

unimpeded (& other cosmological inference tools)

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19th October 2023



UNIVERSITY OF
CAMBRIDGE



Highlighted tools for this audience

1. `anesthetic` [1905.04768]
 - ▶ how to get the most out of your nested sampling runs
 - ▶ `github.com/handley-lab/anesthetic`
2. `margarine` [2207.11457]
 - ▶ easy-to-use (neural) density estimation for marginal statistics
 - ▶ `github.com/htjb/margarine`
3. `prescience` [2309.06942]
 - ▶ Fully Bayesian forecasts (no more need for Fisher)
 - ▶ `github.com/ThomasGesseyJones/FullyBayesianForecastsExample`
4. `unimpeded`
 - ▶ up/downloading tool for transferring inference products (beyond chains)
 - ▶ `github.com/handley-lab/unimpeded`

Marginal inference

- ▶ Many cosmological likelihoods come with nuisance parameters that have limited relevance for onward inference.

- ▶ Notation: $\mathcal{L} = P(D|\theta, \alpha, M)$

\mathcal{L} Likelihood (e.g. plik),

D Data (e.g. CMB),

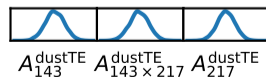
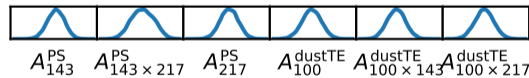
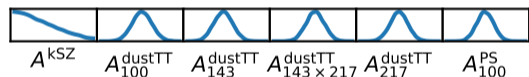
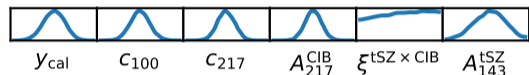
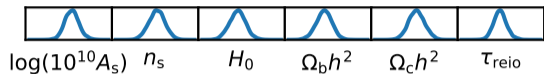
θ Cosmological parameters (e.g. $\Omega_m, H_0 \dots$),

α Nuisance parameters (e.g. $A_{\text{planck}} \dots$),

M Model (e.g. Λ CDM).

- ▶ Some marginal statistics (e.g. marginal means, posteriors...) are easy to compute.

- ▶ More machinery is needed for e.g. nuisance marginalised likelihoods and marginal KL divergences \mathcal{D}_{KL} .



Relevant examples for this audience

1. CMB

- ▶ Galactic foreground parameters: A_i, n_i, \dots
- ▶ Calibration: c, y, \dots

2. Gravitational wave events

- ▶ Nuisance event parameters: $M_1, M_2, \theta, \phi, r, z, \dots$

3. (time-delay) supernovae

- ▶ Nuisance lens parameters: Φ_{lens}
- ▶ Supernova systematics

- ▶ Many modern cosmological problems present themselves in hierarchical form
- ▶ These (often well-studied) objects have a set of event-specific parameters α alongside parameters of global interest θ (e.g. H_0).
- ▶ Ideally we would be able to have a “nuisance marginalised” likelihood for combining hierarchically.

Nuisance marginalised likelihoods: Theory [2207.11457]

- ▶ Bayes theorem

$$\mathcal{L}(\theta, \alpha) \times \pi(\theta, \alpha) = \mathcal{P}(\theta, \alpha) \times \mathcal{Z} \quad (1)$$

Likelihood \times Prior = Posterior \times Evidence

α : nuisance parameters, θ : cosmo parameters.

- ▶ Marginal Bayes theorem

$$\mathcal{L}(\theta) \times \pi(\theta) = \mathcal{P}(\theta) \times \mathcal{Z} \quad (2)$$

- ▶ Non-trivially gives **nuisance-free likelihood**

$$\boxed{\mathcal{L}(\theta) = \frac{\mathcal{P}(\theta)\mathcal{Z}}{\pi(\theta)}} = \frac{\int \mathcal{L}(\theta, \alpha)\pi(\theta, \alpha)d\alpha}{\int \pi(\theta, \alpha)d\alpha} \quad (3)$$

Key properties

- ▶ Given datasets A and B , each with own nuisance parameters α_A and α_B :
- ▶ If you use $\mathcal{L}_A(\theta)$, you get the same (marginal) posterior and evidence if you had run with nuisance parameters α_A (ditto B).
- ▶ If you run inference on $\mathcal{L}_A(\theta) \times \mathcal{L}_B(\theta)$, you get the same (marginal) posterior and evidence if you had run with all nuisance parameters α_A, α_B on.

(weak marginal consistency requirements on joint $\pi(\theta, \alpha_A, \alpha_B)$ and marginal priors)



$$\mathcal{L}(\theta) = \frac{\mathcal{P}(\theta) \mathcal{Z}}{\pi(\theta)}$$

- ▶ To compute the nuisance marginalised likelihood, need:
 1. Bayesian evidence \mathcal{Z}
 2. Marginal prior and posterior densities

$$\mathcal{L}(\theta, \alpha)$$

$$\pi(\theta, \alpha)$$

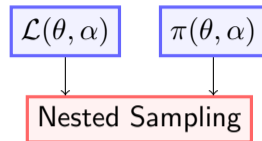
1. Use nested sampling to compute evidence \mathcal{Z} and marginal samples $\{\theta, \alpha\}_{\mathcal{P}}$ and $\{\theta, \alpha\}_{\pi}$.
 2. Use normalising flows to compute density estimators $\mathcal{P}(\theta)$, $\pi(\theta)$ from marginal samples.
- ▶ Emulators usually much faster than original likelihoods
 - ▶ Library of pre-trained bijectors to be used as priors/emulators/nuisance marginalised likelihoods
 - ▶ e.g. easy to apply a *Planck*/DES/HERA/JWST prior or likelihood to your existing MCMC chains without needing to install the whole cosmology machinery.



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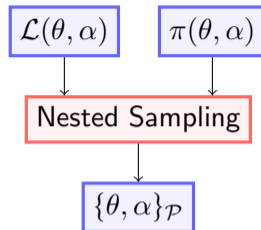




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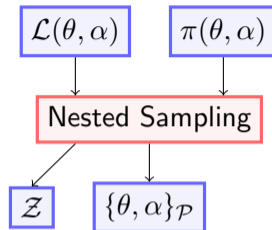




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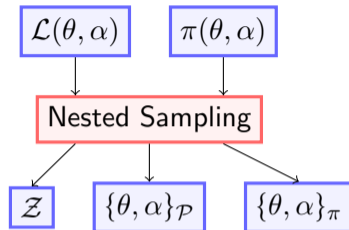




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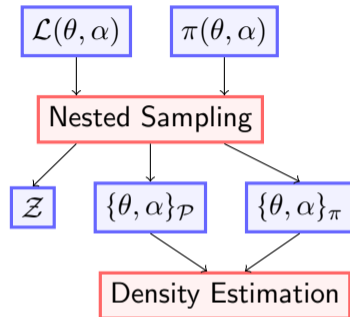




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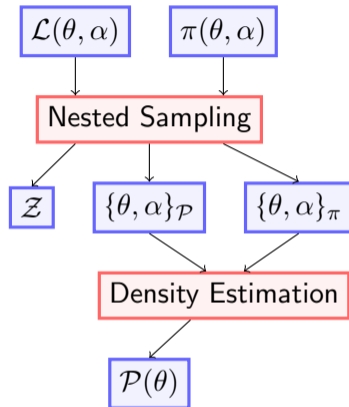




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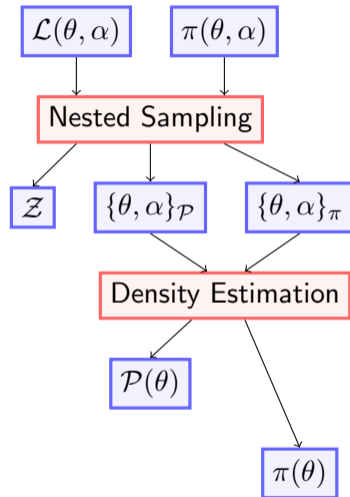




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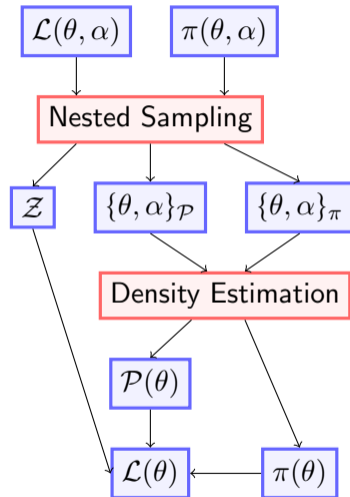




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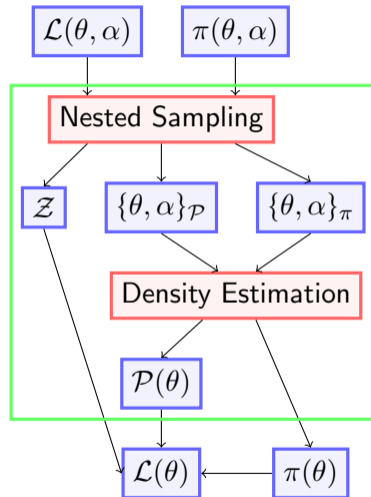




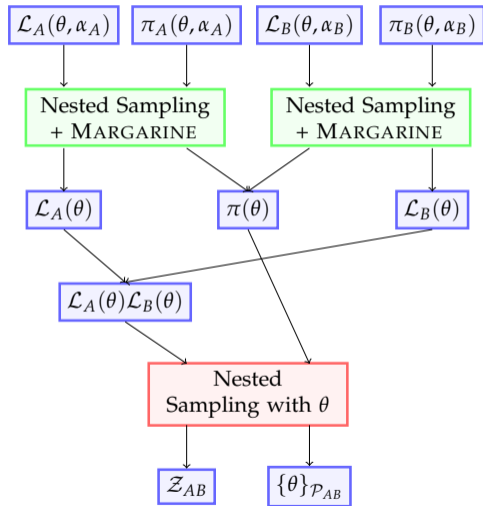
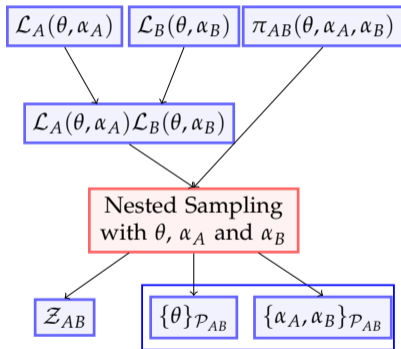
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Combination



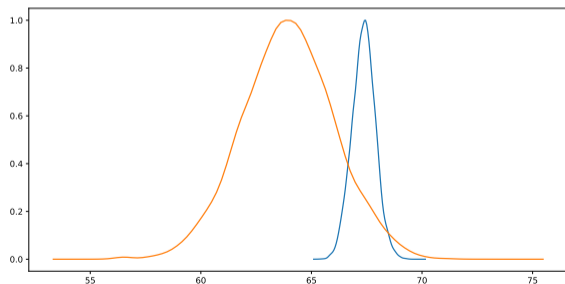
History of margarine

- ▶ Papamakarios et al [1912.02762] (normalising flows)
- ▶ Alsing et al [1903.00007] (Delfi)
- ▶ Nested sampling with any prior you like (Alsing & Handley) [2102.12478]
- ▶ margarine (theory) Bevins et al [2207.11457]
- ▶ margarine (practice) Bevins et al [2205.12841]



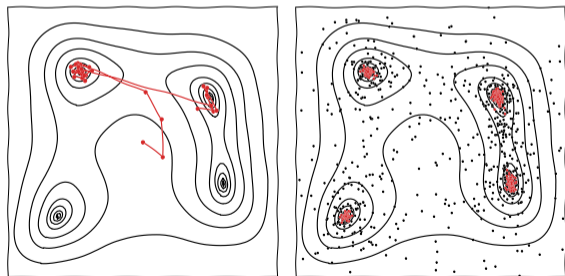
- ▶ Python tool for seamlessly downloading, uploading and cacheing of chains
- ▶ Data stored on zenodo
- ▶ hdf5 storage for fast & reliable storage
- ▶ anesthetic compatible for processing of chains [1905.04768]
- ▶ α -testers wanted! (email wh260@cam.ac.uk)
- ▶ End goal – community library which everyone contributes to so expensive inference products are reusable and reused.

```
from unimpeded import Unimpeded
store = Unimpeded(cache='data.hdf5')
samps = store('planck')
samps.H0.plot.kde_1d()
samps = store('planck', model='klcdm')
samps.H0.plot.kde_1d()
```



- ▶ DiRAC 2020 RAC allocation of 30MCPUh
- ▶ Main goal: Planck Legacy Archive equivalent
- ▶ Parameter estimation → Model comparison
- ▶ MCMC → Nested sampling
- ▶ Planck → {Planck, DESY1, BAO, ...}
- ▶ Pairwise combinations
- ▶ Suite of tools for processing these
 - ▶ anesthetic 2.0
 - ▶ unimpeded 1.0
 - ▶ zenodo archive
 - ▶ margarine
- ▶ MCMC chains also available.
- ▶ Library of bijectors emulators for fast re-use

DiRAC



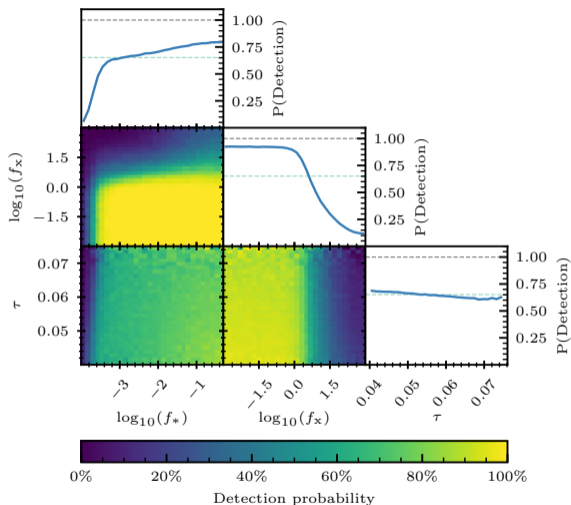


Have you ever done a Fisher forecast, and then felt Bayesian guilt?

- ▶ Cosmologists are interested in forecasting what a Bayesian analysis of future data might produce.
- ▶ Useful for:
 - ▶ white papers/grants,
 - ▶ optimising existing instruments/strategies,
 - ▶ picking theory/observation to explore next.
- ▶ To do this properly:
 1. start from current knowledge $\pi(\theta)$, derived from current data
 2. Pick potential dataset D that might be collected from $P(D)$ ($= \mathcal{Z}$)
 3. Derive posterior $P(\theta|D)$
 4. Summarise science (e.g. constraint on θ , ability to perform model comparison)
- ▶ This procedure should be marginalised over:
 1. All possible parameters θ (consistent with prior knowledge)
 2. All possible data D
- ▶ i.e. marginalised over the joint $P(\theta, D) = P(D|\theta)P(\theta)$.
- ▶ Historically this has proven very challenging.
- ▶ Most analyses assume a fiducial cosmology θ_* , and/or a Gaussian likelihood/posterior (c.f. Fisher forecasting).
- ▶ This runs the risk of biasing forecasts by baking in a given theory/data realisation.



- ▶ Simulation based inference gives us the language to marginalise over parameters θ and possible future data D .
- ▶ Evidence networks [2305.11241] give us the ability to do this at scale for forecasting.
- ▶ Demonstrated in 21cm global experiments, marginalising over:
 - ▶ theoretical uncertainty
 - ▶ foreground uncertainty
 - ▶ systematic uncertainty
- ▶ Able to say “at 67mK radiometer noise”, have a 50% chance of 5σ Bayes factor detection.
- ▶ Can use to optimise instrument design
- ▶ Re-usable package: prescience



Conclusions

github.com/handley-lab



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