Turbulent Magnetic Field Amplification in Binary Neutron Star Mergers

Ricard Aguilera-Miret

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OKC@15, 18th October 2023

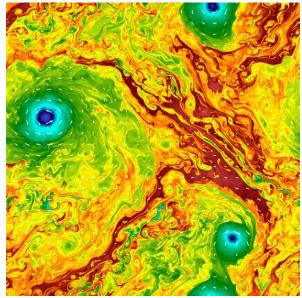
Computational resources: «LESBNS» project (20th PRACE Regular Call) MareNostrum BSC

Long LES BNS project (21th PRACE Regular Call) MareNostrum BSC





3 Institute of Applied Computing & Community Code.

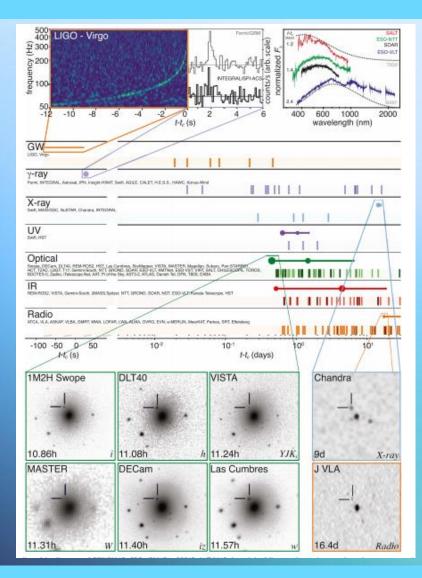


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GW170817: the beginning of the multi-messenger with GW era (first BNS merger detection)

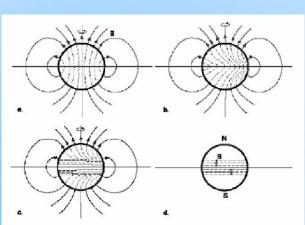
Things that we can learn:

- Internal properties of NSs (eq. state)
- Magnetic field amplification mechanisms
- Test General Relativity (or alternative theories to GR)
- Production of heavy elements
- EM counterpart (short GRB, kilonova)
- Formation of massive NS and/or light BH

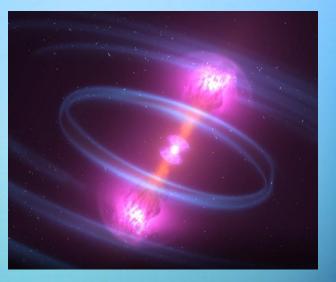
Motivation

- PROCESSES DURING AND AFTER THE MERGER:
 - Kelvin-Helmholtz instability (small scale) ^{*}
 - Winding up (large scale)
 - Magneto-rotational instability (large scale)

Jet appear during the merger \rightarrow Most of current models need a







Simulate these mechanisms via BNS merger simulations

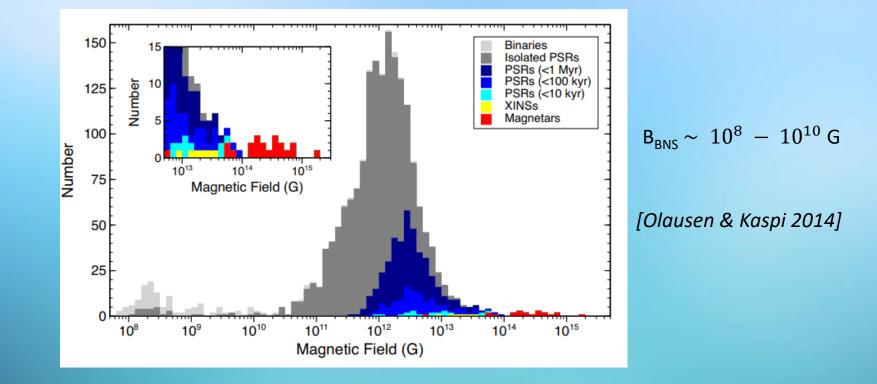
strong large-scale magnetic field

Ricard Aguilera Miret

sGRB

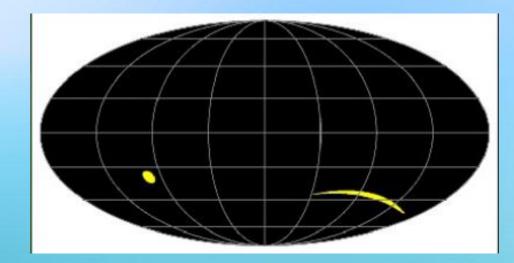
What are the typical magnetic fields expected for merging neutron stars?

Most works for simplicity (and for convenience) start with unrealistic magnetar-like values of purely dipolar fields (**10**¹⁵ **G**), either in the pre-merger or directly in the post-merger stage



What is the typical magnetic field topology of neutron stars?

Most works for simplicity (and for convenience) start with unrealistic magnetar-like values of **purely dipolar** fields (10¹⁵ G), either in the pre-merger or directly in the post-merger stage



NICER results [Riley++ 2019, Bogdanov++ 2019, Miller++ 2019]

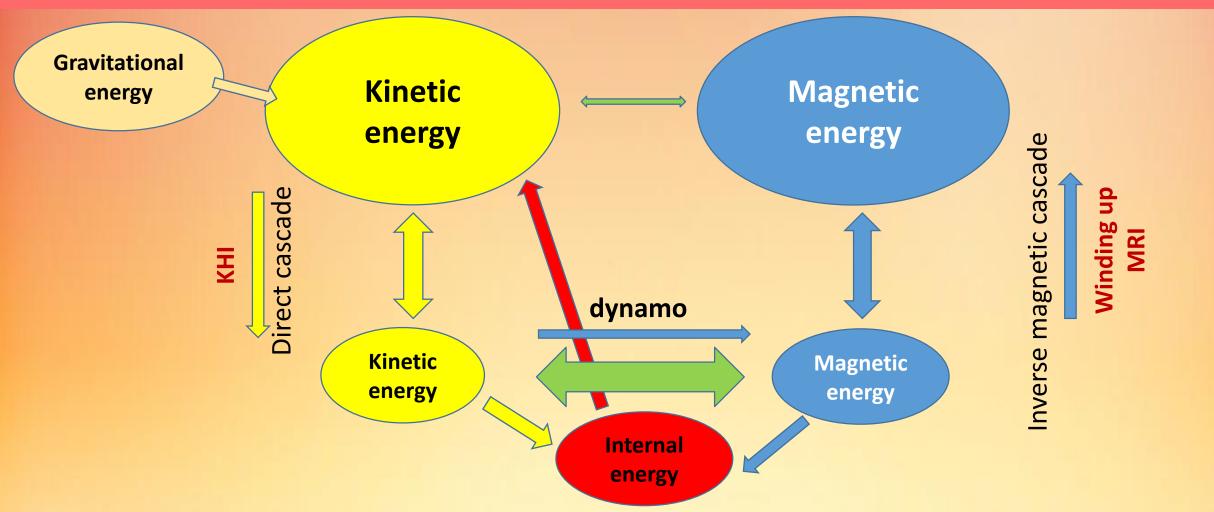
Strong indications of a multipolar structure in NS
 →
 Assuming a strong dipolar magnetic field topology is unsupported by the NICER results.

Does the initial magnetic field strength and topology matter at all in BNS mergers?

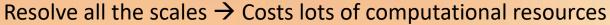
Turbulent Magnetic Field Amplification in Binary Neutron Star Mergers

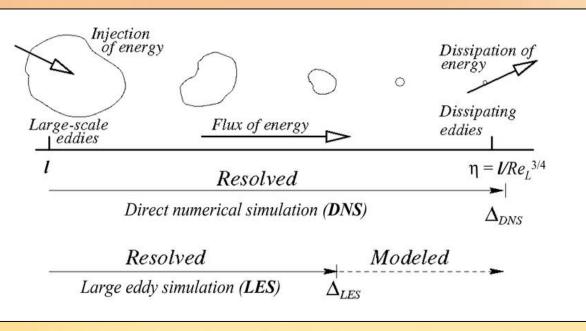
Large Eddy Simulations of BNS mergers

2.1. Filtering



2.1. Filtering





[Foroozani 2015]

The finite resolution of a simulation corresponds to an effective spatial filter for the fields:

2.1. Filtering

Take the simplest non-linear evolution equation, Burgers:

$$\partial_t u + \frac{1}{2} \partial_x u^2 = 0 \implies \partial_t \bar{u} + \frac{1}{2} \partial_x \bar{u}^2 = 0 \implies \partial_t \bar{u} + \frac{1}{2} \partial_x \bar{u}^2 = \frac{1}{2} \partial_x \bar{\tau}$$

$$\bar{\tau} \equiv \bar{u}^2 - \overline{u^2}$$

The new sub-filter-scale tensor is not known, by definition. It needs to be modelled (or ignored)

2.2. The gradient model

$$G_i(|x_i - x'_i|) = \left(\frac{1}{4\pi\xi}\right) \exp\left(-\frac{|x_i - x'_i|^2}{4\xi}\right) \quad \text{with} \quad \xi = \Delta^2/24$$

• The gradient model assumes a Gaussian kernel. After performing a Fourier transformation of the kernel and expand it in Taylor series we can rewrite:

$$\overline{fg} \approx \overline{f}\,\overline{g} + 2\xi\nabla\overline{f}\cdot\nabla\overline{g}$$

$$\overline{fgh} \approx \overline{f}\,\overline{g}\overline{h} + 2\xi\big(\overline{h}\nabla\overline{f}\cdot\nabla\overline{g} + \overline{g}\nabla\overline{f}\cdot\nabla\overline{h} + \overline{f}\nabla\overline{g}\cdot\nabla\overline{h}\big)$$

[Viganò, R. A-M.+ 2020]

2.4. GRMHD evolution equations

$$\begin{split} \partial_t(\sqrt{\gamma}\overline{D}) &+ \partial_k \left[-\beta^k \sqrt{\gamma}\overline{D} + \alpha \sqrt{\gamma} \big(\widetilde{N^k} - \overline{\tau}_N^k \big) \right] = 0 \\ \partial_t(\sqrt{\gamma}\overline{S_i}) &+ \partial_k \left[-\beta^k \sqrt{\gamma}\overline{S_i} + \alpha \sqrt{\gamma} \left(\widetilde{T_i^k} - \gamma_{ij}\overline{\tau}_T^{jk} \right) \right] = \sqrt{\gamma}\overline{R_i^S} \\ \partial_t(\sqrt{\gamma}\overline{U}) &+ \partial_k \left[-\beta^k \sqrt{\gamma}\overline{U} + \alpha \sqrt{\gamma} \big(\widetilde{S^k} - \overline{\tau}_S^k \big) \right] = \sqrt{\gamma}\overline{R^U} \\ \partial_t(\sqrt{\gamma}\overline{B^i}) &+ \partial_k \left[\sqrt{\gamma} \big(-\beta^k \overline{B^i} + \beta^i \overline{B^k} \big) \right. \\ &+ \alpha \sqrt{\gamma} \big(\gamma^{ki}\overline{\Phi} + \widetilde{M}^{ki} - \overline{\tau}_M^{ki} \big) \right] = \sqrt{\gamma}\overline{R_B^i} \\ \partial_t(\sqrt{\gamma}\overline{\Phi}) &+ \partial_k \left[-\beta^k \sqrt{\gamma}\overline{\Phi} + \alpha c_h^2 \sqrt{\gamma}\overline{B^k} \right] = \sqrt{\gamma}\overline{R^\Phi} \end{split}$$

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$$\bar{\tau}_N^k = -C_N \xi H_N^k, \qquad \bar{\tau}_T^{ki} = -C_T \xi H_T^{ki}, \bar{\tau}_S^k = 0, \qquad \bar{\tau}_M^{ki} = -C_M \xi H_M^{ki}$$

2.4. GRMHD evolution equations

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$$\begin{split} \bar{\tau}_{N}^{k} &= -C_{N}\xi H_{N}^{k}, \qquad \bar{\tau}_{T}^{ki} = -C_{T}\xi H_{T}^{ki}, \\ \bar{\tau}_{S}^{k} &= 0, \qquad \bar{\tau}_{M}^{ki} = -C_{M}\xi H_{M}^{ki} \end{split}$$
$$H_{\varepsilon} &= H_{p} - \nabla \bar{B}_{j} \cdot \nabla \bar{B}^{j} - \nabla \tilde{E}_{j} \cdot \nabla \tilde{E}^{j} - \tilde{E}_{k} H_{E}^{k}, \\ H_{\Theta} &= \tilde{\Psi}_{\Theta} + \frac{\tilde{\Theta}}{\tilde{\Theta} - \tilde{E}^{2}} H_{p}, \qquad H_{\upsilon}^{k} = \tilde{\Psi}_{\upsilon}^{k} - \left(\tilde{\upsilon}^{k} + \frac{\overline{\tilde{\upsilon} \cdot B}}{\tilde{\varepsilon}} \bar{B}^{k}\right) \frac{H_{\Theta}}{\tilde{\Theta}} \end{split}$$

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$$\begin{split} H_N^k &= 2\nabla \overline{D} \cdot \nabla \widetilde{v}^k + \overline{D} H_v^k, \\ H_T^{ki} &= 2 \left[\nabla \widetilde{\varepsilon} \cdot \nabla (\widetilde{v}^i \widetilde{v}^k) + \widetilde{\varepsilon} \left(\widetilde{v}^{(i} H_v^{k)} + \nabla \widetilde{v}^i \cdot \nabla \widetilde{v}^k \right) \right] \\ &+ \widetilde{v}^i \widetilde{v}^k H_\varepsilon - 2 \left[\nabla \overline{B}^i \cdot \nabla \overline{B}^k + \nabla \widetilde{E}^i \cdot \nabla \widetilde{E}^k + \widetilde{E}^{(i} H_E^k) \right] \\ &+ \delta^{ki} \Big[H_p + \nabla \overline{B}_j \cdot \nabla \overline{B}^j + \nabla \widetilde{E}_j \cdot \nabla \widetilde{E}^j + \widetilde{E}_j H_E^j \Big], \\ H_M^{ki} &= 4 \nabla \overline{B}^{[i} \cdot \nabla \widetilde{v}^{k]} + 2 \overline{B}^{[i} H_v^{k]} \rightarrow H_E^i = \frac{1}{2} \epsilon_{jk}^i H_M^{jk} \end{split}$$

2.4. GRMHD evolution equations

$$\begin{split} & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{D} + \alpha\sqrt{p}(\bar{W}^{k} - \tau_{k}^{k})] = 0}{\partial_{c}(\sqrt{p}\bar{S}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{S} + \alpha\sqrt{p}(\bar{T}^{k} - \gamma_{k}\bar{\tau}_{k}^{k}]) = \sqrt{p}\bar{R}_{i}^{k}} \\ & \frac{\partial_{c}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{S} + \alpha\sqrt{p}(\bar{S}^{k} - \tau_{k}^{k})] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{S} + \alpha\sqrt{p}(\bar{S}^{k} - \tau_{k}^{k})] = \sqrt{p}\bar{R}_{i}^{k}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{S} + \alpha\sqrt{p}(\bar{S}^{k} - \tau_{k}^{k})] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}(\sqrt{p}\bar{D}) + \partial_{k}[-\beta^{k}\sqrt{p}\bar{G} + M^{k}\bar{I}^{k}] = \sqrt{p}\bar{R}_{i}^{k}}{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}}(\sqrt{p}\bar{D} + M^{k}\bar{I}^{k}) = \sqrt{p}\bar{R}_{i}^{k} \\ & \frac{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}\bar{R}} \\ & \frac{\partial_{t}}(\sqrt{p}\bar{D} + M^{k}\bar{R}) = \sqrt{p}\bar{R}_{i}^{k} \\ & \frac{\partial_{t}\bar{R}} \\$$

2.4. GRMHD evolution equations

$$\begin{split} \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = 0}{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}}{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}}{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\sqrt{\gamma}(\overline{h}^{k} - \tau_{k}^{k})\right] = \sqrt{\gamma}\overline{R}^{\gamma}}{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\overline{c}^{k}_{h}\sqrt{\gamma}\overline{B}^{k}\right] = \sqrt{\gamma}\overline{R}^{n}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{k}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\overline{c}^{k}_{h}\sqrt{\gamma}\overline{B}^{k}\right] = \sqrt{\gamma}\overline{R}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \partial_{t}\left[-\beta^{k}\sqrt{\gamma}\overline{D} + \alpha\overline{c}^{k}_{h}\sqrt{\gamma}\overline{B}^{k}\right] = \sqrt{\gamma}\overline{R}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \nabla^{k}(\sqrt{\gamma}\overline{D} + \alpha\overline{c}^{k}_{h}\sqrt{\gamma}\overline{B}^{k}) + \nabla^{k}(\overline{D} + \overline{D}^{k})\overline{P}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D}) + \nabla^{k}(\sqrt{\gamma}\overline{D} + \overline{D}^{k}) + \overline{P}^{k}\overline{P}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D} + \overline{D}^{k}) + \overline{P}^{k}\overline{P}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D} + \overline{D}^{k}} + \overline{D}^{k}) + \overline{P}^{k}\overline{P}^{k}\overline{P}^{k}} \\ \frac{\partial_{t}(\sqrt{\gamma}\overline{D} + \overline{D}^{k}) + \overline{P}^{k}\overline{P}^{k}} \\ \frac{\partial$$

[Palenzuela, R. A-M+ 2020]

2.5. Effects of LES in BNS mergers

MHDuet code generated with Simflowny software

- Einstein equation 4th order accurate finite differences
- Kreiss-Oliger 6th order dissipation
- Fluid MP5 reconstruction scheme + Lax-Friedrichs flux splitting formula
- LES 4th order differential operators for SGS terms
- 4th order Runge-Kutta
- CCZ4 formulation of Einstein equations.
- Initial data by Lorene code, equal masses (1.3 Msun), quasi-circular orbits separated by 45 km
- Magnetic fields initially **10¹¹ G**, confined to each star
- Hybrid EoS: piecewise APR4 + ideal

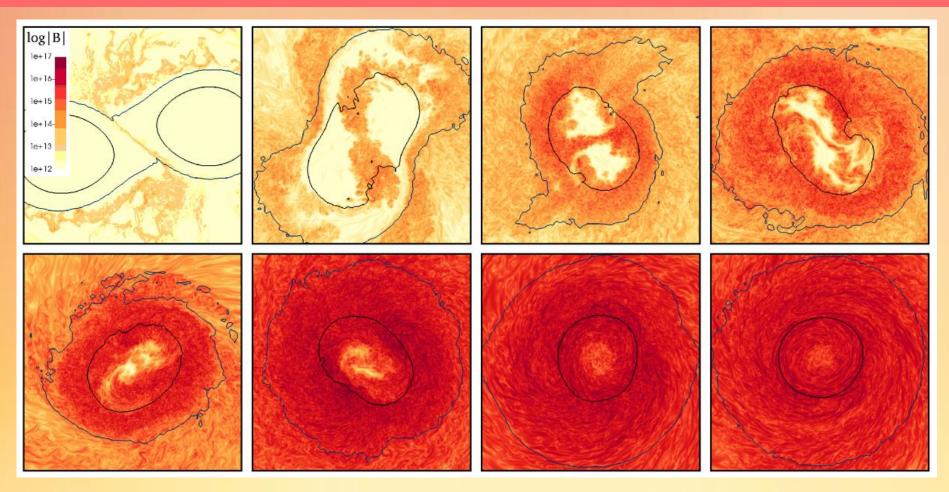
Numerical methods

Physical setup

Case	$\mathcal{C}_{\mathcal{M}}$	Refinement levels	ΔL_{min} [km]	Δ_{min} [m]
LR	0	$7~\mathrm{FMR}$	[-28, 28]	120
MR	0	7 FMR + 1 AMR	[-13, 13]	60
HR	0	7 FMR + 2 AMR	[-11, 11]	30
LR LES	8	$7~\mathrm{FMR}$	[-28, 28]	120
MR LES	8	7 FMR + 1 AMR	[-13, 13]	60
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2.5. Effects of LES in BNS mergers

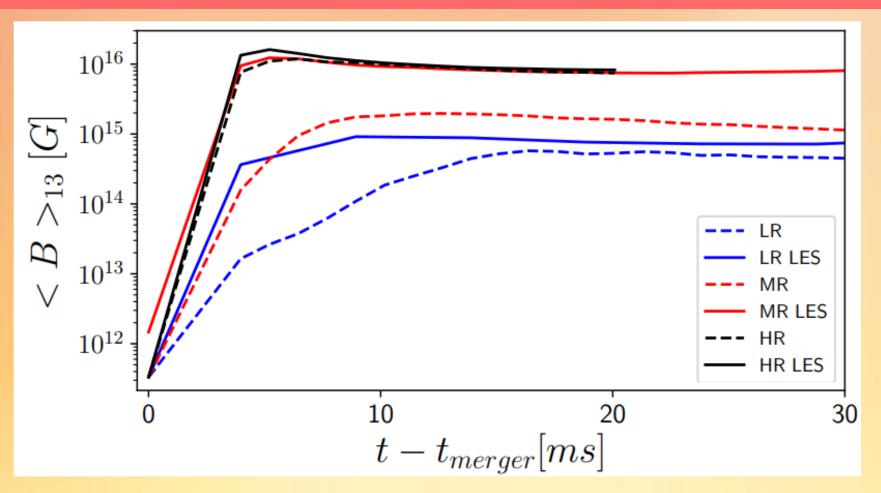
[Palenzuela, R. A-M+ 2022]



t = {0.5, 1.5, 2, 2.5, 3.5, 5, 10, 15} ms Constant density surfaces in 10^{13} and 5 x 10^{14} g / cm³

2.5. Effects of LES in BNS mergers

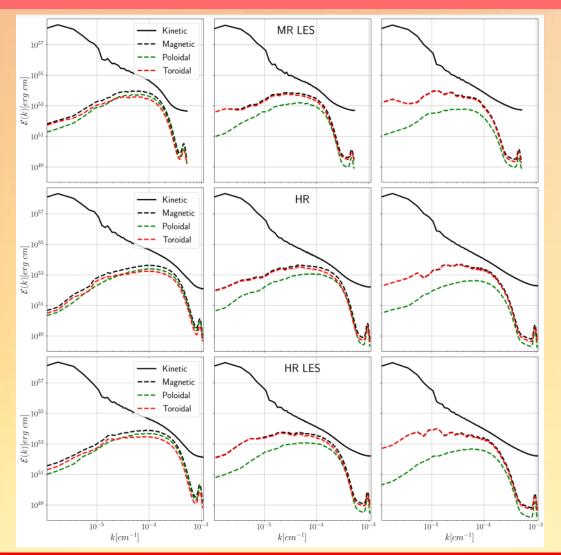
[Palenzuela, R. A-M+ 2022]

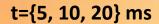


Saturation of magnetic field in t < 5 ms and convergence of averaged magnetic field strength and components!!

2.5. Effects of LES in BNS mergers

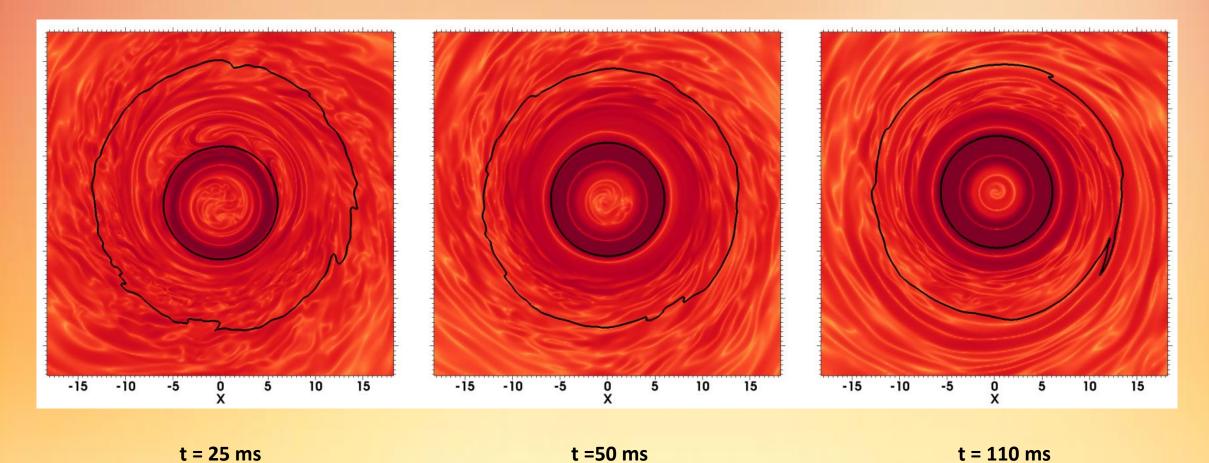
[Palenzuela, R. A-M+ 2022]





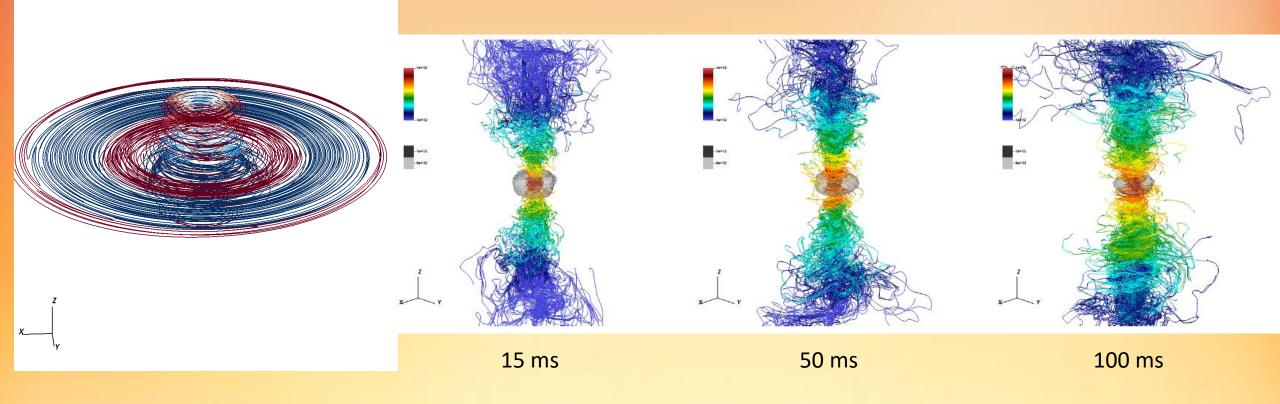
2.6. Magnetic field evolution

[Aguilera-Miret+ 2023]



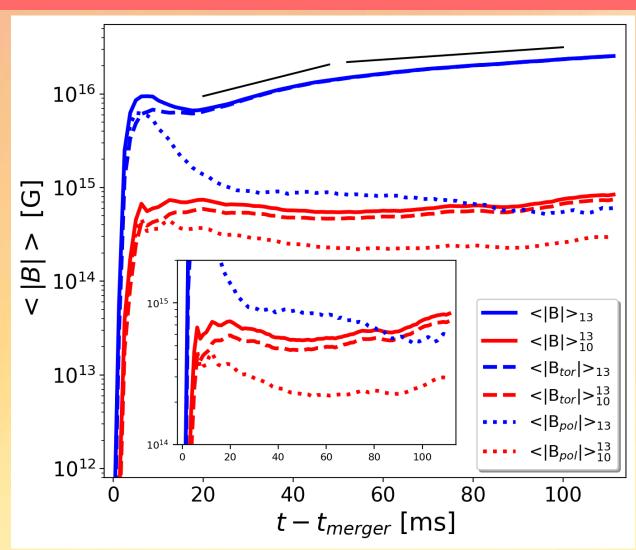
[Aguilera-Miret+ 2023]

2.6. Magnetic field evolution

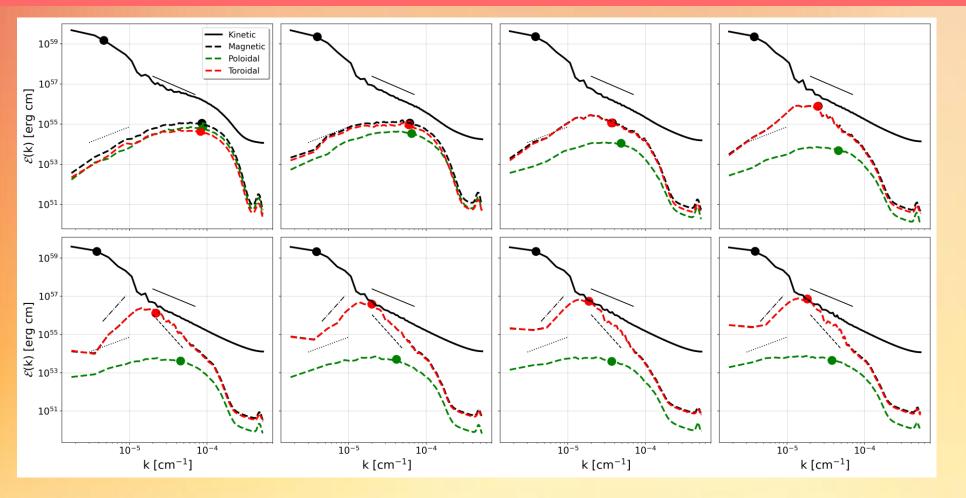


[Aguilera-Miret+ 2023]





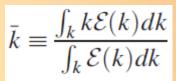
2.6. Magnetic field evolution



[Aguilera-Miret+ 2023]

Average magnetic structure length-scale:

t = 10 ms \rightarrow 700 m t = 100 ms \rightarrow 3,5 km



t = {5, 11, 21, 31, 50, 78, 100, 111} ms

2.7. Importance of the magnetic field topology

Does the initial magnetic field strength and topology matter at all in BNS mergers? Dipolar magnetic field ~ 10¹¹ G (Dip)

Dipolar magnetic field ~ 10¹⁴ G (Bhigh)

Dipolar with magnetic moment perpendicular to the z-axis ~ 10¹¹ G (Misaligned)

Multipolar magnetic field ~ 10¹¹ G (Multipolar)

$$A_{\Phi} \propto \sin^4 \theta \, (1 + \cos \theta) r^2 (P - P_{cut})$$

[Aguilera-Miret+ 2022]



2.7. Importance of the magnetic field topology

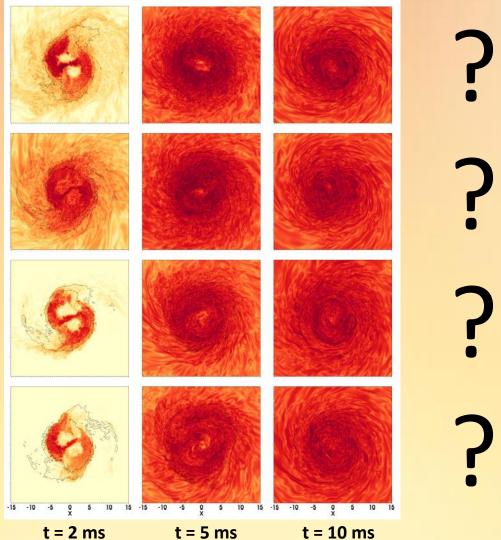
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Multipolar magnetic field ~ 10¹¹ G (Multipolar)

$$A_{\Phi} \propto \sin^4 \theta \, (1 + \cos \theta) r^2 (P - P_{cut})$$



[Aguilera-Miret+ 2022]



t = 20 ms

2.7. Importance of the magnetic field topology

Large Eddy Simulations of BNS mergers

Does the initial magnetic field strength and topology matter at all in BNS mergers? Dipolar magnetic field $\langle B \rangle \sim 10^{11} G$ (Dip) Dipolar magnetic field $\langle B \rangle \simeq 10^{14} G$ (Bhigh) **Dipolar with magnetic moment** perpendicular to the z-axis $\langle B \rangle \sim 10^{11} G$ (Misaligned) Multipolar magnetic field ~ 10¹¹ G (Multipolar)

-15 -10 -5 0

t = 2 ms

10 15 -15 -10 -5 0 5 10 15 -15 -10 -5 0 5 10 15

t = 10 ms

t = 5 ms

[Aguilera-Miret+ 2022]

Ricard Aguilera Miret

 $A_{\Phi} \propto \sin^4 \theta (1 + \cos \theta) r^2 (P - P_{cut})$

t = 20 ms

and topology matter at all in BNS mergers?

Dipolar magnetic field ~ 10¹¹ G

(Dip)

Dipolar magnetic field ~ 10¹⁴ G
(Bhigh)
Dipolar with magnetic moment

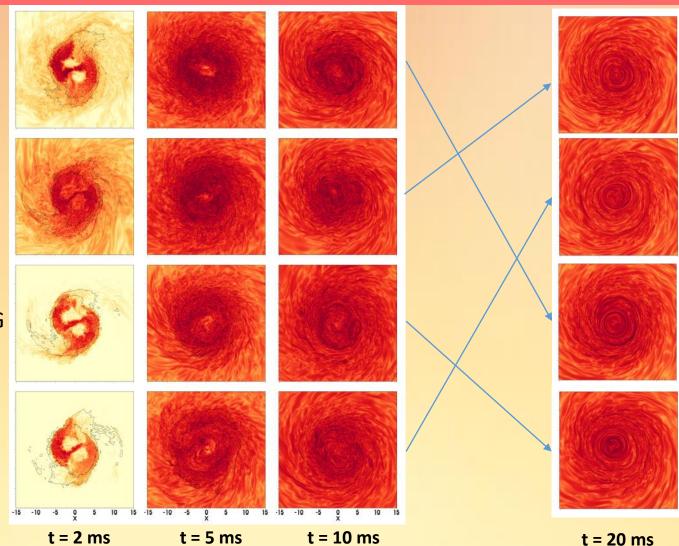
2.7. Importance of the magnetic field topology

perpendicular to the z-axis ~ 10¹¹ G (Misaligned)

Does the initial magnetic field strength

Multipolar magnetic field ~ 10¹¹ G (Multipolar)

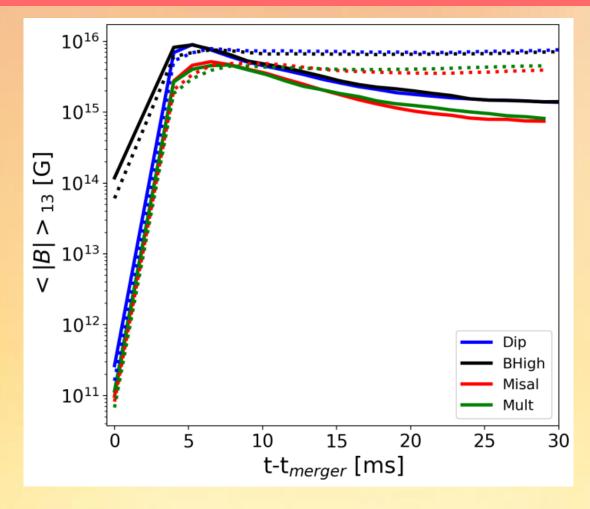
$$A_{\Phi} \propto \sin^4 \theta \, (1 + \cos \theta) r^2 (P - P_{cut})$$



[Aguilera-Miret+ 2022]

2.7. Importance of the magnetic field topology

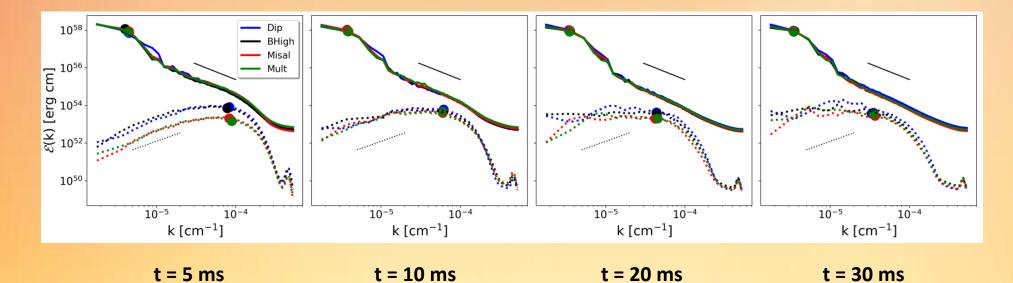
[Aguilera-Miret+ 2022]



Comparable averaged magnetic fields!!

2.7. Importance of the magnetic field topology

[Aguilera-Miret+ 2022]



Comparable magnetic field spectra (both toroidal and poloidal part)!!

2.8. Conclusions

- Average magnetic fields are amplified ~10¹¹ G → 10¹⁶ G in t < 5 ms after merger (bulk) by the KHI. The winding up effect change the magnetic spectra after the KHI from Kazantsev (3/2) to a ±9/2 power law in the equipartition point (located at ~3.5 km)
- 2. Our results do not imply that one can effectively model the exponential amplification produced during the KHI by starting with a strong, large-scale, poloidal magnetic field. In that case, the final state might be already contaminated by the large-scale magnetic field, leading to an accelerated growth due to the winding mechanism and ignoring completely the dominant, small-scale structures. The posterior evolution might be, at best, shifted in time with respect to the correct one. In the worst case, the non-linear dynamics might produce unrealistic results (i.e., like the early production of jets when there should be none, since they are facilitated by large-scale magnetic fields). In the absence of enough numerical resolution, the use of strong magnetic fields could be physically acceptable only if their topology is dominated by an axisymmetric toroidal component with highly turbulent homogeneous perturbations, as seen for the saturation state after the KHI phase.
- 3. The initial magnetic field strength and topology DOES NOT MATTER at all... as long as you can resolve the KHI that causes a turbulent amplification of the magnetic field. The turbulent magnetic field is isotropic and erases any dependence on the initial magnetic field topology and strength.
- 4. The formulation is general and can be applied to BNS post-merger or any scenario where the small scales are important

2.8. Conclusions

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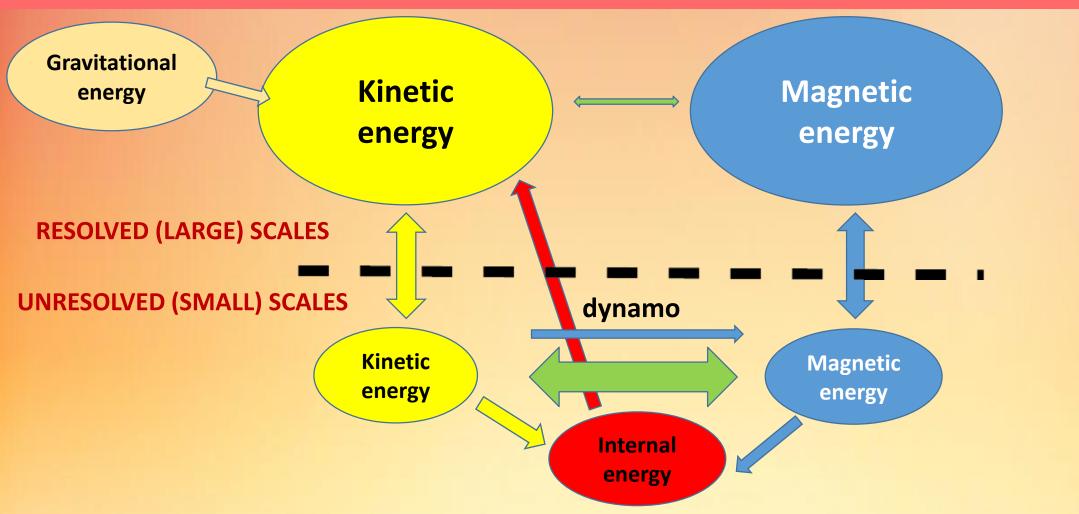


minated by the largempletely the dominant, rrect one. In the worst when there should be solution, the use of mmetric toroidal r the KHI phase.

Turbulent Magnetic Field Amplification in Binary Neutron Star Mergers

Large Eddy Simulations of BNS mergers

2.1. Filtering



2.1. Filtering

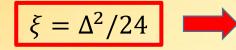
$$\bar{u}(\vec{x},t) = \int_{-\infty}^{\infty} G(\vec{x} - \vec{x}') \, u(\vec{x}',t) \, d^3x'$$

- Ideally, with infinite resolution, the kernel function is a Krönecker delta: $\delta(\vec{x} \vec{x}')$
- <u>BUT:</u>
 - Our world is not ideal \mathfrak{S} . Our simulations have a finite grid cell size (Δ)
- Simplest kernel function: Step function:

$$G_{i}(|\vec{x} - \vec{x}'|) = \begin{cases} 1/\Delta_{f} & \text{if } |\vec{x} - \vec{x}'| \leq \Delta_{f}/2\\ 0 & \text{otherwise} \end{cases}$$

- <u>BUT:</u>
 - It is not suitable for analytical calculations involving derivatives... Better to use this other smooth kernel: (1) (1) (1)

$$G_i(|x_i - x_i'|) = \left(\frac{1}{4\pi\xi}\right) \exp\left(-\frac{|x_i - x_i'|^2}{4\xi}\right)$$



We obtain a Gaussian function that resembles to a step function up to the **third moment!**

2.3. Compressible non-relativistic MHD evolution equations

[Viganò, R. A-M.+ 2019]

$$\begin{aligned} \partial_{t}\bar{\rho} + \partial_{k}N^{k}(\bar{\rho}) &= \partial_{k}\bar{\tau}_{N}^{k} \\ \partial_{t}\bar{N}^{i} + \partial_{k}T^{ki}(\bar{\rho}) &= \partial_{k}\bar{\tau}_{N}^{ki} \\ \partial_{t}\bar{U} + \partial_{k}S^{k}(\bar{\rho}) &= \partial_{k}\bar{\tau}_{N}^{ki} \\ \partial_{t}\bar{B} + \partial_{k}M^{ki}(\bar{\rho}) &= \partial_{k}\bar{\tau}_{N}^{ki} \\ \partial_{t}\bar{B} + \partial_{k}M^{ki}(\bar{\rho}) &= \partial_{k}\bar{\tau}_{N}^{ki} \\ \hline T^{ki}(\bar{\rho}) &= \tilde{v}^{i}\bar{v}^{j}\bar{\rho} - \bar{B}^{i}\bar{B}^{j} + \delta^{ij}\left(\bar{\rho} + \frac{\bar{B}^{2}}{2}\right) \\ S^{k}(\bar{\rho}) &= \left(\bar{U} + \bar{\rho} + \frac{\bar{B}^{2}}{2}\right) \tilde{v}^{k} - \bar{v} \cdot \bar{B}\bar{B}^{k} \\ M^{ki}(\bar{\rho}) &= \tilde{v}^{k}\bar{B}^{i} - \tilde{v}^{i}\bar{B}^{k} \end{aligned}$$

$$(UNKNOWN SFS TERMS)$$

$$\overline{\tau}_{N}^{ki} &= N^{ki}(\bar{\rho}) - N^{k}(\bar{\rho}) \\ \overline{\tau}_{N}^{ki} &= M^{ki}(\bar{\rho}) - \bar{N}^{ki}(\bar{\rho}) \\ \overline{\tau}_{N}^{ki} &= M^{ki}(\bar{\rho}) - \bar{N}^{ki}(\bar{\rho}) \end{aligned}$$

$$(GRADIENT SGS MODEL TERMS)$$

$$\overline{\tau}_{M}^{ki} &= M^{ki}(\bar{\rho}) - M^{ki}(\bar{\rho})$$

$$\overline{\tau}_{M}^{ki} &= -4 \left[\nabla \frac{d\bar{\rho}}{d\bar{\rho}} \cdot \nabla \bar{\rho} + \nabla \frac{d\bar{\rho}}{d\bar{c}} \cdot \nabla \bar{e} - \frac{2}{\bar{\rho}} \frac{d\bar{\rho}}{d\bar{c}} \nabla \bar{\nu} \cdot \nabla \bar{e}^{j} - \frac{1}{\bar{\rho}} \frac{d\bar{\rho}}{d\bar{c}} (\bar{\rho} \nabla \bar{v}_{j} \cdot \nabla \bar{v}^{j} + \nabla \bar{B}_{j} \cdot \nabla \bar{B}^{j}) \right]$$

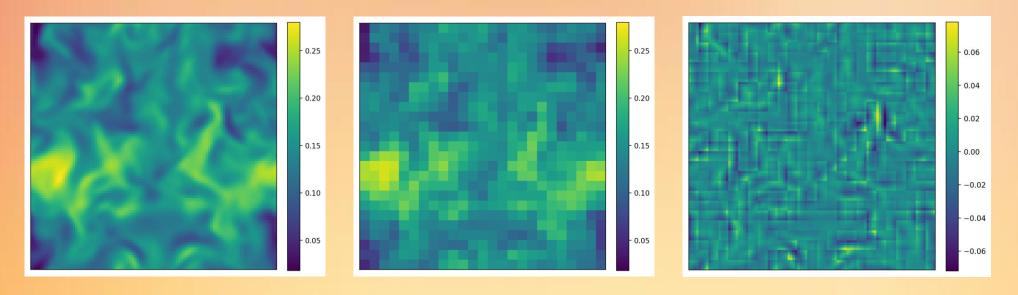
$$\overline{\tau}_{ener}^{ki} &= -2\xi [\nabla \bar{\rho} \nabla \bar{v}^{k} + (\bar{B}^{k}\bar{B}_{j} \nabla \bar{v}^{j} - \bar{\Theta} \nabla \bar{v}^{k}) \cdot \nabla (\ln \bar{\rho}) - \bar{B}^{k} \nabla \bar{B}_{j} \cdot \nabla \bar{v}^{j} - \nabla (\bar{v} \cdot \bar{B}) \cdot \nabla \bar{B}^{k}]$$

 ∂

 ∂

2.3. Compressible non-relativistic MHD evolution equations

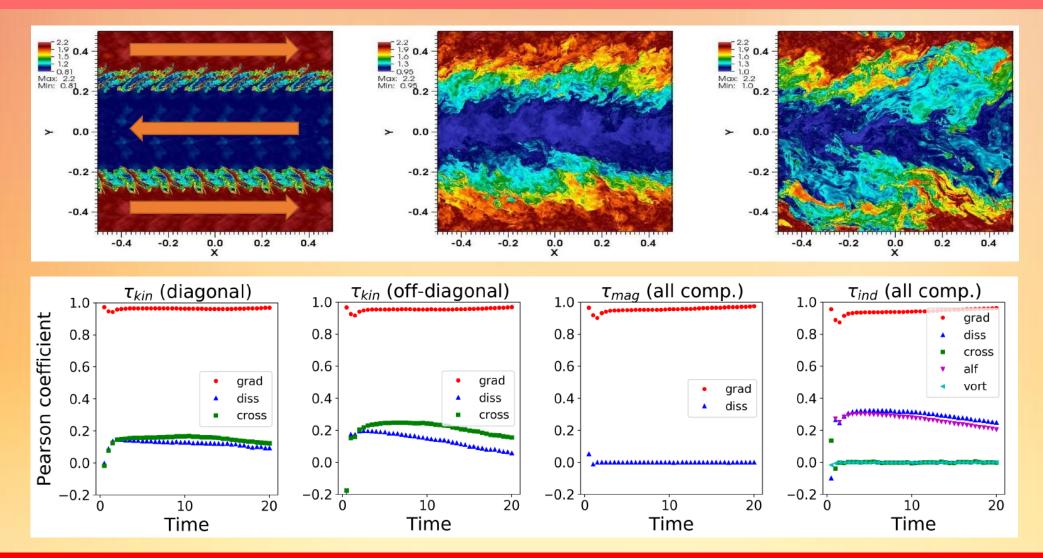
[Viganò, R. A-M.+ 2019]



 $u(\vec{x},t) = \bar{u}(\vec{x},t) + u'(\vec{x},t) \qquad \bar{\tau} = \bar{u}\bar{u} - \overline{u}\bar{u}$

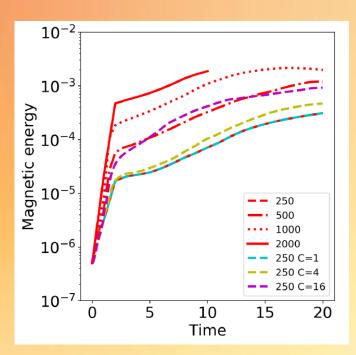
$$\mathcal{P} = Corr\{\bar{\tau}^{ki}, \tau^{ki}\} = [-1, 1], \quad C_{\text{best}}^{\text{ki}} = \frac{\Sigma \bar{\tau}^{ki} \tau^{ki}}{\Sigma (\tau^{ki})^2}$$

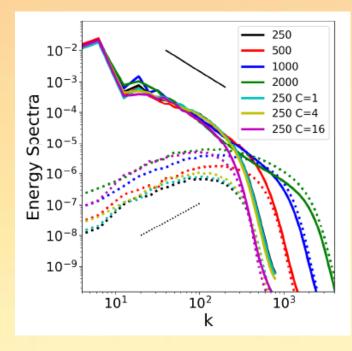
2.3. Compressible non-relativistic MHD evolution equations

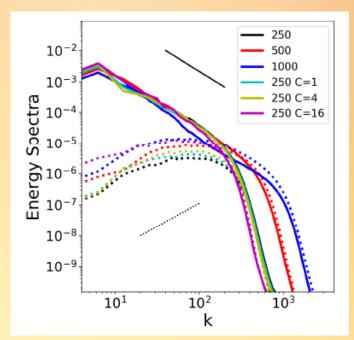




- Amplification of the magnetic energy with SGS
- Effective resolution x2 in the magnetic energy and x8 in the spectra at low k!







[Viganò, R. A-M.+ 2019]

t = 10

t = 20

2.4. GRMHD evolution equations

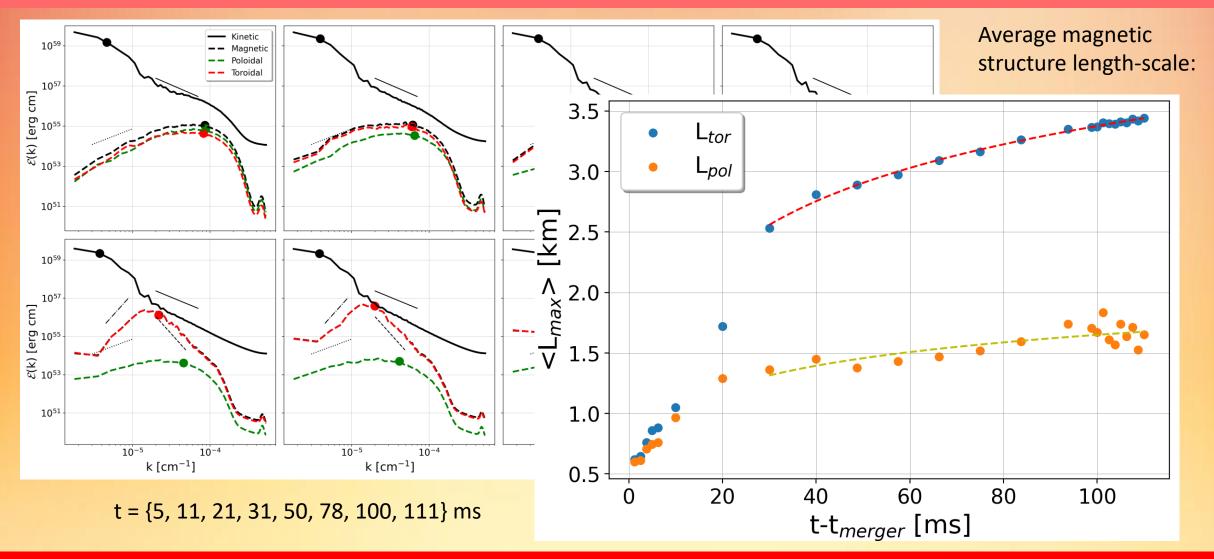
[Viganò, R. A-M.+ 2020]

Assumptions & Caveats

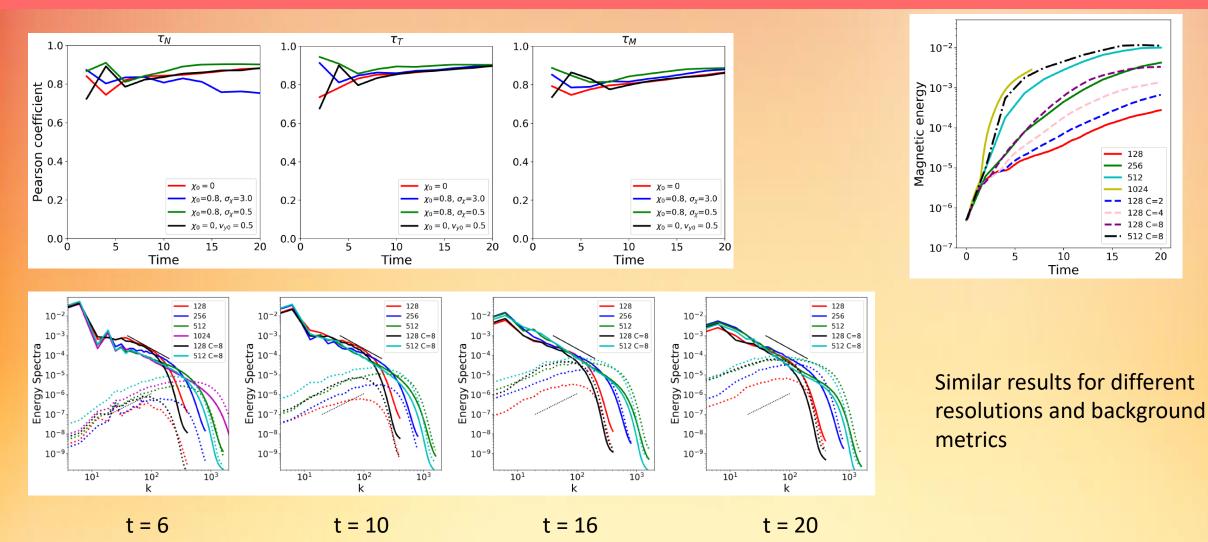
- The space-time metric is not "turbulent", i.e., the gradient terms arising from metric components in the fluid equations are neglected (verified by a-priori tests under typical conditions)
- Similarly, the SGS terms arising in the Einstein equations are not included, i.e., the steepness (derivatives) of MHD fields are dominating the non-linearity of the turbulence.
- The SGS can be thought as a reconstruction scheme because mimics the dynamics down to finite "depths" inside the cell without assuming any physical dynamics: if physical dynamics qualitatively differ at much smaller scales, there is nothing one can do.

2.6. Magnetic field evolution

[Aguilera-Miret+ 2023]



2.4. GRMHD evolution equations

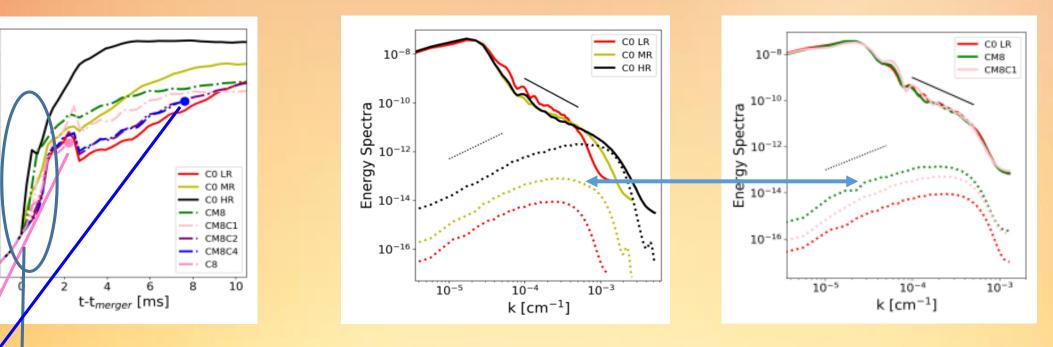


Large Eddy Simulations of Binary Neutron Star Mergers: Turbulent Amplification of the Magnetic Field

Large Eddy Simulations of BNS mergers

2.5. Effects of LES in BNS mergers

[Aguilera-Miret+ 2020]



Spectra at 5 ms

Effectiveness of SGS terms is evident mostly in the fast amplification phase. Non-linearity causes resolution/SGS-dependent collapse (adds an extra dissipation).

1050

[b10⁴⁹] for a 10⁴⁹ and 10⁴⁹ and 10⁴⁷

Magnetic 1046 1042

1046

1044

2.8. Importance of the initial configuration of the NSs?

[Aguilera-Miret+ in prep, 2024]

Ongoing work...

- Is this amplification independent from the initial data of the neutron stars?
 - q = 1, total mass = {1.8 3.0} Msun ---> Firsts results seem not to change at all!
 - $q \neq 1 \rightarrow$ Firsts results seem not to change at all! \bigcirc

0 ...