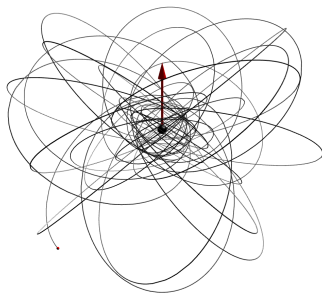


# Demystifying the bound to boundary correspondence with Kerr geodesics

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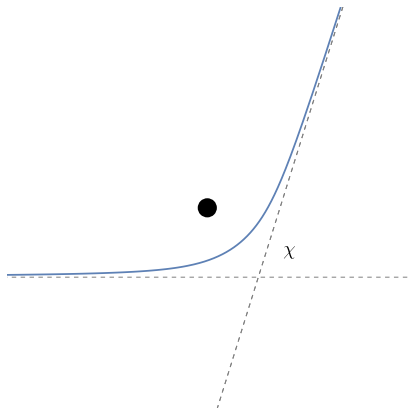


From Amplitudes to Gravitational Waves, Nordita, 24 July 2023



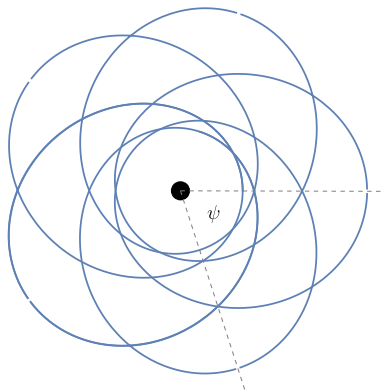
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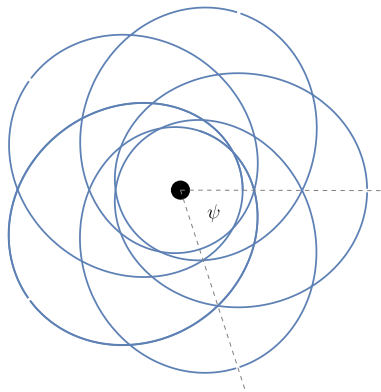
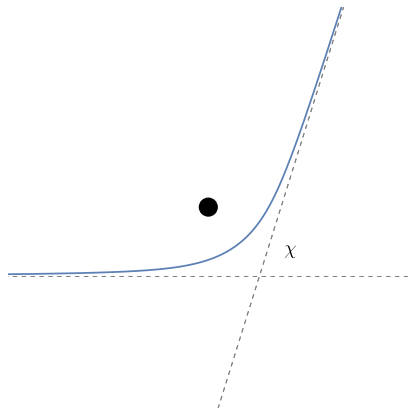
## Amplitude techniques

- Natural setting: scattering



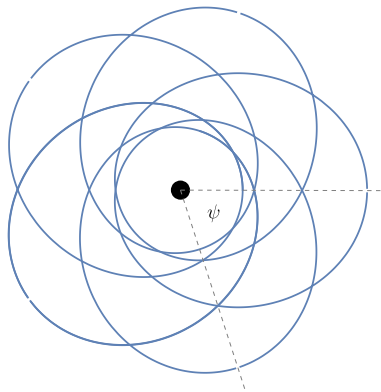
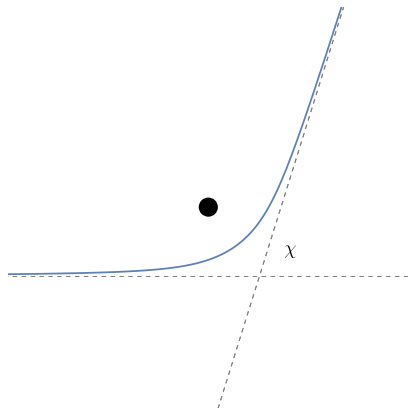
## Gravitational wave observations

- Need: Bound inspirals



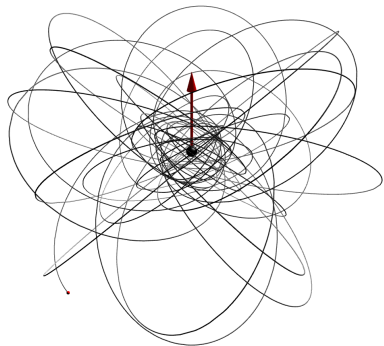
Scattering angle and Periapsis precession are related...

$$\psi(E, L) = \chi(E, L) + \chi(E, -L)$$



Scattering angle and Periapsis precession are related...

$$\psi(E, L, a) = \chi(E, L, a) + \chi(E, -L, -a)$$



## Geodesic Equation

$$\frac{d^2 x^\mu}{d\tau^2} + \Gamma_{\alpha\beta}^\mu \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = 0$$

## Why look at geodesics?

- All orders in  $G$ ,  $\frac{1}{c}$ ,  $M$ , and  $a$
- "0th order" in secondary mass  $m$  and secondary spin  $s$ .
- Integrable system with explicit solutions available.

## Goals

- Improve intuitive understand of B2B map
- Generalizations/alternative formulations

## Norm 4-velocity

$$-1 = \frac{dx^\mu}{d\tau} g_{\mu\nu} \frac{dx^\nu}{d\tau}$$

## Symmetries

$$\mathcal{E} := -\frac{dx^\mu}{d\tau} g_{\mu\nu} \left(\frac{\partial}{\partial t}\right)^\nu \quad \text{energy}$$

$$\mathcal{L} := \frac{dx^\mu}{d\tau} g_{\mu\nu} \left(\frac{\partial}{\partial \phi}\right)^\nu \quad \text{angular momentum}$$

## Hidden symmetry and Carter constant

$$Q := \frac{dx^\mu}{d\tau} \mathcal{K}_{\mu\nu} \frac{dx^\nu}{d\tau}$$

First order form of geodesic equation:

$$\begin{aligned} \Sigma^2 \left(\frac{du}{d\tau}\right)^2 &= (\mathcal{E} - a(\mathcal{L} - a\mathcal{E})u^2)^2 \\ &\quad - (1 - 2GMu + a^2u^2) \left(1 + (Q + (\mathcal{L} - a\mathcal{E})^2)u^2\right) \\ &= -a^2Q(u - u_1)(u - u_2)(u - u_3)(u - u_4) =: U(u) \end{aligned}$$

$$\begin{aligned} \Sigma^2 \left(\frac{dz}{d\tau}\right)^2 &= Q - z^2 \left(a^2(1 - \mathcal{E}^2)(1 - z^2) + \mathcal{L}^2 + Q\right) \\ &= a^2(1 - \mathcal{E}^2)(z^2 - z_1^2)(z^2 - z_2^2) =: Z(z) \end{aligned}$$

$$\Sigma \frac{d\phi}{d\tau} = a \frac{\mathcal{E} - a(\mathcal{L} - a\mathcal{E})u^2}{1 - 2GMu + a^2u^2} + \frac{\mathcal{L}}{1 - z^2} - a\mathcal{E},$$

$$\Sigma \frac{dt}{d\tau} = \frac{(1 + a^2u^2)(\mathcal{E} - a(\mathcal{L} - a\mathcal{E})u^2)}{(1 - 2GMu + a^2u^2)u^2} - a^2\mathcal{E}(1 - z^2) + a\mathcal{L},$$

with

$$u := 1/r \qquad z := \cos \theta$$

$$\Sigma := r^2 + a^2 \cos^2 \theta$$

## New (non-affine) parameter

$$d\lambda = \frac{1}{\Sigma} d\tau$$

## Crucial bonus feature

Geodesics reach infinity in finite Mino time:

$$\frac{d\lambda}{du} = \pm \frac{1}{\sqrt{U(u)}} = \frac{1}{\sqrt{\mathcal{E}^2 - 1}} + \mathcal{O}(u)$$

Decoupled equations:

$$\left(\frac{du}{d\lambda}\right)^2 = -a^2 Q(u - u_1)(u - u_2)(u - u_3)(u - u_4) = U(u)$$

$$\left(\frac{dz}{d\lambda}\right)^2 = a^2(1 - \mathcal{E}^2)(z^2 - z_1^2)(z^2 - z_2^2) = Z(z)$$

$$\frac{d\phi}{d\lambda} = a \frac{\mathcal{E} - a(\mathcal{L} - a\mathcal{E})u^2}{1 - 2GMu + a^2u^2} + \frac{\mathcal{L}}{1 - z^2} - a\mathcal{E},$$

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## Radial Solution

$$u = \frac{(u_2 - u_1)u_3 \operatorname{sn}^2(Aq_r|k_r) - u_2(u_3 - u_1)}{(u_2 - u_1) \operatorname{sn}^2(Aq_r|k_r) - (u_3 - u_1)}$$

with

$$q_r = \Upsilon_r \lambda + q_{r,0}$$

## Polar Solution

$$z = z_1 \operatorname{sn}(Bq_z|k_z)$$

with

$$q_z = \Upsilon_z \lambda + q_{z,0}$$

## Definitions:

- $A, B, k_r, k_z, \Upsilon_r, \Upsilon_z, \Upsilon_\phi, \Upsilon_t$  Functions of  $a, GM, \mathcal{E}, \mathcal{L}$ , and  $Q$
- $K(\cdot), E(\cdot), \Pi(\cdot|\cdot)$ : Complete elliptic functions
- $F(\cdot|\cdot), E(\cdot|\cdot), \Pi(\cdot; \cdot|\cdot)$ : Incomplete elliptic functions
- $\operatorname{sn}(\cdot|\cdot), \operatorname{am}(\cdot|\cdot)$  Jacobi elliptic sine and amplitude

## Azimuthal solution

$\phi(q_\phi, q_r, q_z) = q_\phi + \phi_r(q_r) + \phi_z(q_z)$  with  $q_\phi = \Upsilon_\phi \lambda + q_{\phi,0}$ , and

$$\phi_r(q_r) := \tilde{\phi}_r \left( \operatorname{am} \left( K(k_r) \frac{q_r}{\pi} \mid k_r \right) \right) - \frac{\tilde{\phi}_r(\pi)}{2\pi} q_r,$$

$$\tilde{\phi}_r(\xi_r) := \frac{\mathcal{L}u_+(u_3 - u_2)(u_+ - \frac{2GM\mathcal{E}}{a\mathcal{L}})\Pi(h_+; \xi_r|k_r)}{A(u_+ - u_2)(u_+ - u_3)(u_- - u_+)} + (+ \leftrightarrow -),$$

$$\phi_z(q_z) := \tilde{\phi}_z \left( \operatorname{am} \left( K(k_z) \frac{2q_z}{\pi} \mid k_z \right) \right) - \frac{\tilde{\phi}_z(\pi)}{\pi} q_z, \quad \tilde{\phi}_z(\xi_z) := -\frac{\mathcal{L}}{z_2} \Pi(z_1^2; \xi_z|k_z).$$

## Time solution

$t(q_t, q_r, q_z) = q_t + \phi_r(q_r) + \phi_z(q_z)$  with  $q_t = \Upsilon_t \lambda + q_{t,0}$ , and

$$t_r(q_r) := \tilde{t}_r \left( \operatorname{am} \left( K(k_r) \frac{q_r}{\pi} \mid k_r \right) \right) - \frac{\tilde{t}_r(\pi)}{2\pi} q_r,$$

$$\tilde{t}_r(\xi_r) := \mathcal{E} \left( \frac{u_3 - u_2}{A} \left( \frac{2\mathcal{E}^2 - 3}{u_2 u_3 (\mathcal{E}^2 - 1)} \Pi(h_r; \xi_r|k_r) - \frac{2}{a^2} \left\{ \frac{u_+ (4(GM)^2 - a(\mathcal{L}/\mathcal{E} + 2aGMu_+))}{(u_- - u_+)(u_+ - u_2)(u_+ - u_3)} \Pi(h_+; \xi_r|k_r) + (+ \leftrightarrow -) \right\} \right) \right. \\ \left. - \frac{2A}{GM(\mathcal{E}^2 - 1)} \left( E(\xi_r|k_r) - h_r \frac{\sin \xi_r \cos \xi_r \sqrt{1 - k_r \sin^2 \xi_r}}{1 - h_r \sin^2 \xi_r} \right) \right)$$

$$t_z(q_z) := \tilde{t}_z \left( \operatorname{am} \left( K(k_z) \frac{2q_z}{\pi} \mid k_z \right) \right) - \frac{\tilde{t}_z(\pi)}{\pi} q_z, \quad \tilde{t}_z(\xi_z) := -\frac{\mathcal{E}}{1 - \mathcal{E}^2} z_2 E(\xi_z|k_z),$$

## The Kerr background

Mass  $M$  and spin  $a$

## Initial conditions

$x^\mu(0)$  and  $\frac{dx^\mu}{d\tau}(0)$

## Constants of motion

$\mathcal{E}$ ,  $\mathcal{L}$ , and  $Q$  plus initial phases  $q_{r,0}$ ,  $q_{z,0}$ ,  $q_{t,0}$ , and  $q_{\phi,0}$

## Turning points

$u_1$ ,  $u_2$ , and  $z_1$  plus initial phases  $q_{r,0}$ ,  $q_{z,0}$ ,  $q_{t,0}$ , and  $q_{\phi,0}$

$(p, e, x)$

$p := \frac{2}{u_1+u_2}$ ,  $e := \frac{u_2-u_1}{u_1+u_2}$ , and  $x := \text{sign}(\mathcal{L})\sqrt{1-z_1^2}$

## Scattering variables

Impact parameter  $b^\mu$ , and velocity  $v_\infty^\mu$

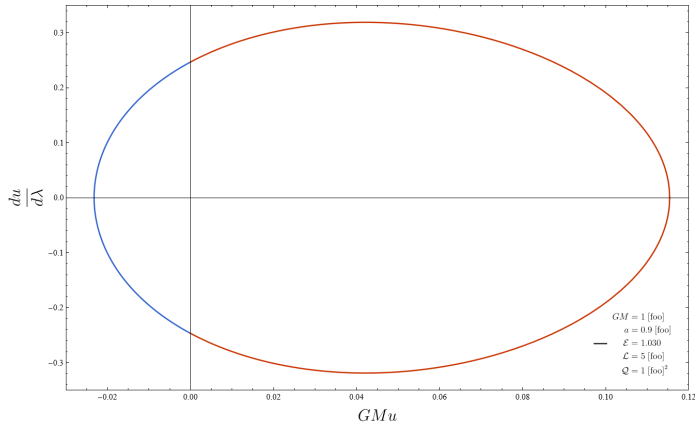
## Notes

- All parameters linked by analytic relationships
- Geodesic solutions are analytic in all parameters
- $q_{t,0}$  and  $q_{\phi,0}$  can be freely fixed using global symmetries
- $q_{r,0}$  can be fixed by letting  $\lambda = 0$  at periapsis
- Relationship between  $(b^\mu, v_\infty^\mu)$  and  $(\mathcal{E}, \mathcal{L}, Q)$  features  $q_{z,0}$ .

- Bound and scatter solutions belong to the same class of geodesic solutions with root structure:

$$u_1 < u_2 < u_3 < u_+ < u_- < u_4$$

- Can analytically deform bound ( $u_1 > 0$ ,  $\mathcal{E} < 1$ ,  $e < 1$ ) to scatter ( $u_1 < 0$ ,  $\mathcal{E} > 1$ ,  $e > 1$ ) solutions.



- Analytical continuation of bound orbit consists of two scattering events
- One event in  $u > 0$  universe
- One event in  $u < 0$  universe
- Need both to reconstruct bound solution!

## Question:

Given knowledge of scattering in  $u > 0$ , can we reconstruct scattering in  $u < 0$ ?

- Solutions are analytic in  $\lambda$
- Given a partial solution on some interval, full solution can be recovered through analytic continuation
- Beware branch cut for  $t$  (and  $\tau$ ) solution

Fix

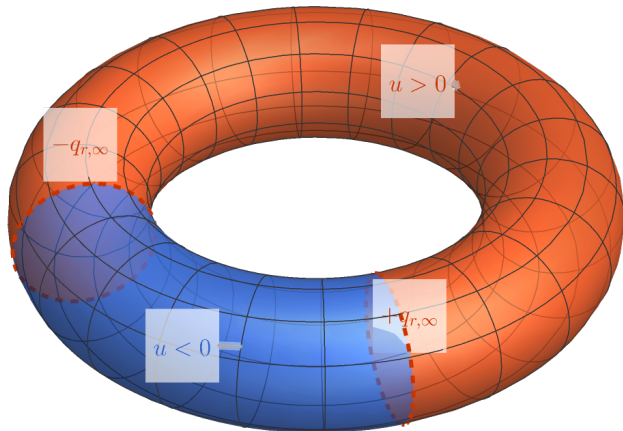
$M, a, \mathcal{E}, \mathcal{L}, Q$

## Option 1b: Analytic continuation on the $(q_r, q_z)$ -torus

- Solution not periodic in  $\lambda$
- Geodesics depends on  $\lambda$  through  $(q_t, q_r, q_z, q_\phi)$
- $(q_t, q_\phi)$  dependence from background symmetry
- Scattering in  $u > 0$  gives solution for  $-q_{r,\infty} < q_r < q_{r,\infty}$  and all  $q_z$
- Full solution by anal. cont. on  $(q_r, q_z)$ -torus

Fix

$M, a, \mathcal{E}, \mathcal{L}, Q$



## Option 2: Exchange of the radial roots

Exchange

$$u_1 \leftrightarrow u_2$$

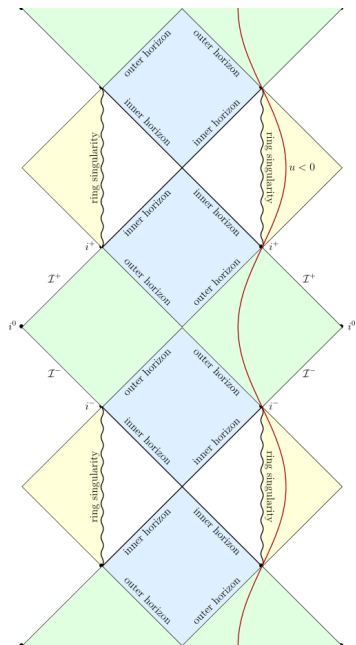
Equivalent

$$e \leftrightarrow -e$$

Fix

$M, a, z_1$

# Option 3: Relating the universe to the anti-universe $GM \rightarrow -GM$



Fix

$a, \mathcal{E}, \mathcal{L}, Q$

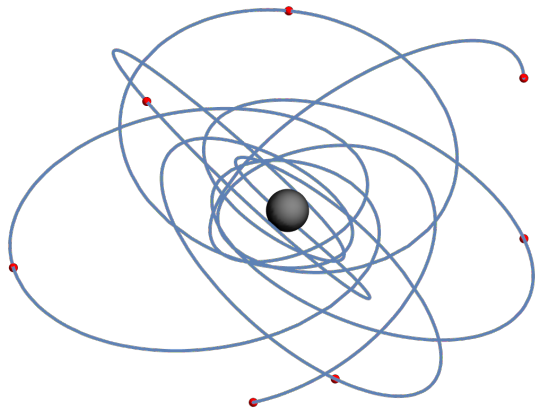


## Option 4: Invert angular momenta ( $1/\mathcal{L} \rightarrow -1/\mathcal{L}$ and $a \rightarrow -a$ )

- As in [Kälin&Porto,2019+] prescription
- Needs  $z_1 \rightarrow -z_1$  for precessing orbits

Fix

$M, \mathcal{E}$



The accumulated azimuthal phase per radial period depends on  $q_z$  at radial turning points. Not coordinate independent!

## Gauge invariant definition

$$\begin{aligned}\psi &:= \Lambda_r \left\langle \frac{d\phi}{d\lambda} \right\rangle \\ &= \Lambda_r \lim_{\Lambda \rightarrow \infty} \frac{1}{2\Lambda} \int_{-\Lambda}^{\Lambda} \frac{d\phi}{d\lambda} d\lambda \\ &= \frac{\Lambda_r}{(2\pi)^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{d\phi}{d\lambda} dq_r dq_z \quad [\text{Drasco\&Hughes, 2003}]\end{aligned}$$

## Scattering angle

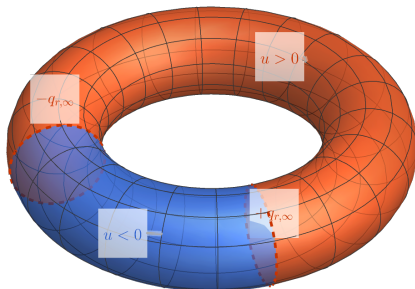
$$\begin{aligned}\chi &= \int_{-\Lambda_\infty}^{\Lambda_\infty} \frac{d\phi}{d\lambda} d\lambda \\ &= \frac{\Lambda_r}{2\pi} \int_{-q_{r,\infty}}^{q_{r,\infty}} \frac{d\phi}{d\lambda} dq_r\end{aligned}$$

Define:

$$\bar{\chi} = \frac{\Lambda_r}{(2\pi)^2} \int_{-q_{r,\infty}}^{q_{r,\infty}} \int_{-\pi}^{\pi} \frac{d\phi}{d\lambda} dq_r dq_z$$

## B2B relationship

$$\begin{aligned}\psi &= \frac{\Lambda_r}{(2\pi)^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{d\phi}{d\lambda} dq_r dq_z \\ &= \frac{\Lambda_r}{(2\pi)^2} \int_{-q_{r,\infty}}^{q_{r,\infty}} \int_{-\pi}^{\pi} \frac{d\phi}{d\lambda} dq_r dq_z + \frac{\Lambda_r}{(2\pi)^2} \int_{q_{r,\infty}}^{2\pi - q_{r,\infty}} \int_{-\pi}^{\pi} \frac{d\phi}{d\lambda} dq_r dq_z \\ &= \bar{\chi}(u > 0) + \bar{\chi}(u < 0)\end{aligned}$$



## Gravitational Self Force (GSF) Formalism

Expansion of relativistic two body dynamics around geodesic solutions

$$\begin{aligned}\frac{d\vec{q}}{d\lambda} &= \vec{\Upsilon}(\vec{P}) + \epsilon \vec{f}_1(\vec{P}, \vec{q}) + \epsilon^2 \vec{f}_2(\vec{P}, \vec{q}) + \mathcal{O}(\epsilon^3) \\ \frac{d\vec{P}}{d\lambda} &= 0 + \epsilon \vec{F}_1(\vec{P}, \vec{q}) + \epsilon^2 \vec{F}_2(\vec{P}, \vec{q}) + \mathcal{O}(\epsilon^3)\end{aligned}$$

- Geodesic results lift to general dynamics
- Possible obstruction:  $\vec{f}_i$  and  $\vec{F}_i$  may not be analytic everywhere (tails?!)

Waveform observed at null infinity at  $t(\lambda) - r_*(\lambda)$ :

$$h(\lambda, \Theta_{\text{obs}}, \Phi_{\text{obs}}) = \frac{1}{D} \sum_{\ell m n k} \mathcal{A}_{\ell m n k}(\vec{P}) e^{-i(nq_r + kq_z + mq_\phi)} {}_{-2}Y_{\ell m}(\Theta_{\text{obs}}, \Phi_{\text{obs}})$$

## 2 distinct relations:

- 1 relating bound and unbound
- 1 relating scattering and anti-scattering

## 4-ways to relate (anti)-scattering

- Analytic continuation of Mino time
- Exchange of radial roots ( $e \leftrightarrow -e$ )
- Inversion of gravitational constant ( $G \rightarrow -G$ )
- Reversal of angular momenta ( $1/\mathcal{L} \rightarrow -1/\mathcal{L}$ ,  $a \rightarrow -a$  and  $z_1 \rightarrow -z_1$ )

