

Holographic confining theories on space-times with constant positive curvature

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Introduction

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- At low energies, they do not propagate as free particles
- They are always found confined inside stable baryons (three quarks)
- This phenomenon is known as confinement
- Made possible by the fact that quantum chromodynamics (QCD) is strongly coupled at low energies

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- Heating up a gas of baryons will break them apart
- Thermal phase transition from a confined baryon gas to a deconfined quark-gluon plasma

Quantum deconfinement transition

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- High energies can be reached by putting the baryon gas in a small box
- Deconfinement transition as the volume of the box is decreased

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- We focus on strongly-coupled large- N QFTs and use holographic duality
- No quarks $\Rightarrow$ confinement in the form of glueball bound states (only gluons)

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- The theory is described by a single dimensionless curvature parameter

$$\mathcal{R} \equiv \frac{d(d-1)}{\alpha^2} \lambda^{-2/(d-\Delta)}. \quad (2)$$

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[Ghosh–Kiritsis–Nitti–Witkowski '17 and '18]

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[Ghosh–Kiritsis–Nitti–Witkowski '17 and '18]
- A lot of work on QFTs on curved manifolds in recent years
[Ghosh, Kiritsis, Nitti, Witkowski, Jokela, Nourry, Préau, Litos, Raymond, Ghodsi, Mashayekhi, Aharony, Urbach, Weiss, Marolf, Rangamani, Van Raamsdonk, Blackman, MacDermott, Karch, O'Bannon, Klebanov, Pufu, Jafferis, Safdi, Freedman, JK, ...]

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- The theory is said to exhibit confinement in flat space if the Wilson loop has an area law
- The Wilson loop cannot be applied as a criterion on the compact sphere directly

1. The holographic model
2. Classification of gravity solutions
3. The phase diagram

1. The holographic model

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- The scalar field is dual to the relevant scalar operator $\mathcal{O}$ of dimension $\frac{d}{2} < \Delta < d$
- Look for backreacted domain-wall solutions with spherical S^d -slices

$$ds_{d+1}^2 = du^2 + e^{2A(u)} \alpha^2 ds_{S^d}^2, \quad \varphi = \varphi(u), \quad (4)$$

where u is a holographic radial coordinate

Choice of UV behavior of the potential

- Scalar potential is chosen to have a maximum at $\varphi = 0$

$$V(\varphi) = 2\Lambda - \frac{\Delta(d-\Delta)}{2\ell^2} \varphi^2 + \mathcal{O}(\varphi^3), \quad \varphi \rightarrow 0, \quad (5)$$

where $\Lambda = -\frac{d(d-1)}{2\ell^2} < 0$

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- The maximum is reached at $u \rightarrow -\infty$ where

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- Asymptotically locally EAdS $_{d+1}$ metric with S_α^d conformal boundary

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- Produces a soft-wall at $u = u_0$ where the slices shrink to zero size $e^{2A(u_0)} = 0$ and space ends

Why exponential asymptotics?

- The dual theory on a flat space $\mathbb{R}^d$ exhibits confinement when

$$b_c < b < \sqrt{d} b_c, \quad b_c \equiv \frac{1}{\sqrt{2(d-1)}} \quad (9)$$

[Gursoy–Kiritsis–Nitti '07, Kiritsis–Nitti–Pimenta '16]

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- Specifically, for domain wall solutions with flat $\mathbb{R}^d$ -slices

$$ds_{d+1}^2 = dr^2 + e^{2A(r)} \alpha^2 ds_{\mathbb{R}^d}^2, \quad \varphi = \varphi(r), \quad (10)$$

the holographic Wilson loop exhibits an area law in this case

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- Dimensional reduction of $d + N + 1$ -dimensional Einstein action on the S^N gives a potential

$$b = \sqrt{\frac{d + N - 1}{2N(d - 1)}} \quad (11)$$

[Goutéraux–Kiritsis '11, Goutéraux–Smolic–Smolic–Skenderis–Taylor '11]

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- The scalar potential has an uplift only when b is below the Gubser bound $\sqrt{d} b_c$

[Gubser '00]

2. Classification of gravity solutions

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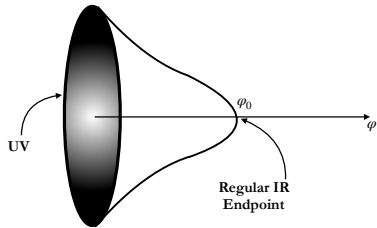
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- For type I and II, the scalar field diverges logarithmically $\varphi(u) \rightarrow \infty$ as $u \rightarrow u_0$

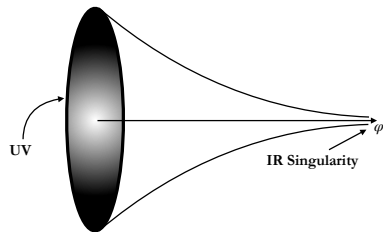
[JK–Kiritsis–Nitti '25]

Geometry	$\varphi(u_0)$
type III	finite
type II	∞
type I	∞

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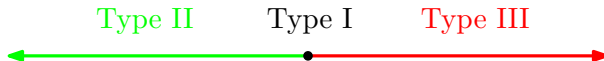
Type III



Type I-II

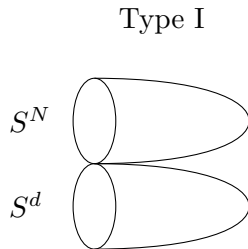
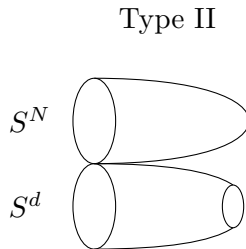
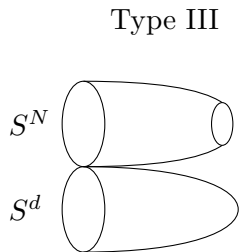
The space of solutions

Geometry	$\varphi(u_0)$	Integration constant
type III	finite	yes
type II	∞	yes
type I	∞	no, unique



Uplift to pure Einstein gravity

- The solutions uplift to $S^d \times S^N$ domain wall metrics in $d + N + 1$ dimensions



3. The phase diagram

The free energy

- Quantity of interest is the renormalized Euclidean path integral

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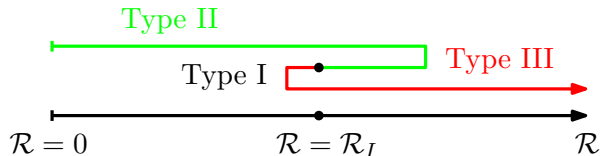
- For fixed $\mathcal{R}$, the solution with the smallest on-shell action gives $F(\mathcal{R})$

Holographic deconfinement transition

- The integration constant of the solution is fixed in terms of $\mathcal{R}$

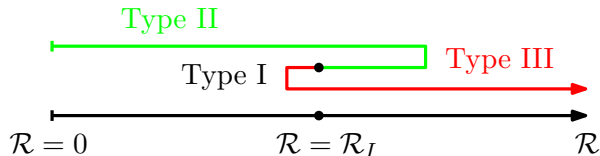
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Holographic deconfinement transition

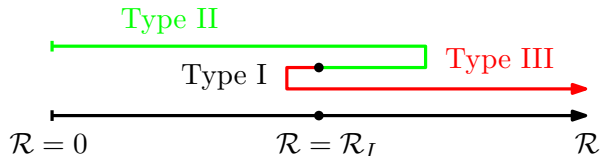
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- Thus there must be a transition from II to III solutions in the vicinity of $\mathcal{R} = \mathcal{R}_I$
- This is the holographic deconfinement transition as $\mathcal{R}$ increases

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- Type III solution corresponds to the deconfined phase
- This is also reflected in the spectrum of fluctuations (spectrum of glueball bound states)

[[Ghodsí–Kiritsis–Mashayekhi–Nitti '25](#)]

The order of the transition

$$V(\varphi) \sim V_\infty e^{2b\varphi}, \quad \varphi \rightarrow \infty \quad (15)$$

- There is a special value b_E (the Efimov bound) for the exponent b defined by

$$b_E \equiv \frac{2}{\sqrt{(d-1)(9-d)}}, \quad b_c < b_E \quad (16)$$

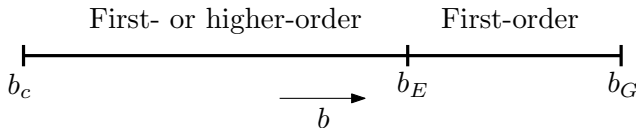
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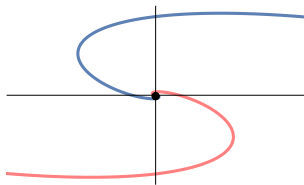
- It controls the order of the deconfinement transition



[JK–Kiritsis–Nitti '25]

The order of the transition

$$\langle \mathcal{O} \rangle = \langle \mathcal{O} \rangle(\mathcal{R})$$

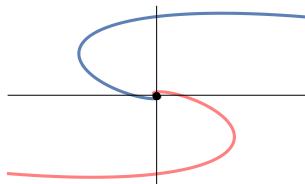


$b > b_E$ Efimov spiral

- First-order transition

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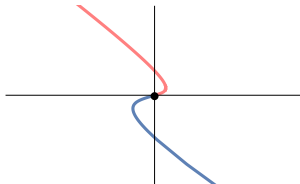
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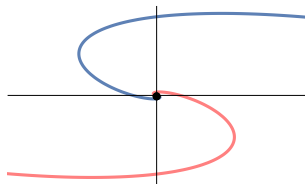


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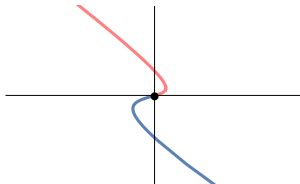
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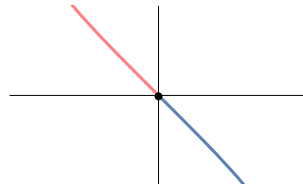
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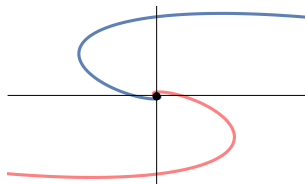


$b < b_E$ 2nd possibility

- Second- or higher-order

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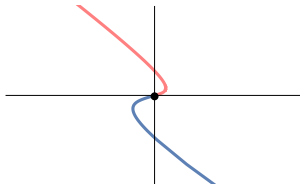
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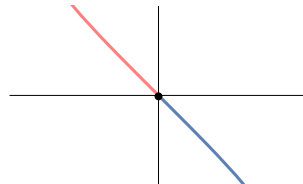
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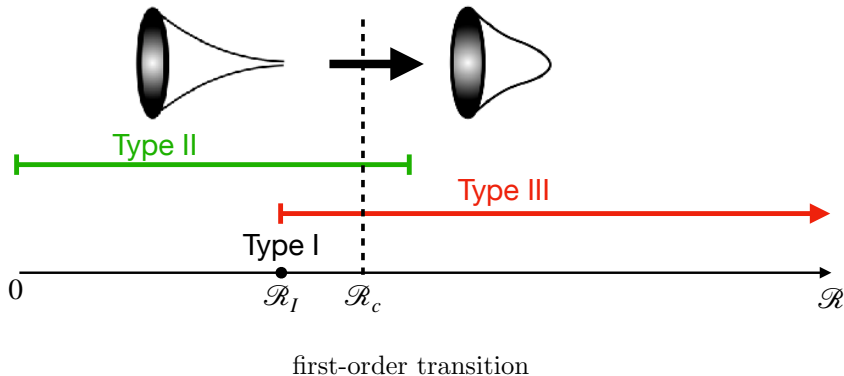
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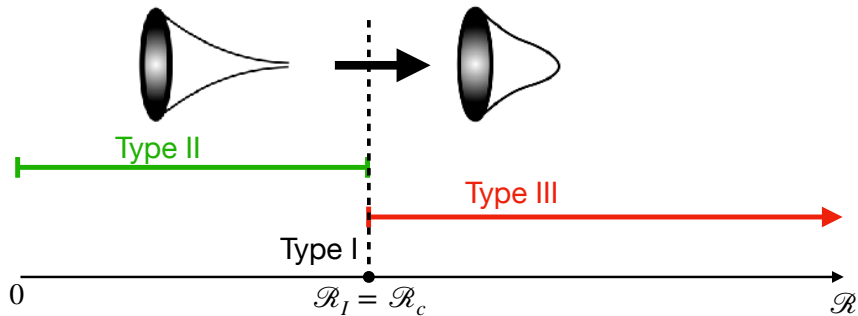
$b < b_E$ 2nd possibility

- Second- or higher-order
- Not infinite-order

Holographic deconfinement transition



Holographic deconfinement transition



second- or higher-order transition

Concrete numerical example

Choice of the potential for numerics

- For numerics, we consider the potential (for $0 < \varphi < \infty$)

$$V(\varphi) = -\frac{d(d-1)}{\ell^2} - \left(\frac{\Delta(\Delta-d)}{2\ell^2} + 4V_\infty b^2 \right) \varphi^2 + 4V_\infty \sinh^2(b\varphi). \quad (17)$$

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- Solve equations of motion numerically

Choice of the potential for numerics

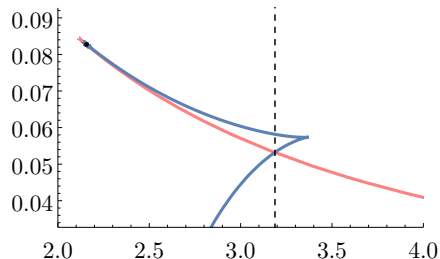
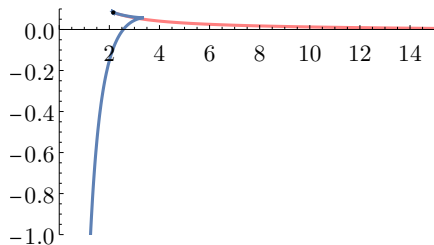
- For numerics, we consider the potential (for $0 < \varphi < \infty$)

$$V(\varphi) = -\frac{d(d-1)}{\ell^2} - \left(\frac{\Delta(\Delta-d)}{2\ell^2} + 4V_\infty b^2 \right) \varphi^2 + 4V_\infty \sinh^2(b\varphi). \quad (17)$$

- Solve equations of motion numerically
- Compute on-shell actions and the free energy numerically (for $d = 4$)

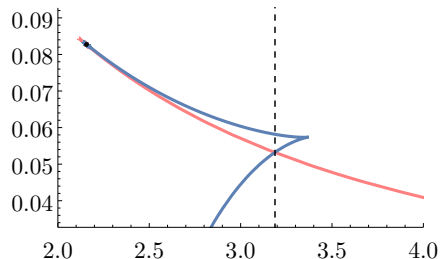
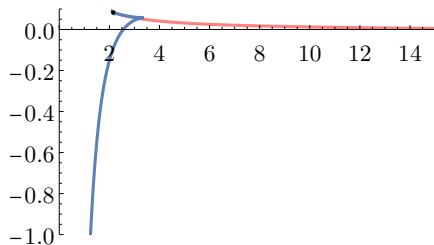
[JK–Kiritsis–Nitti '25]

Free energy above the Efimov bound



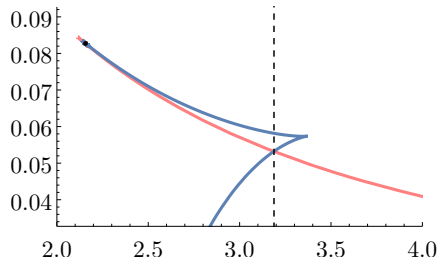
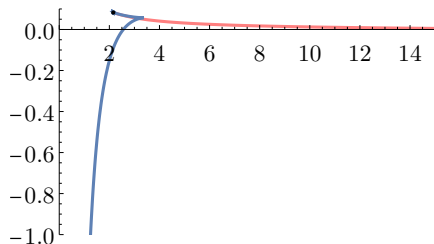
- Free energy $F = F(\mathcal{R})$ above the Efimov bound $b_E < b < b_G$

Free energy above the Efimov bound



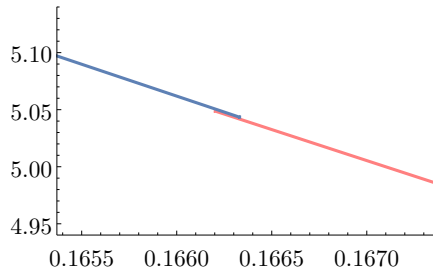
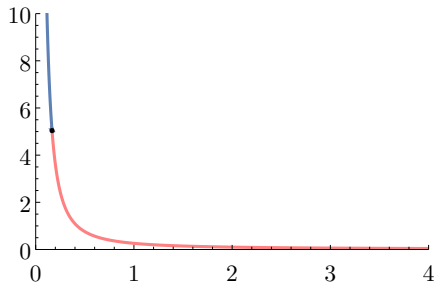
- Free energy $F = F(\mathcal{R})$ above the Efimov bound $b_E < b < b_G$
- First-order transition

Free energy above the Efimov bound



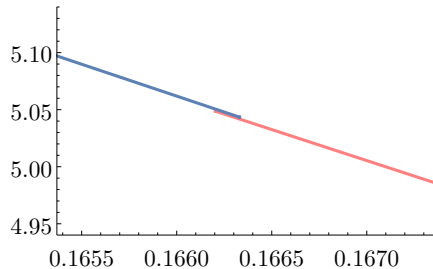
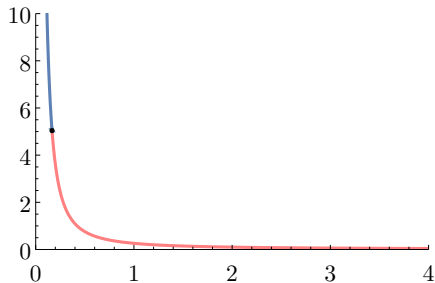
- Free energy $F = F(\mathcal{R})$ above the Efimov bound $b_E < b < b_G$
- First-order transition
- Type I solution is thermodynamically unstable

Free energy below the Efimov bound



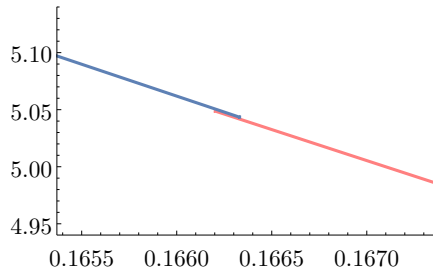
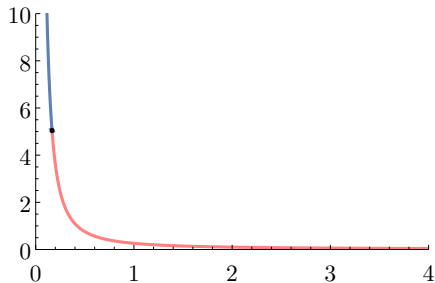
- Free energy $F = F(\mathcal{R})$ below the Efimov bound $b_c < b < b_E$

Free energy below the Efimov bound



- Free energy $F = F(\mathcal{R})$ below the Efimov bound $b_c < b < b_E$
- Second-order transition according to the numerics

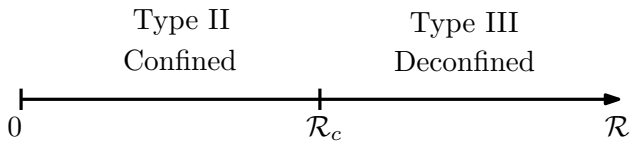
Free energy below the Efimov bound



- Free energy $F = F(\mathcal{R})$ below the Efimov bound $b_c < b < b_E$
- Second-order transition according to the numerics
- Transition through the type I solution

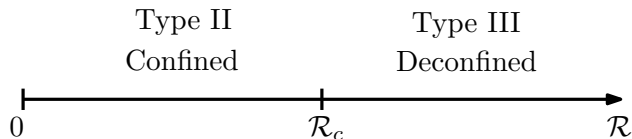
Conclusions

- We demonstrated that a (holographic) deconfinement transition can be induced by curvature

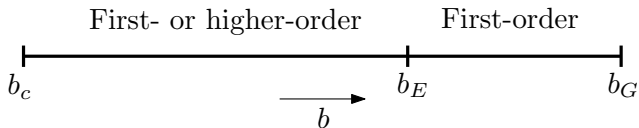


Conclusions

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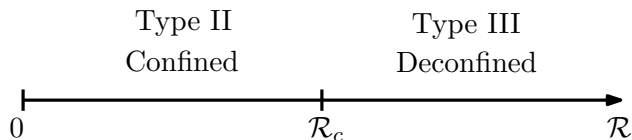


- The order of the transition depends on the exponent b of the potential $V \sim e^{2b\varphi}$

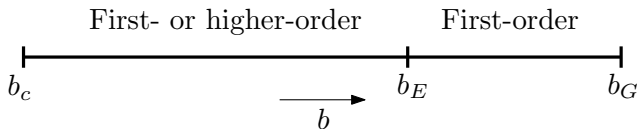


Conclusions

- We demonstrated that a (holographic) deconfinement transition can be induced by curvature



- The order of the transition depends on the exponent b of the potential $V \sim e^{2b\varphi}$



Thank you

Confinement-deconfinement transition

- Without quarks in $N = 3$ QCD, the transition is first-order
- With one massive quark (real world), the transition is a crossover

- $d = 4$:

$$b_c \approx 0.408, \quad b_E \approx 0.516, \quad b_G \approx 0.816 \quad (18)$$

- $\alpha = \ell = 1$, $V_\infty = -1$ and $\Delta = 5/2$ (larger than $d/2 = 2$ and smaller than $d = 4$)
- We considered $b = 0.47$ and $b = 0.65$

Gubser bound

- Type II solution only exists below the Gubser bound
- For flat slices, there are no regular solutions when $b > b_G$ (since no type II)
- No solution reaching $\varphi = \infty$ exists when $b > b_G$, but it bounces back
- Certain IR boundary terms in the on-shell action vanish below the Gubser bound

- It gives

$$\mathcal{C} \equiv \frac{\Delta_-}{d} \langle \mathcal{O} \rangle |\varphi_-|^{-\Delta_+/\Delta_-} . \quad (19)$$

- It is given by the derivative of the free energy

$$F'(\mathcal{R}) = \mathcal{N} \left(\frac{2\mathcal{C}(\mathcal{R})}{\mathcal{R}^3} - \frac{1}{96} \frac{1}{\mathcal{R}} \right) , \quad (20)$$

Below the confinement bound

- Exponents $b < b_c$ obtained by dimensional reduction on a torus