e \notin F} x_e, \quad \deg(\mathcal{F}) = L + 1$$

Contour Deformation

Why $i\varepsilon$?

Chooses the causal branch and ensures the convergence.

Contour Deformation

Why $i\varepsilon$?

Chooses the causal branch and ensures the convergence.

Why not $i\varepsilon$?

- Modifies the analytic structure by displacing branch points and introducing spurious branch cuts.
 - Numerics is hard, as $\varepsilon \rightarrow 0$ poles can get arbitrarily close to the integration contour.
-

Contour Deformation

Why $i\varepsilon$?

Chooses the causal branch and ensures the convergence.

Why not $i\varepsilon$?

- Modifies the analytic structure by displacing branch points and introducing spurious branch cuts.
 - Numerics is hard, as $\varepsilon \rightarrow 0$ poles can get arbitrarily close to the integration contour.
-

Instead: Change of variables

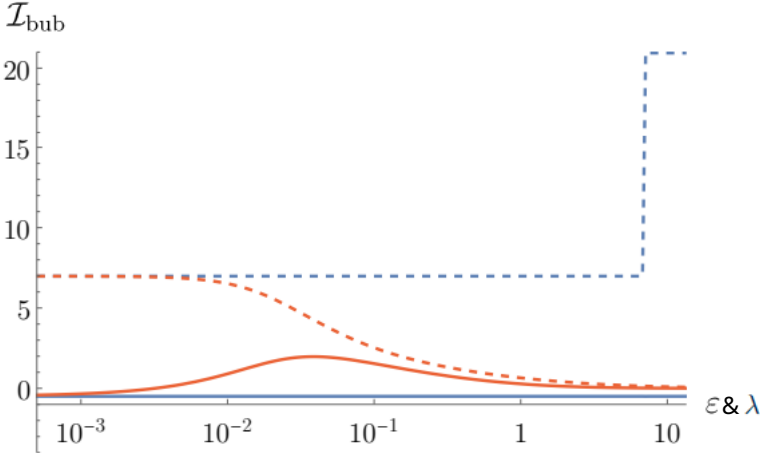
$$x_e = x_e \exp\left(-i\lambda \frac{\partial \mathcal{V}}{\partial x_e}\right)$$

Picks the same causal branch as $i\varepsilon$ as long as λ is *sufficiently small* and

$$x_e \frac{\partial \mathcal{V}}{\partial x_e} \neq 0 \quad \forall e \in E$$

i.e. the *Landau equations* have no solutions.

Comparison with direct numerics on the Feynman parameterization with $i\epsilon$ and with deformation:



[Hannesdottir, Mizera]

For too large λ we get a jump.

Tropical Monte Carlo

The *tropical approximation* of a polynomial $p(\mathbf{x}) = \sum_{\alpha \in \text{supp}(p)} c_{\alpha} \mathbf{x}^{\alpha}$:

$$p^{\text{tr}}(\mathbf{x}) = \max_{\alpha \in \text{supp}(p)} \{c_{\alpha} \mathbf{x}^{\alpha}\}.$$

Tropical Monte Carlo

The *tropical approximation* of a polynomial $p(\mathbf{x}) = \sum_{\alpha \in \text{supp}(p)} c_{\alpha} \mathbf{x}^{\alpha}$:

$$p^{\text{tr}}(\mathbf{x}) = \max_{\alpha \in \text{supp}(p)} \{c_{\alpha} \mathbf{x}^{\alpha}\}.$$

Theorem

For a homogeneous polynomial $p \in \mathbb{C}[x_1, \dots, x_n]$ that is completely non-vanishing in \mathbb{P}_+^n there exists constants $C_1, C_2 > 0$ s.t.

$$C_1 \leq \frac{|p(\mathbf{x})|}{p^{\text{tr}}(\mathbf{x})} \leq C_2 \quad \text{for all } \mathbf{x} \in \mathbb{P}_+^n$$

Tropical Monte Carlo

The *tropical approximation* of a polynomial $p(\mathbf{x}) = \sum_{\alpha \in \text{supp}(p)} c_{\alpha} \mathbf{x}^{\alpha}$:

$$p^{\text{tr}}(\mathbf{x}) = \max_{\alpha \in \text{supp}(p)} \{c_{\alpha} \mathbf{x}^{\alpha}\}.$$

Theorem

For a homogeneous polynomial $p \in \mathbb{C}[x_1, \dots, x_n]$ that is completely non-vanishing in \mathbb{P}_+^n there exists constants $C_1, C_2 > 0$ s.t.

$$C_1 \leq \frac{|p(\mathbf{x})|}{p^{\text{tr}}(\mathbf{x})} \leq C_2 \quad \text{for all } \mathbf{x} \in \mathbb{P}_+^n$$

Key assumption: You can find bounds on a deformed polynomial with the un-deformed one.

i.e. there are λ dependent constants $C_1(\lambda), C_2(\lambda) > 0$ s.t.

$$C_1(\lambda) \leq \left| \left(\frac{\mathcal{U}^{\text{tr}}(\mathbf{x})}{\mathcal{U}(\mathbf{x})} \right)^{D_0/2} \left(\frac{\mathcal{V}^{\text{tr}}(\mathbf{x})}{\mathcal{V}(\mathbf{x})} \right)^{\omega_0} \right| \leq C_2(\lambda) \quad \text{for all } \mathbf{x} \in \mathbb{P}_+^E$$

where the denominators are the deformed polynomials.

Expanding in ϵ :

Assuming that the only potential divergence comes from $\Gamma(\omega)$ we have:

$$\mathcal{I} = \Gamma(\omega_0 + \epsilon L) \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \int_{\mathbb{P}_+^E} \left(\prod_{e \in E} \frac{\chi_e^{\nu_e}}{\Gamma(\nu_e)} \right) \frac{\det \mathcal{J}_\lambda(\mathbf{x})}{\mathcal{U}(\mathbf{x})^{D_0/2} \cdot \mathcal{V}(\mathbf{x})^{\omega_0}} \log^k \left(\frac{\mathcal{U}(\mathbf{x})}{\mathcal{V}(\mathbf{x})^L} \right) \Omega$$

where $\omega_0 = \sum_{e \in E} \nu_e - D_0 L / 2$.

Expanding in ϵ :

Assuming that the only potential divergence comes from $\Gamma(\omega)$ we have:

$$\mathcal{I} = \Gamma(\omega_0 + \epsilon L) \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \int_{\mathbb{P}_+^E} \left(\prod_{e \in E} \frac{\chi_e^{\nu_e}}{\Gamma(\nu_e)} \right) \frac{\det \mathcal{J}_\lambda(\mathbf{x})}{\mathcal{U}(\mathbf{x})^{D_0/2} \cdot \mathcal{V}(\mathbf{x})^{\omega_0}} \log^k \left(\frac{\mathcal{U}(\mathbf{x})}{\mathcal{V}(\mathbf{x})^L} \right) \Omega$$

where $\omega_0 = \sum_{e \in E} \nu_e - D_0 L / 2$.

Writing the integral with these fractions in the integrand:

$$\mathcal{I} = \frac{\Gamma(\omega_0 + \epsilon L)}{\prod_{e \in E} \Gamma(\nu_e)} \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \mathcal{I}_k$$

with

$$\mathcal{I}_k = \int_{\mathbb{P}_+^E} \frac{(\prod_{e \in E} (\chi_e / x_e)^{\nu_e}) \det \mathcal{J}_\lambda(\mathbf{x})}{(\mathcal{U}(\mathbf{x}) / \mathcal{U}^{\text{tr}}(\mathbf{x}))^{D_0/2} \cdot (\mathcal{V}(\mathbf{x}) / \mathcal{V}^{\text{tr}}(\mathbf{x}))^{\omega_0}} \log^k \left(\frac{\mathcal{U}(\mathbf{x})}{\mathcal{V}(\mathbf{x})^L} \right) \mu^{\text{tr}}$$

and

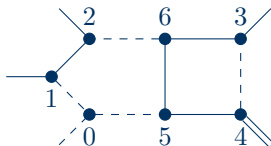
$$\mu^{\text{tr}} = \frac{1}{\int_{\mathbb{P}_+^E} \frac{\prod_{e \in E} \chi_e^{\nu_e}}{\mathcal{U}^{\text{tr}}(\mathbf{x})^{D_0/2} \mathcal{V}^{\text{tr}}(\mathbf{x})^{\omega_0}} \Omega}, \quad \int_{\mathbb{P}_+^E} \mu^{\text{tr}} = 1.$$

The program feyntrop

Available at <https://github.com/michibo/feyntrop>

A C++ program with Python interface:

Example:



Dashed lines: massless, the solid lines: mass m and double $p_4^2 \neq 0$.

edges = [((0,1), 1, '0'), ((1,2), 1, 'mm'), ((2,6), 1, '0'),
((6,3), 1, 'mm'), ((3,4), 1, '0'), ((4,5), 1, 'mm'),
((5,0), 1, '0'), ((5,6), 1, 'mm')]

Phase space point

$$p_0^2 = 0, \quad p_1^2 = p_2^2 = p_3^2 = m^2 = 1/2, \quad s_{01} = 2.2, \quad s_{02} = 2.3, \\ s_{03} = 2.4, \quad s_{12} = 2.5, \quad s_{13} = 2.6, \quad s_{23} = 2.7,$$

where $s_{ij} = (p_i + p_j)^2$. With $\lambda = 0.28$, $N = 10^8$, we obtain:

Prefactor: $\gamma(2\epsilon + 2)$.

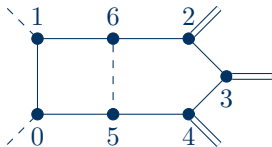
(Effective) kinematic regime: Minkowski (exceptional).

Finished in 8.20 seconds.

```
-- eps^0: [0.06480 +/- 0.00078] + i * [-0.08150 +/- 0.00098]
-- eps^1: [0.4036 +/- 0.0045 ] + i * [ 0.3257 +/- 0.0035 ]
-- eps^2: [-0.7889 +/- 0.0060 ] + i * [ 0.957 +/- 0.016 ]
-- eps^3: [-1.373 +/- 0.030 ] + i * [ -1.181 +/- 0.034 ]
-- eps^4: [ 1.258 +/- 0.088 ] + i * [ -1.205 +/- 0.036 ]
```

This is a **two-loop** integral with different mass scales that you can integrate on your **laptop** in **8 seconds**.

Example:



```
edges = [((0,1), 1, 'mm_top'), ((1,6), 1, 'mm_top'),  
         ((5,6), 1, '0'), ((6,2), 1, 'mm_top'),  
         ((2,3), 1, 'mm_top'), ((3,4), 1, 'mm_top'),  
         ((4,5), 1, 'mm_top'), ((5,0), 1, 'mm_top')]
```

With $s_{ij} := (p_i + p_j)^2$, we have the following kinematic setup:

$$p_0^2 = p_1^2 = 0, \quad p_2^2 = p_3^2 = p_4^2 = m_H^2,$$
$$s_{01} = 5m_H^2 - s_{02} - s_{03} - s_{12} - s_{13} - s_{23}.$$

Phase space point:

$$m_t^2 = 1.8995, \quad m_H^2 = 1,$$
$$s_{02} = -4.4, \quad s_{03} = -0.5, \quad s_{12} = -0.6, \quad s_{13} = -0.7, \quad s_{23} = 1.8,$$

Setting $\lambda = 0.64$ and $N = 10^8$, we get:

Prefactor: $\text{gamma}(2*\text{eps} + 4)$.

(Effective) kinematic regime: Minkowski (generic).

Finished in 8.12 seconds.

```
-- eps^0: [-0.0114757 +/- 0.0000082]
          + i * [0.0035991 +/- 0.0000068]
-- eps^1: [ 0.003250 +/- 0.000031 ]
          + i * [-0.035808 +/- 0.000041 ]
-- eps^2: [ 0.046575 +/- 0.000098 ]
          + i * [0.016143 +/- 0.000088 ]
-- eps^3: [ -0.01637 +/- 0.00017 ]
          + i * [ 0.03969 +/- 0.00016 ]
-- eps^4: [ -0.02831 +/- 0.00023 ]
          + i * [-0.00823 +/- 0.00024 ]
```

- feynthrop 8.12 seconds with relative error $\sim 10^{-3}$
- pySecDec 3 hours with relative error $\sim 10^{-2}$

Thank you!