

Relational Quantum Relativity

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Motivation

- Motivation: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - compromised operationality and relationality
- Goal:
 - operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

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Plan

- 1 Preliminaries
- 2 Reference frames
- 3 Frame-relative descriptions
- 4 Restriction and localization
- 5 Frame transformations
- 6 Further perspectives

Quantum Mechanics

We endorse the following perspective on quantum mechanics (aligned with GPT frameworks):

- States are density operators $\mathcal{S}(\mathcal{H}) \subset \mathcal{T}(\mathcal{H})^{sa}$,
- Observables are positive operator-valued measures (POVMs)

$$E : \mathcal{F}(\Sigma) \rightarrow B(\mathcal{H}),$$

giving rise to probability distributions via Born rule:

$$\mu_{\omega}^E : \mathcal{F}(\Sigma) \ni X \mapsto \text{tr}[\omega E(X)].$$

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Operational equivalence

Set of available operators may be constrained $\mathcal{O} \subset B(\mathcal{H})$. Then

- $\omega \sim_{\mathcal{O}} \omega'$ iff $\text{tr}[\omega A] = \text{tr}[\omega' A]$ for all $A \in \mathcal{O}$,
- \mathcal{O} -operational state space:

$$\mathcal{S}(\mathcal{H})/\sim_{\mathcal{O}} \subset \mathcal{T}(\mathcal{H})^{sa}/\sim_{\mathcal{O}}.$$

We have:

$$[\text{span}(\mathcal{O})^{cl}]_* \cong \mathcal{T}(\mathcal{H})/\sim_{\mathcal{O}},$$

which extends the usual states/operators duality ($\mathcal{O} = B(\mathcal{H})$):

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What is an operational quantum reference frame?

Intuition: coordinates are *abstractions of physical systems*

- 1 **Reference frames can be (re)oriented.** Operationally speaking, they should be equipped with *group action* on system's state space, and (covariant) *frame observable* measuring orientation.
- 2 **Relativity of measurement/observation.** The operationally meaningful observables depend on the choice of the *reference frame = measuring instrument*. They should be defined on composite systems, (gauge-)invariant and compatible with choice of frame observable.
- 3 **Universality of quantum mechanics.** Physical systems are modelled by Hilbert space-based quantum mechanics.

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Quantum reference frames

Quantum reference frame (for G) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathbf{E}_{\mathcal{R}})$:

- Hilbert space $\mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}} : G \rightarrow B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathbf{E}_{\mathcal{R}} : \mathcal{B}(G) \rightarrow B(\mathcal{H}_{\mathcal{R}})$, i.e. for all $X \in \mathcal{B}(G)$

$$\mathbf{E}(g.X) = U_{\mathcal{R}}(g). \mathbf{E}(X) U_{\mathcal{R}}^*(g)$$

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Frame-relative descriptions

Given $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathbf{E}_{\mathcal{R}})$, $\mathcal{S} = (\mathcal{H}_{\mathcal{S}}, U_{\mathcal{S}})$ *restrict* available effects to those respecting choice of *frame observable* (call them *framed*):

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathbf{E}_{\mathcal{R}}} := \text{conv}\{\mathbf{E}(X) \otimes A_{\mathcal{S}} \mid X \in \mathcal{B}(G), A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})\}.$$

But we also want them to be *invariant*:

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathbf{E}_{\mathcal{R}}}^G := B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathbf{E}_{\mathcal{R}}} \cap B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G.$$

Is this *non-empty*?

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Relativization

Relativization map is given by

$$\mathbb{Y}^{\mathcal{R}} : B(\mathcal{H}_S) \ni A_S \mapsto \int_G dE_{\mathcal{R}}(g) \otimes g.A_S \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_S)_{E_{\mathcal{R}}}^G.$$

$$h.\mathbb{Y}^{\mathcal{R}}(A_S) = h. \int_G dE_{\mathcal{R}}(g) \otimes g.A_S = \int_G dE_{\mathcal{R}}(hg) \otimes hg.A_S = \mathbb{Y}^{\mathcal{R}}(A_S)$$

It is understood as incorporating reference explicitly into the description of \mathcal{S} . *Relative* description is given by

$$B(\mathcal{H}_S)^{\mathcal{R}} := \text{Im}(\mathbb{Y}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_S)_{E_{\mathcal{R}}}^G,$$

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Restriction and localization

For $\omega \in \mathcal{S}(\mathcal{H}_{\mathcal{R}})$ the ω -restriction maps are given by

$$\Gamma_{\omega} : B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{R}} \otimes A_{\mathcal{S}} \mapsto \omega(A_{\mathcal{R}})A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$$

and understood as conditioning description of composite system, upon a choice of reference's state. For frames that we call *localizable* one can find a sequence of states (ω_n) such that

$$\lim_{n \rightarrow \infty} (\Gamma_{\omega_n} \circ \Upsilon^{\mathcal{R}})(A_{\mathcal{S}}) = A_{\mathcal{S}}$$

for all $A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$. Thus the non-relational QM is recovered in a limiting sense upon externalizing localizable reference frames.

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Internal frame change maps

Consider two *internal* localizable frames

$$\mathcal{H} \cong \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_S$$

$$E_1 : \mathcal{B}(G) \rightarrow B(\mathcal{H}_1), \quad E_2 : \mathcal{B}(G) \rightarrow B(\mathcal{H}_2).$$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1 \rightarrow 2}^{loc}$ making the following diagrams commute

$$\begin{array}{ccc}
 & \mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_S)_G & \\
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 \end{array}$$

Internal frame change maps

Consider two *internal* localizable frames

$$\mathcal{H} \cong \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_S$$

$$E_1 : \mathcal{B}(G) \rightarrow B(\mathcal{H}_1), \quad E_2 : \mathcal{B}(G) \rightarrow B(\mathcal{H}_2).$$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1 \rightarrow 2}^{loc}$ making the following diagrams commute

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Further research directions:

- More general frames and systems
- Relational interactions
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Framed quantum observables

For any $\mathbf{E}_{\mathcal{R}} : \mathcal{F}(\Sigma) \rightarrow B(\mathcal{H}_{\mathcal{R}})$ and $f : \Sigma \rightarrow B(\mathcal{H}_{\mathcal{S}})$ such that

$$\Sigma \ni x \mapsto \text{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

are *integrable* for any state $\rho \in \mathcal{S}(\mathcal{H}_{\mathcal{S}})$, the operator

$$\int_{\Sigma} d\mathbf{E}_{\mathcal{R}}(x) \otimes f(x) \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})$$

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$$\mathcal{T}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni \omega \otimes \rho \mapsto \int_{\Sigma} d\mu_{\omega}^{\mathbf{E}_{\mathcal{R}}}(x) \text{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}.$$

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General framed observables

For any $\hat{\mathbf{E}}_{\mathcal{R}} : L^\infty(\Sigma, \mu) \rightarrow X_{\mathcal{R}}$ and $f : \Sigma \rightarrow X_{\mathcal{S}}$ such that

$$\Sigma \ni x \mapsto f(x)[t_{\mathcal{S}}] \in \mathbb{R}$$

are *integrable* for any $t_{\mathcal{S}} \in (X_{\mathcal{S}})_*$, the operator

$$\int_{\Sigma} d\hat{\mathbf{E}}_{\mathcal{R}}(x) \otimes f(x) \in X_{\mathcal{R}} \otimes X_{\mathcal{S}}$$

is *defined* as continuous linear extension of

$$(X_{\mathcal{R}})_* \odot (X_{\mathcal{S}})_* \ni t_{\mathcal{R}} \otimes t_{\mathcal{S}} \mapsto \int_{\Sigma} d\hat{\mathbf{E}}_{\mathcal{R}}[t_{\mathcal{R}}](x) f(x)[t_{\mathcal{S}}] d\mu \in \mathbb{R}.$$

Relational interactions

For $\Sigma \cong G/H$ and $\sigma : G/H \rightarrow G$ (equivariant, Borel) we define

$$\mathbb{Y}_\sigma^{\mathcal{R}}(A) := \int_{G/H} dE(x) \otimes \sigma(x).A \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G. \quad (1)$$

For $G = P$ (Poincar'e) and $H = O(1, 3)$ (Lorentz) consider

$$\sigma : P/O(1, 3) \cong \mathbb{M}^4 \ni x \mapsto (x, \hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1, 3) \cong P.$$

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Relational Process Theories

The relativization construction can be seen as a functor

$$\mathbb{Y} : \mathbf{Frm}_G \times \mathbf{Rep}_G \ni (\mathcal{R}, \mathcal{S}) \mapsto B(\mathcal{H}_S)^{\mathcal{R}} \subset B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_S)^G \in \mathbf{Equiv}_G,$$

where category \mathbf{Frm}_G is defined with $\mathcal{R} \rightarrow \mathcal{R}'$ given by

$$\begin{array}{ccc} B(\mathcal{H}_{\mathcal{R}}) & \xrightarrow{\psi} & B(\mathcal{H}_{\mathcal{R}'}) \\ E_{\mathcal{R}} \uparrow & & E_{\mathcal{R}'} \uparrow \\ \mathcal{B}(G) & \xleftarrow{h_{\cdot}} & \mathcal{B}(G) \end{array}$$

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Relativization map $\mathbb{Y}^{\mathcal{R}}$ can be seen as a natural transformation

$$\mathbb{Y} : i_G \Rightarrow B(\mathcal{H}_{\mathcal{R}}) \otimes i_G,$$

which follows from the commutativity of the following diagram

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 B(\mathcal{H}_S) & \xrightarrow{\mathbb{Y}^{\mathcal{R}'}} & & \xrightarrow{\psi \otimes h.(_)} & B(\mathcal{H}_{\mathcal{R}'} \otimes \mathcal{H}_S) \\
 \downarrow \phi & & \downarrow \mathbb{1}_{\mathcal{R}} \otimes \phi & & \downarrow \mathbb{1}_{\mathcal{R}'} \otimes \phi \\
 & \nearrow \mathbb{Y}^{\mathcal{R}} & B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{S'}) & \searrow \psi \otimes h.(_) & \\
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 \downarrow \phi & & \downarrow \mathbb{1}_{\mathcal{R}} \otimes \phi & & \downarrow \mathbb{1}_{\mathcal{R}'} \otimes \phi \\
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Thank you for your attention!