Relational Quantum Relativity

Jan Głowacki

International Center for Theory of Quantum Technologies, Gdańsk, Poland Basic Research Community for Physics, Leipzig, Germany Computer Science Department, Oxford, UK (soon)

17.11.2023



This project has received funding from the European Union's Horizon Europe Research and Innovation programme under Grant Agreement No. 101070558

The project named "Foundations of quantum computational

advantage" — FoQaCiA, No. 101070558 has received funding from the European Union within the Horizon Europe Framework Programme (HORIZON), the type of action HORIZON Research

and Innovation Actions (HORIZON-RIA).

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - compromised operationality and relationality

• Goal:

• operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - compromised operationality and relationality
- Goal:
 - operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - compromised operationality and relationality
- Goal:
 - operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - · compromised operationality and relationality
- Goal:
 - operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - · compromised operationality and relationality

• Goal:

• operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Motivation

- <u>Motivation</u>: despite tremendous success, quantum field theory is not fully satisfactory as a fundamental framework for physics:
 - no rigorous formalization of interacting theories
 - dependent on fixed background space-time
 - compromised operationality and relationality

• Goal:

 operational, completely rigorous, non-perturbative and background-less approach to relativistic (post-)quantum physics with a fully relational account of interactions, including gravity.

Plan

- Preliminaries
- Reference frames
- Frame-relative descriptions
- 4 Restriction and localization
- 5 Frame transformations
- 6 Further perspectives

We endorse the following perspective on quantum mechanics (aligned with GPT frameworks):

- States are density operators $S(\mathcal{H}) \subset T(\mathcal{H})^{sa}$,
- Observables are positive operator-valued measures (POVMs)

$$\mathsf{E}:\mathcal{F}(\Sigma)\to B(\mathcal{H}),$$

giving rise to probability distributions via Born rule

$$\mu_{\omega}^{\mathsf{E}}: \mathcal{F}(\Sigma) \ni X \mapsto \operatorname{tr}[\omega \mathsf{E}(X)]$$

We endorse the following perspective on quantum mechanics (aligned with GPT frameworks):

- States are density operators $\mathcal{S}(\mathcal{H}) \subset \mathcal{T}(\mathcal{H})^{sa}$,
- Observables are positive operator-valued measures (POVMs)

$$\mathsf{E}:\mathcal{F}(\Sigma)\to B(\mathcal{H}),$$

giving rise to probability distributions via Born rule

$$\mu_{\omega}^{\mathsf{E}}: \mathcal{F}(\Sigma) \ni X \mapsto \operatorname{tr}[\omega \mathsf{E}(X)]$$

We endorse the following perspective on quantum mechanics (aligned with GPT frameworks):

- States are density operators $\mathcal{S}(\mathcal{H}) \subset \mathcal{T}(\mathcal{H})^{sa}$,
- Observables are positive operator-valued measures (POVMs)

$$\mathsf{E}:\mathcal{F}(\Sigma)\to B(\mathcal{H}),$$

giving rise to probability distributions via Born rule:

$$\mu_{\omega}^{\mathsf{E}}: \mathcal{F}(\Sigma) \ni X \mapsto \operatorname{tr}[\omega \mathsf{E}(X)]$$

We endorse the following perspective on quantum mechanics (aligned with GPT frameworks):

- States are density operators $\mathcal{S}(\mathcal{H}) \subset \mathcal{T}(\mathcal{H})^{sa}$,
- Observables are positive operator-valued measures (POVMs)

$$\mathsf{E}:\mathcal{F}(\Sigma)\to B(\mathcal{H}),$$

giving rise to probability distributions via Born rule:

$$\mu_{\omega}^{\mathsf{E}}: \mathcal{F}(\Sigma) \ni X \mapsto \operatorname{tr}[\omega \mathsf{E}(X)].$$

Set of available operators may be constrained $\mathcal{O} \subset B(\mathcal{H})$. Then

- $\omega \sim_{\mathcal{O}} \omega'$ iff $\operatorname{tr}[\omega A] = \operatorname{tr}[\omega' A]$ for all $A \in \mathcal{O}$,
- *O*-operational state space:

$$S(\mathcal{H})/\sim_{\mathcal{O}}\subset T(\mathcal{H})^{sa}/\sim_{\mathcal{O}}$$

We have

$$\left[\operatorname{span}(\mathcal{O})^{cl}\right]_* \cong \mathcal{T}(\mathcal{H})/\sim_{\mathcal{O}},$$

$$[B(\mathcal{H})]_* \cong \mathcal{T}(\mathcal{H})$$

Set of available operators may be constrained $\mathcal{O} \subset B(\mathcal{H})$. Then

- $\omega \sim_{\mathcal{O}} \omega'$ iff $\operatorname{tr}[\omega A] = \operatorname{tr}[\omega' A]$ for all $A \in \mathcal{O}$,
- *O*-operational state space:

$$\mathcal{S}(\mathcal{H})/{\sim_{\mathcal{O}}}{\subset \mathcal{T}(\mathcal{H})^{sa}/{\sim_{\mathcal{O}}}}$$
.

We have

$$[\operatorname{span}(\mathcal{O})^{cl}]_{\star} \cong \mathcal{T}(\mathcal{H})/\sim_{\mathcal{O}},$$

$$[B(\mathcal{H})]_* \cong \mathcal{T}(\mathcal{H})$$

Set of available operators may be constrained $\mathcal{O} \subset B(\mathcal{H})$. Then

- $\omega \sim_{\mathcal{O}} \omega'$ iff $\operatorname{tr}[\omega A] = \operatorname{tr}[\omega' A]$ for all $A \in \mathcal{O}$,
- *O*-operational state space:

$$\mathcal{S}(\mathcal{H})/{\sim_{\mathcal{O}}}{\subset \mathcal{T}(\mathcal{H})^{sa}}/{\sim_{\mathcal{O}}}$$
 .

We have:

$$\left[\operatorname{span}(\mathcal{O})^{cl}\right]_* \cong \mathcal{T}(\mathcal{H})/\sim_{\mathcal{O}},$$

$$[B(\mathcal{H})]_* \cong \mathcal{T}(\mathcal{H}).$$

Set of available operators may be constrained $\mathcal{O} \subset B(\mathcal{H})$. Then

- $\omega \sim_{\mathcal{O}} \omega'$ iff $\operatorname{tr}[\omega A] = \operatorname{tr}[\omega' A]$ for all $A \in \mathcal{O}$,
- *O*-operational state space:

$$\mathcal{S}(\mathcal{H})/\sim_{\mathcal{O}}\subset \mathcal{T}(\mathcal{H})^{sa}/\sim_{\mathcal{O}}$$
.

We have:

$$[\operatorname{span}(\mathcal{O})^{cl}]_* \cong \mathcal{T}(\mathcal{H})/\sim_{\mathcal{O}},$$

$$[B(\mathcal{H})]_* \cong \mathcal{T}(\mathcal{H}).$$

What is an operational quantum reference frame?

<u>Intuition</u>: coordinates are abstractions of physical systems

- Reference frames can be (re)oriented. Operationally speaking they should be equipped with group action on system's state space, and (covariant) frame observable measuring orientation.
- **Relativity of measurement/observation.** The operationally meaningful observables depend on the choice of the *reference frame = measuring instrument*. They should be defined on composite systems, (gauge-)invariant and compatible with choice of frame observable.
- Universality of quantum mechanics. Physical systems are modelled by Hilbert space-based quantum mechanics.

What is an operational quantum reference frame?

Intuition: coordinates are abstractions of physical systems

- Reference frames can be (re)oriented. Operationally speaking, they should be equipped with group action on system's state space, and (covariant) frame observable measuring orientation.
- Relativity of measurement/observation. The operationally meaningful observables depend on the choice of the *reference frame = measuring instrument*. They should be defined on composite systems, (gauge-)invariant and compatible with choice of frame observable.
- Universality of quantum mechanics. Physical systems are modelled by Hilbert space-based quantum mechanics.

What is an operational quantum reference frame?

Intuition: coordinates are abstractions of physical systems

- Reference frames can be (re)oriented. Operationally speaking, they should be equipped with group action on system's state space, and (covariant) frame observable measuring orientation.
- **Relativity of measurement/observation.** The operationally meaningful observables depend on the choice of the *reference frame = measuring instrument*. They should be defined on composite systems, (gauge-)invariant and compatible with choice of frame observable.
- Universality of quantum mechanics. Physical systems are modelled by Hilbert space-based quantum mechanics.

What is an operational quantum reference frame?

Intuition: coordinates are abstractions of physical systems

- Reference frames can be (re)oriented. Operationally speaking, they should be equipped with group action on system's state space, and (covariant) frame observable measuring orientation.
- Relativity of measurement/observation. The operationally meaningful observables depend on the choice of the reference frame = measuring instrument. They should be defined on composite systems, (gauge-)invariant and compatible with choice of frame observable.
- **Universality of quantum mechanics.** Physical systems are modelled by Hilbert space-based quantum mechanics.

Quantum reference frame (for G) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$:

- Hilbert space $\mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}}: G \to B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathsf{E}_{\mathcal{R}}:\mathcal{B}(G)\to B(\mathcal{H}_{\mathcal{R}})$, i.e. for all $X\in\mathcal{B}(G)$

$$\mathsf{E}(g.X) = U_{\mathcal{R}}(g).\mathsf{E}(X)U_{\mathcal{R}}^*(g)$$

Quantum reference frame $\equiv quantum \ system + frame \ observable$.

Quantum reference frame (for G) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$:

- $\bullet \ \ Hilbert \ space \ \mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}}: G \to B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathsf{E}_{\mathcal{R}}:\mathcal{B}(G)\to B(\mathcal{H}_{\mathcal{R}})$, i.e. for all $X\in\mathcal{B}(G)$

$$\mathsf{E}(g.X) = U_{\mathcal{R}}(g).\mathsf{E}(X)U_{\mathcal{R}}^*(g)$$

Quantum reference frame $\equiv quantum \ system + frame \ observable$

Quantum reference frame (for G) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$:

- Hilbert space $\mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}}:G \to B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathsf{E}_{\mathcal{R}}:\mathcal{B}(G)\to B(\mathcal{H}_{\mathcal{R}})$, i.e. for all $X\in\mathcal{B}(G)$

$$\mathsf{E}(g.X) = U_{\mathcal{R}}(g).\mathsf{E}(X)U_{\mathcal{R}}^*(g)$$

Quantum reference frame $\equiv quantum \ system + frame \ observable$

Quantum reference frame (for *G*) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$:

- Hilbert space $\mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}}:G \to B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathsf{E}_\mathcal{R}:\mathcal{B}(G)\to B(\mathcal{H}_\mathcal{R})$, i.e. for all $X\in\mathcal{B}(G)$

$$\mathsf{E}(g.X) = U_{\mathcal{R}}(g).\mathsf{E}(X)U_{\mathcal{R}}^*(g)$$

Quantum reference frame $\equiv quantum \ system + frame \ observable$.

Quantum reference frame (for *G*) is a triple $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$:

- Hilbert space $\mathcal{H}_{\mathcal{R}}$
- group action $U_{\mathcal{R}}: G \to B(\mathcal{H}_{\mathcal{R}})^{uni}$
- *covariant* POVM $\mathsf{E}_\mathcal{R}:\mathcal{B}(G)\to B(\mathcal{H}_\mathcal{R})$, i.e. for all $X\in\mathcal{B}(G)$

$$\mathsf{E}(g.X) = U_{\mathcal{R}}(g).\mathsf{E}(X)U_{\mathcal{R}}^*(g)$$

Quantum reference frame $\equiv quantum \ system + frame \ observable$.

Given $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$, $\mathcal{S} = (\mathcal{H}_{\mathcal{S}}, U_{\mathcal{S}})$ restrict available effects to those respecting choice of frame observable (call them framed):

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} := \mathsf{conv}\{\mathsf{E}(X) \otimes A_{\mathcal{S}} \mid X \in \mathcal{B}(G), A_{\mathcal{S}} \in \mathcal{B}(\mathcal{H}_{\mathcal{S}})\}$$

But we also want them to be invariant

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}}^G := B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} \cap B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G.$$
Is this *non-empty*?

Given $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$, $\mathcal{S} = (\mathcal{H}_{\mathcal{S}}, U_{\mathcal{S}})$ restrict available effects to those respecting choice of frame observable (call them framed):

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} := \mathsf{conv}\{\mathsf{E}(X) \otimes A_{\mathcal{S}} \mid X \in \mathcal{B}(G), A_{\mathcal{S}} \in \mathcal{B}(\mathcal{H}_{\mathcal{S}})\}.$$

But we also want them to be invariant

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}}^G := B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} \cap B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G$$
Is this *non-empty*?

Given $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$, $\mathcal{S} = (\mathcal{H}_{\mathcal{S}}, U_{\mathcal{S}})$ restrict available effects to those respecting choice of frame observable (call them framed):

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} := \mathsf{conv}\{\mathsf{E}(X) \otimes A_{\mathcal{S}} \,|\, X \in \mathcal{B}(G), A_{\mathcal{S}} \in \mathcal{B}(\mathcal{H}_{\mathcal{S}})\}.$$

But we also want them to be *invariant*:

$$\mathit{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{\mathit{G}}_{\mathsf{E}_{\mathcal{R}}} := \mathit{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} \cap \mathit{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{\mathit{G}}.$$

Is this non-empty

Given $\mathcal{R} = (\mathcal{H}_{\mathcal{R}}, U_{\mathcal{R}}, \mathsf{E}_{\mathcal{R}})$, $\mathcal{S} = (\mathcal{H}_{\mathcal{S}}, U_{\mathcal{S}})$ restrict available effects to those respecting choice of frame observable (call them framed):

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} := \mathsf{conv}\{\mathsf{E}(X) \otimes A_{\mathcal{S}} \mid X \in \mathcal{B}(G), A_{\mathcal{S}} \in \mathcal{B}(\mathcal{H}_{\mathcal{S}})\}.$$

But we also want them to be *invariant*:

$$B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}}^G := B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{\mathcal{R}}} \cap B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G.$$
Is this *non-empty*?

Relativization map is given by

$$\Psi^{\mathcal{R}}: B(\mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{S}} \mapsto \int_{G} dE_{\mathcal{R}}(g) \otimes g.A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}.$$

$$h. \mathbb{Y}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathbb{Y}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \operatorname{Im}(\mathbb{Y}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}},$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{\textit{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \; \cong \text{Im}(\boldsymbol{\Psi}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

Relativization map is given by

$$\mathfrak{X}^{\mathcal{R}}: B(\mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{S}} \mapsto \int_{G} dE_{\mathcal{R}}(g) \otimes g.A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}.$$

$$h. \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \operatorname{Im}(\mathbb{Y}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{\mathit{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \; \cong \mathrm{Im}(\boldsymbol{\Psi}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

Relativization map is given by

$$h. \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \operatorname{Im}(\mathbb{Y}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \cong \operatorname{Im}(\mathbb{Y}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

Relativization map is given by

$$\Psi^{\mathcal{R}}: B(\mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{S}} \mapsto \int_{G} dE_{\mathcal{R}}(g) \otimes g.A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}.$$

$$h. \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \operatorname{Im}({\mathbb{Y}}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}},$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \cong \operatorname{Im}(\mathbb{Y}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

Relativization map is given by

$$\Psi^{\mathcal{R}}: B(\mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{S}} \mapsto \int_{G} dE_{\mathcal{R}}(g) \otimes g.A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}.$$

$$h. \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$B(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \operatorname{Im}({\mathbb{Y}}^{\mathcal{R}})^{cl} \subseteq B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}},$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{\textit{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \; \cong \text{Im}(\boldsymbol{\Psi}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

Relativization map is given by

$$\Psi^{\mathcal{R}}: B(\mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{S}} \mapsto \int_{G} dE_{\mathcal{R}}(g) \otimes g.A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}_{\mathsf{E}_{\mathcal{R}}}.$$

$$h. \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}}) = h. \int_{G} dE_{\mathcal{R}}(g) \otimes g. A_{\mathcal{S}} = \int_{G} dE_{\mathcal{R}}(hg) \otimes hg. A_{\mathcal{S}} = \mathfrak{X}^{\mathcal{R}}(A_{\mathcal{S}})$$

$$\textit{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} := \text{Im}(\boldsymbol{\Psi}^{\mathcal{R}})^{\textit{cl}} \subseteq \textit{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{\textit{G}}_{\mathsf{E}_{\mathcal{R}}},$$

$$\mathcal{S}(\mathcal{H}_{\mathcal{S}})_{\mathcal{R}} := \mathcal{S}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) / \sim_{\textit{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}}} \; \cong \text{Im}(\boldsymbol{\Psi}_{*}^{\mathcal{R}}) =: \mathcal{S}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subseteq \mathcal{S}(\mathcal{H}_{\mathcal{S}}).$$

For $\omega \in \mathcal{S}(\mathcal{H}_{\mathcal{R}})$ the ω -restriction maps are given by

$$\Gamma_{\omega}: B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{R}} \otimes A_{\mathcal{S}} \mapsto \omega(A_{\mathcal{R}})A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$$

and understood as conditioning description of composite system, upon a choice of reference's state. For frames that we call *localizable* one can find a sequence of states (ω_n) such that

$$\lim_{n\to\infty}(\Gamma_{\omega_n}\circ {\mathbb Y}^{\mathcal R})(A_{\mathcal S})=A_{\mathcal S}$$

For $\omega \in \mathcal{S}(\mathcal{H}_{\mathcal{R}})$ the ω -restriction maps are given by

$$\Gamma_{\omega}: B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{R}} \otimes A_{\mathcal{S}} \mapsto \omega(A_{\mathcal{R}})A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$$

and understood as conditioning description of composite system, upon a choice of reference's state. For frames that we call *localizable* one can find a sequence of states (ω_n) such that

$$\lim_{n\to\infty}(\Gamma_{\omega_n}\circ {\mathbb{Y}}^{\mathcal{R}})(A_{\mathcal{S}})=A_{\mathcal{S}}$$

For $\omega \in \mathcal{S}(\mathcal{H}_{\mathcal{R}})$ the ω -restriction maps are given by

$$\Gamma_{\omega}: B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{R}} \otimes A_{\mathcal{S}} \mapsto \omega(A_{\mathcal{R}})A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$$

and understood as conditioning description of composite system, upon a choice of reference's state. For frames that we call *localizable* one can find a sequence of states (ω_n) such that

$$\lim_{n\to\infty} (\Gamma_{\omega_n} \circ \mathbf{Y}^{\mathcal{R}})(A_{\mathcal{S}}) = A_{\mathcal{S}}$$

For $\omega \in \mathcal{S}(\mathcal{H}_{\mathcal{R}})$ the ω -restriction maps are given by

$$\Gamma_{\omega}: B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni A_{\mathcal{R}} \otimes A_{\mathcal{S}} \mapsto \omega(A_{\mathcal{R}})A_{\mathcal{S}} \in B(\mathcal{H}_{\mathcal{S}})$$

and understood as conditioning description of composite system, upon a choice of reference's state. For frames that we call *localizable* one can find a sequence of states (ω_n) such that

$$\lim_{n\to\infty} (\Gamma_{\omega_n} \circ \mathbf{Y}^{\mathcal{R}})(A_{\mathcal{S}}) = A_{\mathcal{S}}$$

Consider two internal localizable frames

$$\mathcal{H}\cong\mathcal{H}_1{\otimes}\mathcal{H}_2\otimes\mathcal{H}_{\mathcal{S}}$$

$$\mathsf{E}_1:\mathcal{B}(G)\to B(\mathcal{H}_1), \quad \mathsf{E}_2:\mathcal{B}(G)\to B(\mathcal{H}_2)$$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1\rightarrow2}^{loc}$ making the following diagrams commute

$$\mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_G \xrightarrow{\pi_{\mathsf{E}_1} \circ \Psi_*^{\mathcal{R}_1}} \mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_G \xrightarrow{\pi_{\mathsf{E}_1} \circ \Psi_*^{\mathcal{R}_2}} \mathcal{S}(\mathcal{H}_2 \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_1}^{R_1} \xrightarrow{\Phi_{1 \to 2}^{\mathsf{loc}}} \mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_1}^{R_2}.$$

Consider two internal localizable frames

$$\mathcal{H} \cong \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_{\mathcal{S}}$$

 $\mathsf{E}_1 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_1), \quad \mathsf{E}_2 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_2).$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1\to 2}^{loc}$ making the following diagrams commute

$$\mathcal{S}(\mathcal{H}_{1}\otimes\mathcal{H}_{2}\otimes\mathcal{H}_{\mathcal{S}})_{G}$$

$$\pi_{\mathsf{E}_{2}}\circ Y_{*}^{\mathcal{R}_{1}}$$

$$\mathcal{S}(\mathcal{H}_{2}\otimes\mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{1}}^{R_{1}} \xrightarrow{\Phi_{1\rightarrow 2}^{\mathsf{loc}}} \mathcal{S}(\mathcal{H}_{1}\otimes\mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{1}}^{R_{2}}$$

Consider two internal localizable frames

$$\mathcal{H} \cong \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_{\mathcal{S}}$$

 $\mathsf{E}_1 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_1), \quad \mathsf{E}_2 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_2).$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1\to 2}^{loc}$ making the following diagrams commute

$$\mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_G \xrightarrow{\pi_{\mathsf{E}_1} \circ \Psi_*^{\mathcal{R}_2}} \mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_G \xrightarrow{\pi_{\mathsf{E}_1} \circ \Psi_*^{\mathcal{R}_2}} \mathcal{S}(\mathcal{H}_2 \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_1}^{R_1} \xrightarrow{\Phi_{1 \to 2}^{\mathsf{loc}}} \mathcal{S}(\mathcal{H}_1 \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_1}^{R_2}.$$

Consider two *internal* localizable frames

$$\mathcal{H} \cong \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \mathcal{H}_{\mathcal{S}}$$

 $\mathsf{E}_1 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_1), \quad \mathsf{E}_2 : \mathcal{B}(G) \to \mathcal{B}(\mathcal{H}_2).$

There is a well-defined, invertible and composable (in the context of three frames) map $\Phi_{1\to 2}^{loc}$ making the following diagrams commute

$$\mathcal{S}(\mathcal{H}_{1} \otimes \mathcal{H}_{\mathcal{S}})_{G}$$

$$\xrightarrow{\pi_{\mathsf{E}_{2}} \circ \Psi_{*}^{\mathcal{R}_{1}}} \xrightarrow{\Phi_{1 \to 2}^{\mathsf{loc}}} \mathcal{S}(\mathcal{H}_{1} \otimes \mathcal{H}_{\mathcal{S}})_{G}$$

$$\xrightarrow{\pi_{\mathsf{E}_{1}} \circ \Psi_{*}^{\mathcal{R}_{2}}} \longrightarrow \mathcal{S}(\mathcal{H}_{1} \otimes \mathcal{H}_{\mathcal{S}})_{\mathsf{E}_{1}}^{R_{2}}.$$

Preliminaries Reference frames Frame-relative descriptions Restriction and localization Frame transformations Further perspectives

Further research directions:

- More general frames and systems
- Relational interactions
- Relational Process Theories
-

Preliminaries
Reference frames
Frame-relative descriptions
Restriction and localization
Frame transformations
Further perspectives

Further research directions:

- More general frames and systems
- Relational interactions
- Relational Process Theories
- ...

For any $\mathsf{E}_{\mathcal{R}}:\mathcal{F}(\Sigma)\to B(\mathcal{H}_{\mathcal{R}})$ and $f:\Sigma\to B(\mathcal{H}_{\mathcal{S}})$ such that

$$\Sigma \ni x \mapsto \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

are *integrable* for any state $\rho \in \mathcal{S}(\mathcal{H}_{\mathcal{S}})$, the operator

$$\int_{\Sigma} d\mathsf{E}_{\mathcal{R}}(x) \otimes f(x) \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})$$

$$\mathcal{T}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni \omega \otimes \rho \mapsto \int_{\Sigma} d\mu_{\omega}^{\mathsf{E}_{\mathcal{R}}}(x) \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

For any
$$\mathsf{E}_\mathcal{R}:\mathcal{F}(\Sigma)\to B(\mathcal{H}_\mathcal{R})$$
 and $f:\Sigma\to B(\mathcal{H}_\mathcal{S})$ such that

$$\Sigma \ni x \mapsto \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

are *integrable* for any state $\rho \in \mathcal{S}(\mathcal{H}_{\mathcal{S}})$, the operator

$$\int_{\Sigma} d\mathsf{E}_{\mathcal{R}}(x) \otimes f(x) \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})$$

$$\mathcal{T}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni \omega \otimes \rho \mapsto \int_{\Sigma} d\mu_{\omega}^{\mathsf{E}_{\mathcal{R}}}(x) \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

For any
$$\mathsf{E}_\mathcal{R}:\mathcal{F}(\Sigma)\to B(\mathcal{H}_\mathcal{R})$$
 and $f:\Sigma\to B(\mathcal{H}_\mathcal{S})$ such that

$$\Sigma \ni x \mapsto \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

are *integrable* for any state $\rho \in \mathcal{S}(\mathcal{H}_{\mathcal{S}})$, the operator

$$\int_{\Sigma} d\mathsf{E}_{\mathcal{R}}(x) \otimes f(x) \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})$$

$$\mathcal{T}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni \omega \otimes \rho \mapsto \int_{\Sigma} d\mu_{\omega}^{\mathsf{E}_{\mathcal{R}}}(x) \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

For any $\mathsf{E}_\mathcal{R}:\mathcal{F}(\Sigma)\to B(\mathcal{H}_\mathcal{R})$ and $f:\Sigma\to B(\mathcal{H}_\mathcal{S})$ such that

$$\Sigma \ni x \mapsto \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}$$

are *integrable* for any state $\rho \in \mathcal{S}(\mathcal{H}_{\mathcal{S}})$, the operator

$$\int_{\Sigma} d\mathsf{E}_{\mathcal{R}}(x) \otimes f(x) \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})$$

$$\mathcal{T}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}}) \ni \omega \otimes \rho \mapsto \int_{\Sigma} d\mu_{\omega}^{\mathsf{E}_{\mathcal{R}}}(x) \operatorname{tr}[\rho f_{\mathcal{S}}(x)] \in \mathbb{C}.$$

General framed observables

For any $\hat{\mathsf{E}}_{\mathcal{R}}: L^{\infty}(\Sigma, \mu) \to X_{\mathcal{R}}$ and $f: \Sigma \to X_{\mathcal{S}}$ such that

$$\Sigma \ni x \mapsto f(x)[t_{\mathcal{S}}] \in \mathbb{R}$$

are *integrable* for any $t_S \in (X_S)_*$, the operator

$$\int_{\Sigma} d\hat{\mathsf{E}}_{\mathcal{R}}(x) \otimes f(x) \in X_{\mathcal{R}} \otimes X_{\mathcal{S}}$$

$$(X_{\mathcal{R}})_* \odot (X_{\mathcal{S}})_* \ni t_{\mathcal{R}} \otimes t_{\mathcal{S}} \mapsto \int_{\Sigma} d\hat{\mathsf{E}}_{\mathcal{R}}[t_{\mathcal{R}}](x) f(x)[t_{\mathcal{S}}] d\mu \in \mathbb{R}.$$

For $\Sigma \cong G/H$ and $\sigma: G/H \to G$ (equivariant, Borel) we define

For G = P (Poincar'e) and H = O(1,3) (Lorentz) consider

$$\sigma: P/O(1,3) \cong \mathbb{M}^4 \ni x \mapsto (x,\hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1,3) \cong P$$

Section $\hat{\sigma}: \mathbb{M}^4 \to O(1,3)$ can be interpreted as encoding interaction between frame and system, reflected by relativization map $\mathbb{Y}_{\sigma}^{\mathcal{R}}$.

For $\Sigma \cong G/H$ and $\sigma: G/H \to G$ (equivariant, Borel) we define

$$\Psi_{\sigma}^{\mathcal{R}}(A) := \int_{G/H} d\mathsf{E}(x) \otimes \sigma(x) . A \in B(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}. \tag{1}$$

For G = P (Poincar'e) and H = O(1,3) (Lorentz) consider

$$\sigma: P/O(1,3) \cong \mathbb{M}^4 \ni x \mapsto (x,\hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1,3) \cong P$$

Section $\hat{\sigma}: \mathbb{M}^4 \to O(1,3)$ can be interpreted as encoding interaction between frame and system, reflected by relativization map $\mathbb{Y}^{\mathcal{R}}_{\sigma}$.

For $\Sigma \cong G/H$ and $\sigma: G/H \to G$ (equivariant, Borel) we define

For G = P (Poincar'e) and H = O(1,3) (Lorentz) consider

$$\sigma: P/O(1,3) \cong \mathbb{M}^4 \ni x \mapsto (x,\hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1,3) \cong P$$

Section $\hat{\sigma}: \mathbb{M}^4 \to O(1,3)$ can be interpreted as encoding interaction between frame and system, reflected by relativization map $\mathbb{Y}^{\mathcal{R}}_{\sigma}$.

For $\Sigma \cong G/H$ and $\sigma: G/H \to G$ (equivariant, Borel) we define

$$\mathfrak{X}_{\sigma}^{\mathcal{R}}(A) := \int_{G/H} d\mathsf{E}(x) \otimes \sigma(x).A \in \mathcal{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}.$$
 (1)

For G = P (Poincar'e) and H = O(1,3) (Lorentz) consider

$$\sigma: P/O(1,3) \cong \mathbb{M}^4 \ni x \mapsto (x,\hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1,3) \cong P.$$

Section $\hat{\sigma}: \mathbb{M}^4 \to O(1,3)$ can be interpreted as encoding interaction between frame and system, reflected by relativization map $\mathbb{Y}^{\mathcal{R}}_{\sigma}$.

For $\Sigma \cong G/H$ and $\sigma : G/H \to G$ (equivariant, Borel) we define

$$\mathfrak{Y}_{\sigma}^{\mathcal{R}}(A) := \int_{G/H} d\mathsf{E}(x) \otimes \sigma(x) . A \in \mathcal{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^{G}. \tag{1}$$

For G = P (Poincar'e) and H = O(1,3) (Lorentz) consider

$$\sigma: P/O(1,3) \cong \mathbb{M}^4 \ni x \mapsto (x,\hat{\sigma}(x)) \in \mathbb{M}^4 \rtimes O(1,3) \cong P.$$

Section $\hat{\sigma}: \mathbb{M}^4 \to O(1,3)$ can be interpreted as encoding interaction between frame and system, reflected by relativization map $\mathbb{Y}_{\sigma}^{\mathcal{R}}$.

Relational Process Theories

The relativization construction can be seen as a functor

$$\Psi: \mathbf{Frm}_G \times \mathbf{Rep}_G \ni (\mathcal{R}, \mathcal{S}) \mapsto \mathcal{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subset \mathcal{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G \in \mathbf{Equiv}_G,$$

where category \mathbf{Frm}_G is defined with $\mathcal{R} \to \mathcal{R}'$ given by

$$B(\mathcal{H}_{\mathcal{R}}) \xrightarrow{\psi} B(\mathcal{H}_{\mathcal{R}'})$$

$$E_{\mathcal{R}} \uparrow \qquad E_{\mathcal{R}'} \uparrow$$

$$\mathcal{B}(G) \xleftarrow{h_{-}} \mathcal{B}(G)$$

and $i_G : \mathbf{Equiv}_G \hookrightarrow \mathbf{Rep}_G$ is a subcategory of equivariant channels.

Relational Process Theories

The relativization construction can be seen as a functor

where category \mathbf{Frm}_G is defined with $\mathcal{R} \to \mathcal{R}'$ given by

and $i_G : \mathbf{Equiv}_G \hookrightarrow \mathbf{Rep}_G$ is a subcategory of equivariant channels.

Relational Process Theories

The relativization construction can be seen as a functor

$$\Psi: \mathbf{Frm}_G \times \mathbf{Rep}_G \ni (\mathcal{R}, \mathcal{S}) \mapsto \mathcal{B}(\mathcal{H}_{\mathcal{S}})^{\mathcal{R}} \subset \mathcal{B}(\mathcal{H}_{\mathcal{R}} \otimes \mathcal{H}_{\mathcal{S}})^G \in \mathbf{Equiv}_G$$

where category \mathbf{Frm}_G is defined with $\mathcal{R} \to \mathcal{R}'$ given by

$$B(\mathcal{H}_{\mathcal{R}}) \xrightarrow{\psi} B(\mathcal{H}_{\mathcal{R}'})$$

$$\mathsf{E}_{\mathcal{R}} \uparrow \qquad \mathsf{E}_{\mathcal{R}'} \uparrow$$

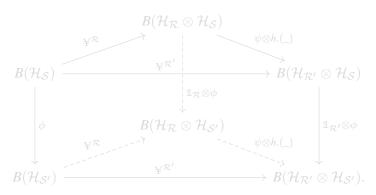
$$\mathcal{B}(G) \longleftarrow^{h_{-}} \mathcal{B}(G)$$

and $i_G : \mathbf{Equiv}_G \hookrightarrow \mathbf{Rep}_G$ is a subcategory of equivariant channels.

Relativization map $Y^{\mathcal{R}}$ can be seen as a natural transformation

$$Y: i_G \Rightarrow B(\mathcal{H}_{\mathcal{R}}) \otimes i_G,$$

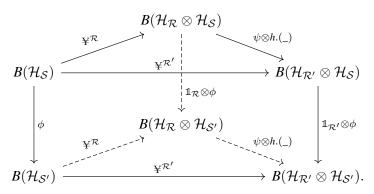
which follows from the commutativity of the following diagram



Relativization map $Y^{\mathcal{R}}$ can be seen as a natural transformation

$$Y: i_G \Rightarrow B(\mathcal{H}_{\mathcal{R}}) \otimes i_G$$

which follows from the commutativity of the following diagram



Preliminaries Reference frames Frame-relative descriptions Restriction and localization Frame transformations Further perspectives

Thank you for your attention!