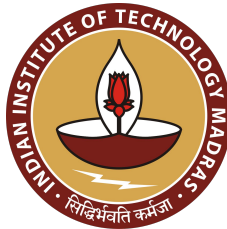


Tracking Tapered Gridded Estimator: Results from MWA drift scan observations

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Collaborators

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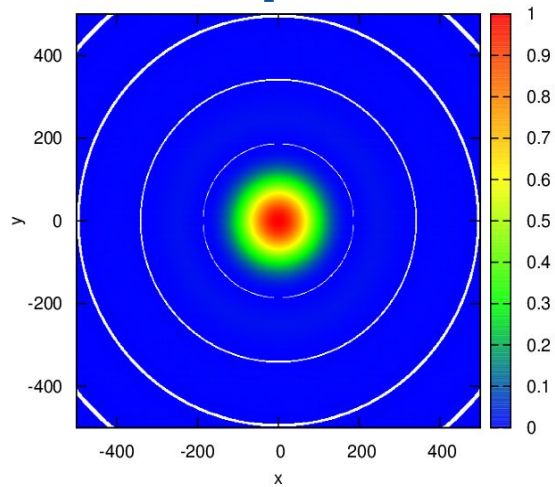
Aim

Develop an power spectrum estimator for Drift scan radio observation which will increase SNR

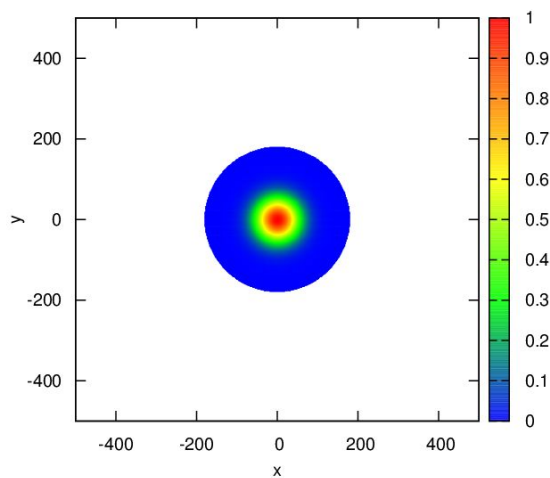
-Tracking Tapered Gridded Estimator (TTGE)

Tapered Gridded Estimator

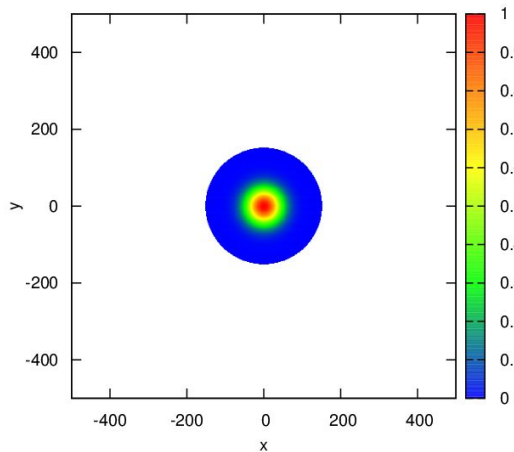
Tapered Gridded Estimator



\times



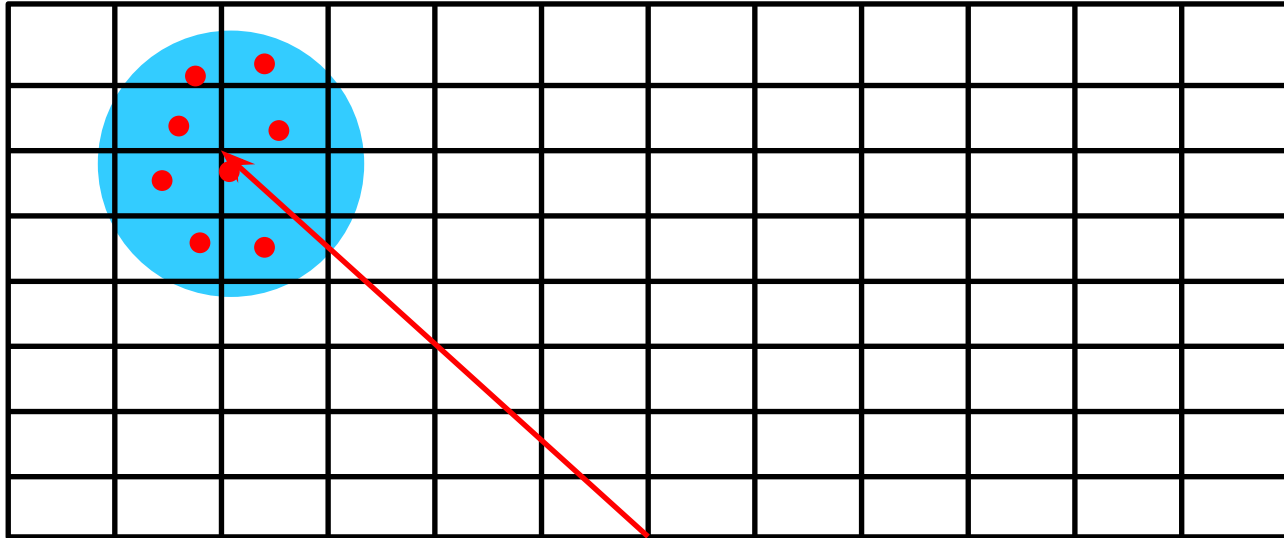
Primary Beam



Taper Window

Tapering and Gridding

Visibility-based :



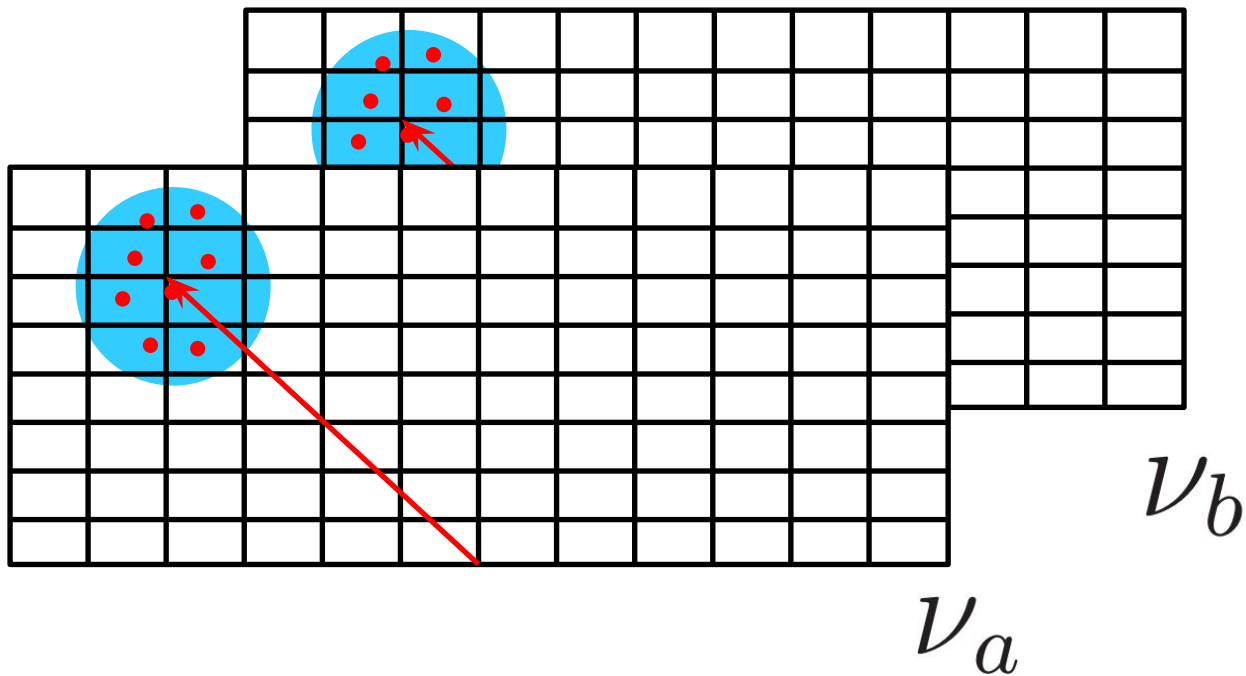
$$\mathcal{V}_{cg} = \sum_i \tilde{w}(\mathbf{U}_g - \mathbf{U}_i) \mathcal{V}_i$$

Tapered Gridded Estimator

1. Gridded Estimator
2. Suppress Side-lobe Response
3. Remove Noise Bias

$$\hat{E}_g = M_g^{-1} \left(|\mathcal{V}_{cg}|^2 - \sum_i |\tilde{w}(\mathbf{U}_g - \mathbf{U}_i)|^2 |\mathcal{V}_i|^2 \right)$$

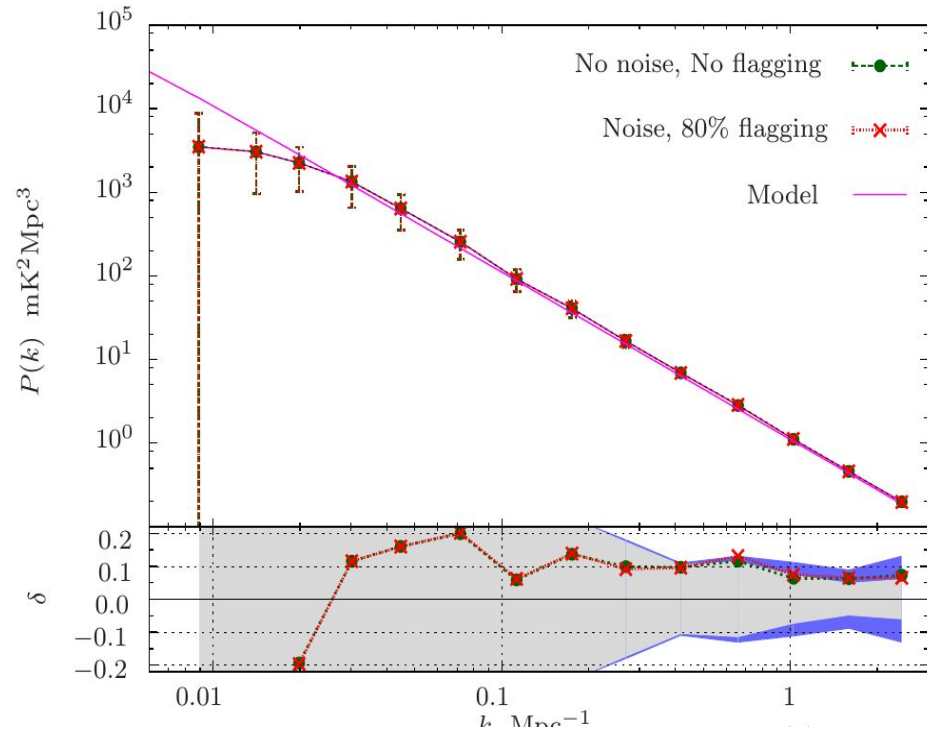
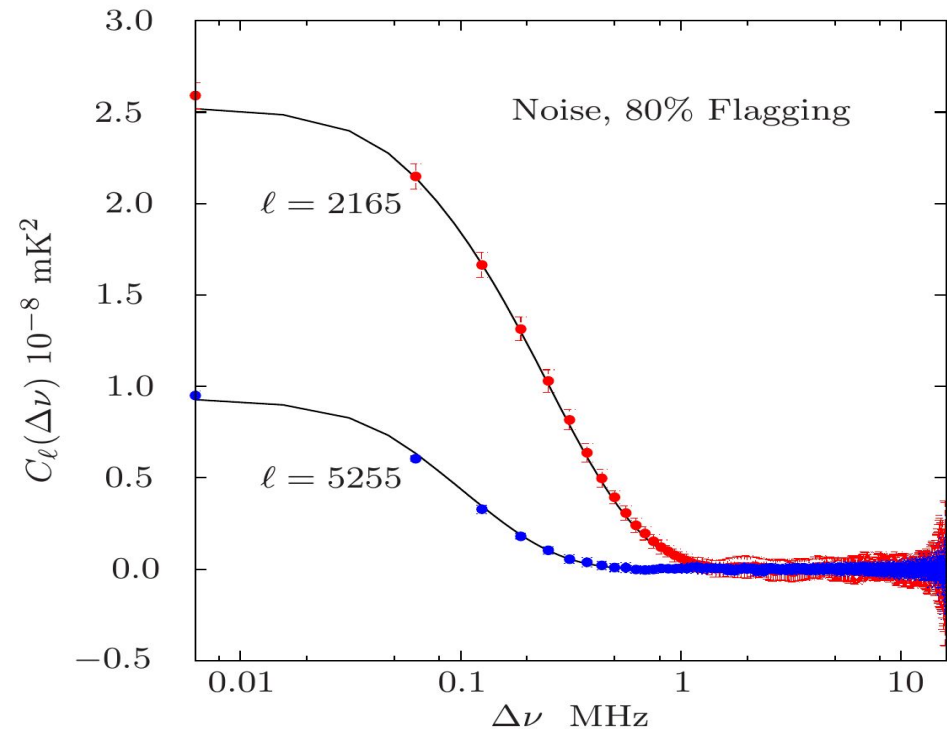
TGE: the MAPS and the Power-Spectrum



$$P(k_{\perp}, k_{\parallel}) = r^2 r' \int_{-\infty}^{\infty} d(\Delta\nu) e^{-ik_{\parallel} r' \Delta\nu} C_{\ell}(\Delta\nu)$$

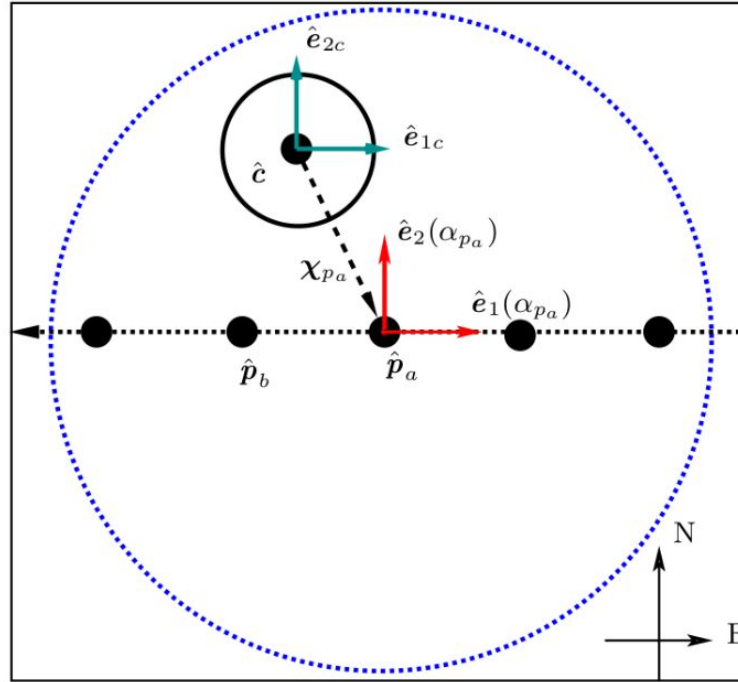
MAPS

TGE: the MAPS and the Power-Spectrum

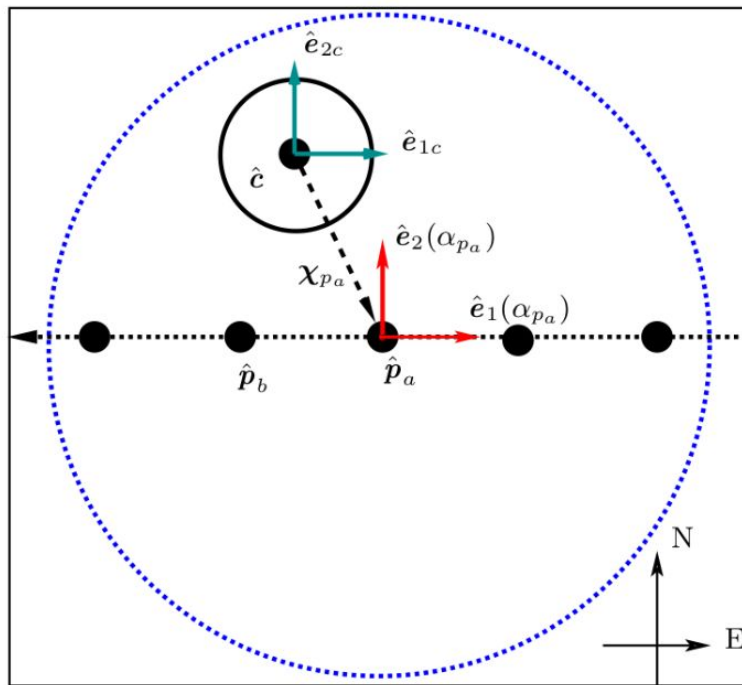


Bharadwaj, Pal, Choudhuri et al 2019, MNRAS

Tracking TGE

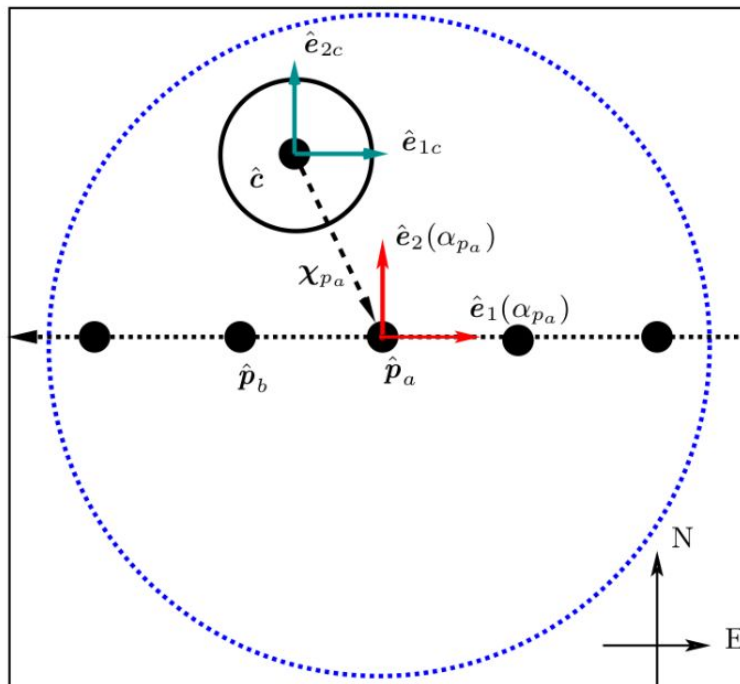


Tracking TGE



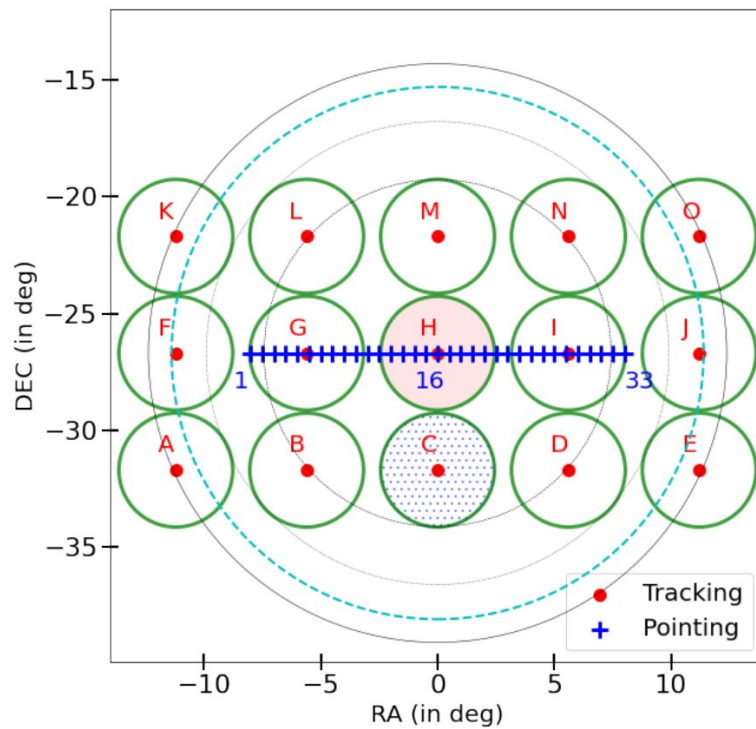
$$\mathcal{V}_{cg}(\nu) = \sum_p s_p \sum_n \tilde{w}(\mathbf{U}_g - \mathbf{U}_n) e^{2\pi i \mathbf{U}_n \cdot \chi_p} \mathcal{V}(\alpha_p, \mathbf{U}_n, \nu)$$

Tracking TGE

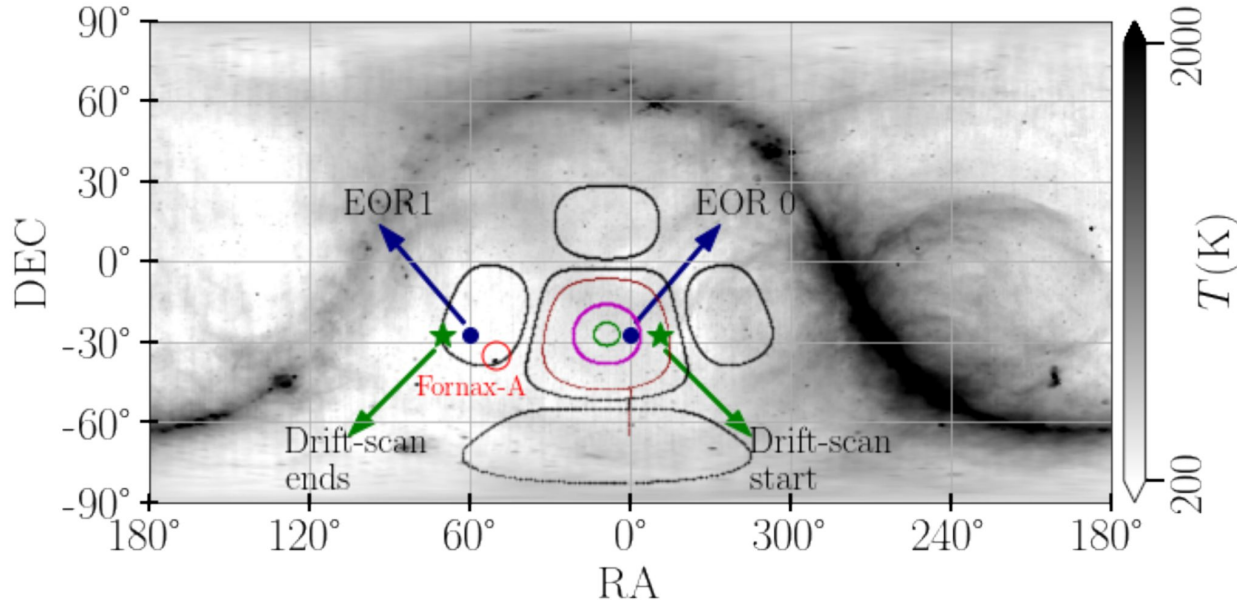


$$\begin{aligned} \hat{E}_g(\nu_a, \nu_b) &= M_g^{-1}(\nu_a, \nu_b) \mathcal{R}e [\mathcal{V}_{cg}(\nu_a) \mathcal{V}_{cg}^*(\nu_b) \\ &- \delta_{a,b} \sum_{p,n} |s_p \tilde{w}(\mathbf{U}_g - \mathbf{U}_n)|^2 |\mathcal{V}(\alpha_p, \mathbf{U}_n, \nu_a)|^2]. \end{aligned}$$

Tracking TGE



MWA Observation



Time duration of 5 hr 24 min, 10 nights

RA - 349° to 70.3°, 162 different pointing centers

MWA Observation

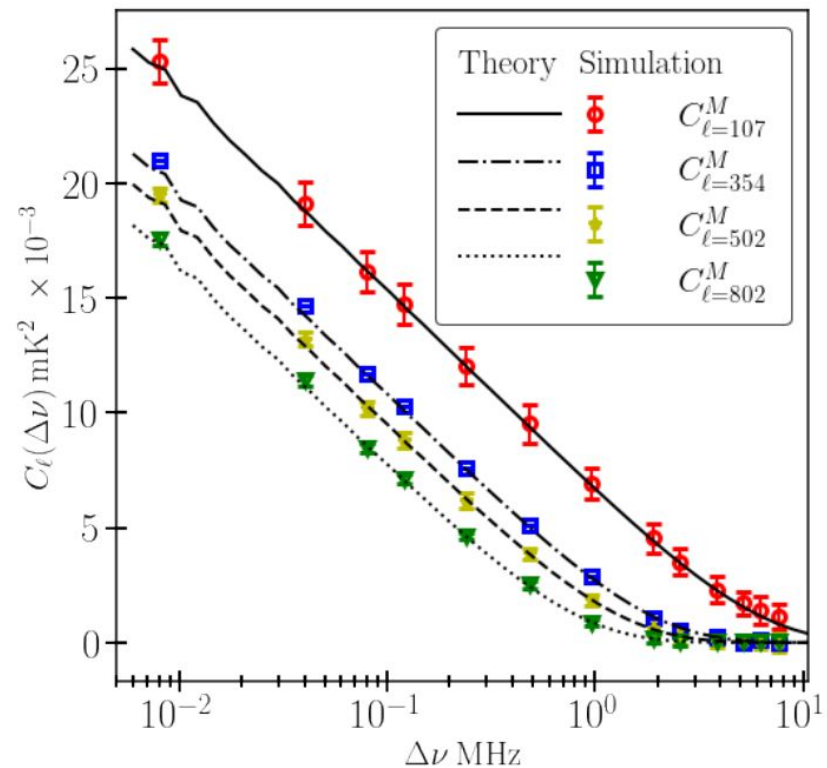
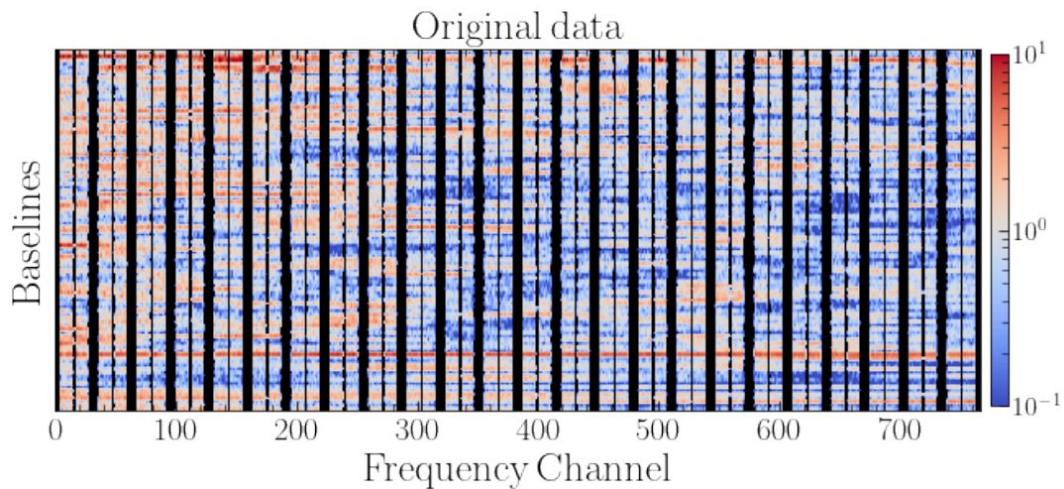
Central frequency = 154.2 MHz ($z = 8.2$)

$N_c = 768$ channels

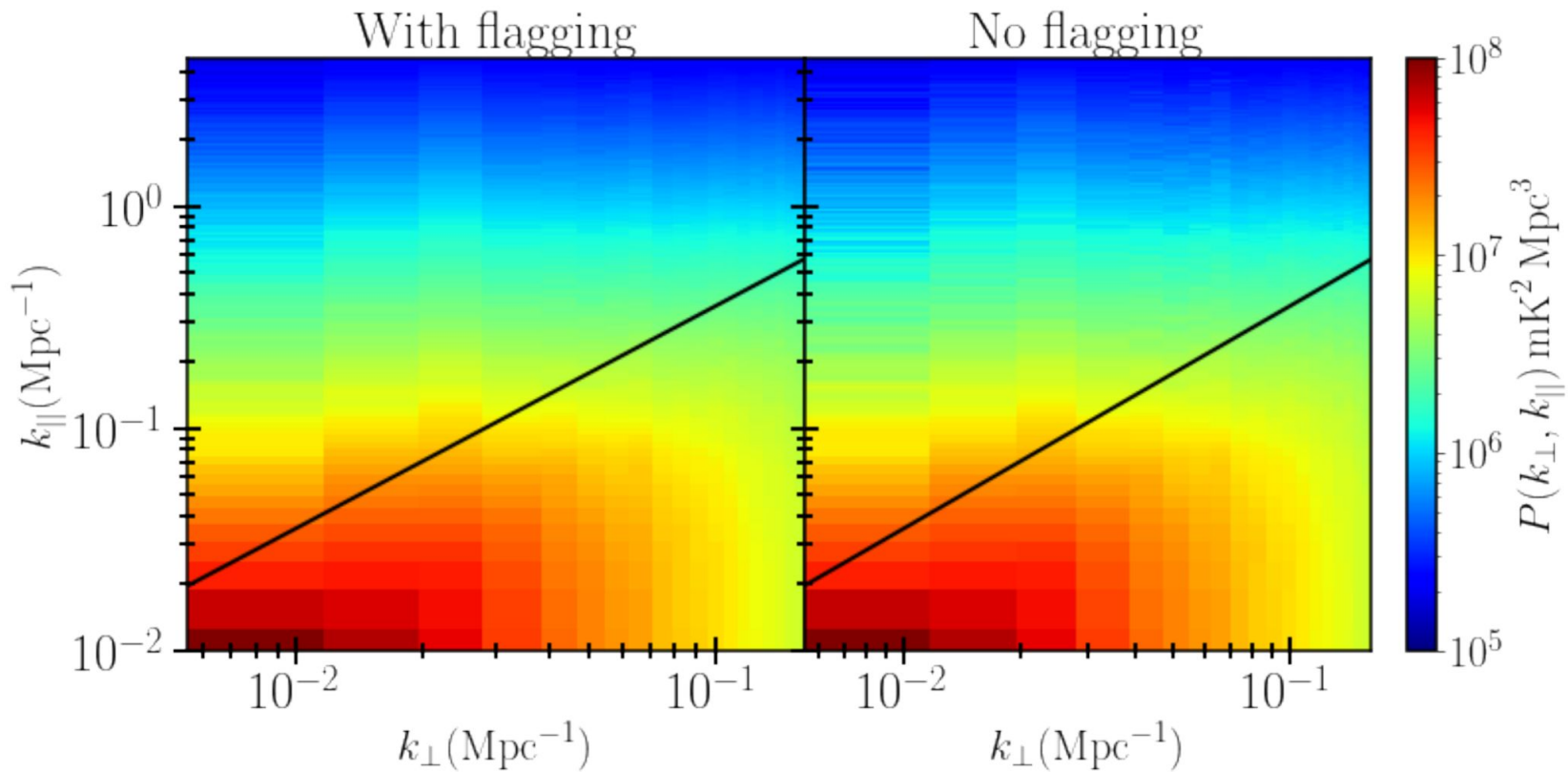
resolution of $\Delta\nu_c = 40$ kHz (BW = 30.72 MHz)

This is further divided into 24 coarse bands each containing 32 channels or 1.28 MHz

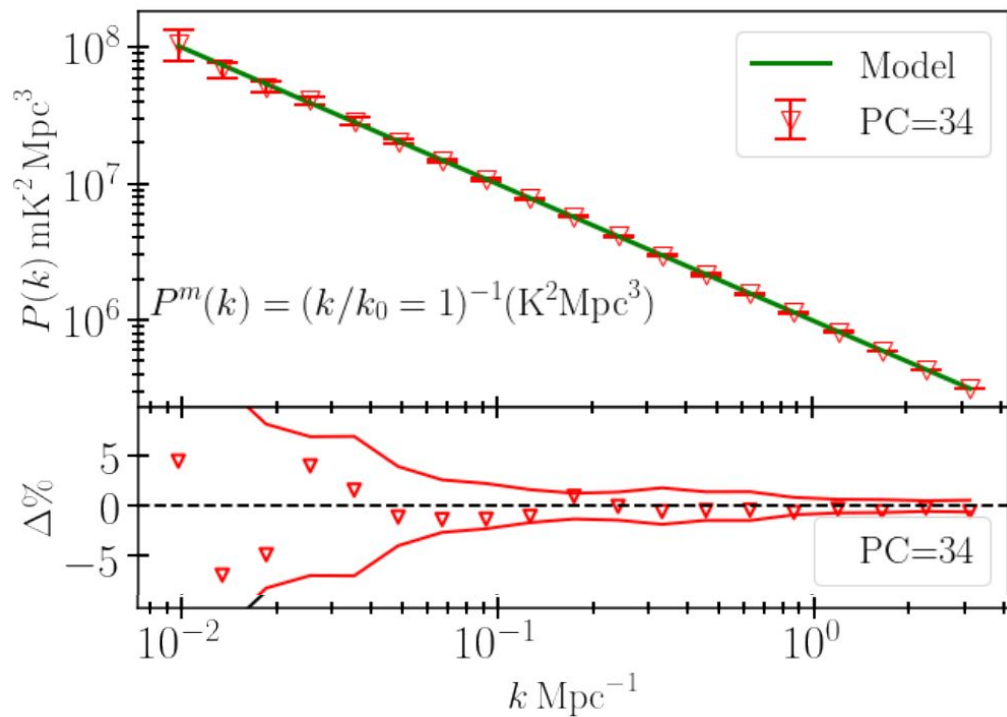
Results: Validation



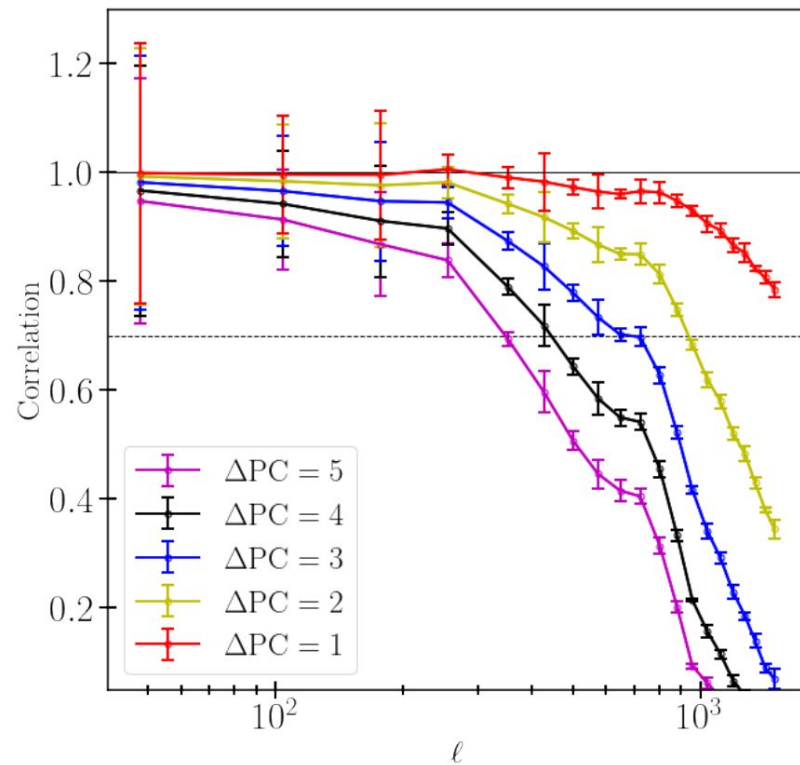
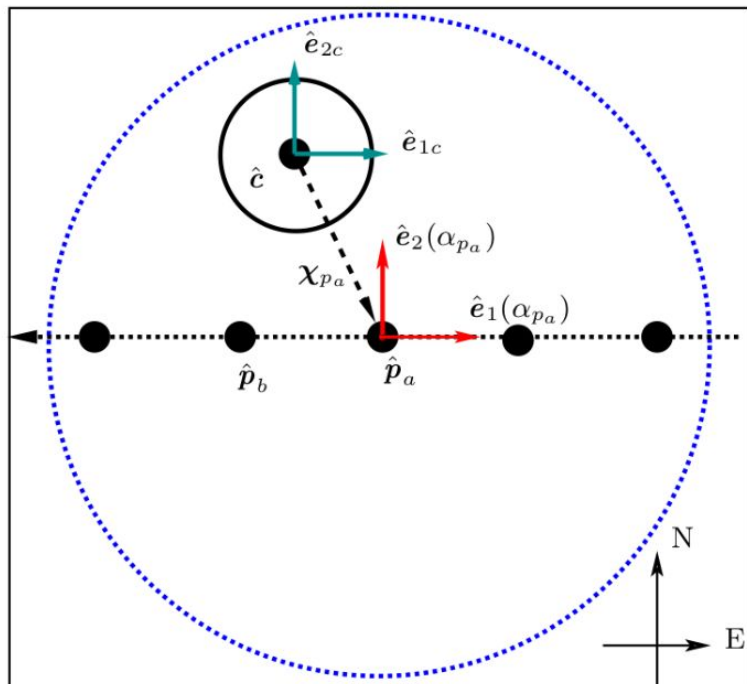
Results: Validation



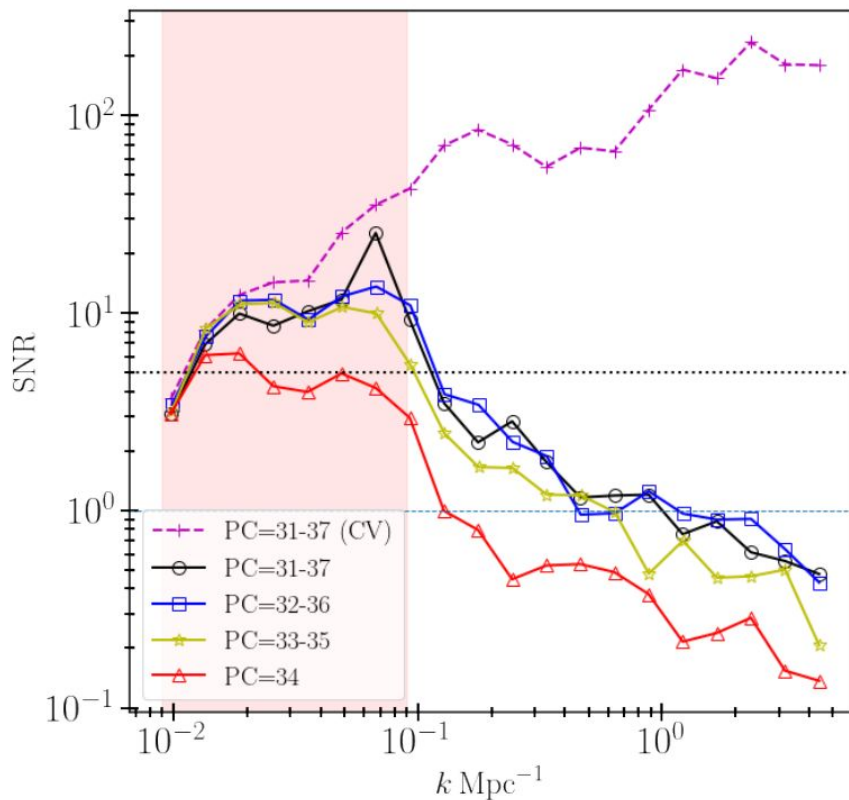
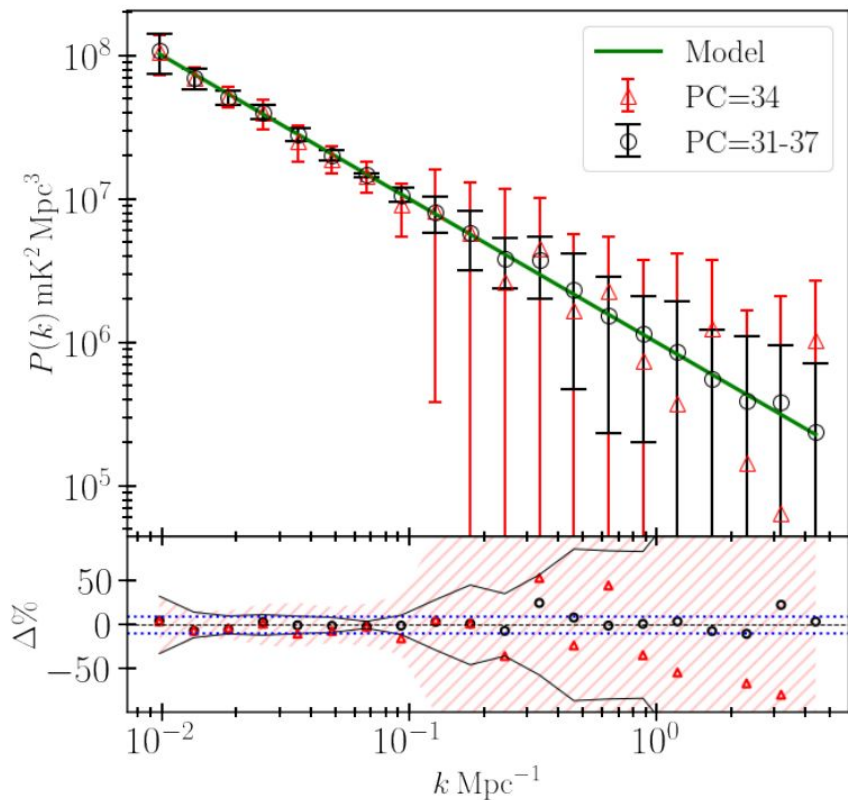
Results: Validation



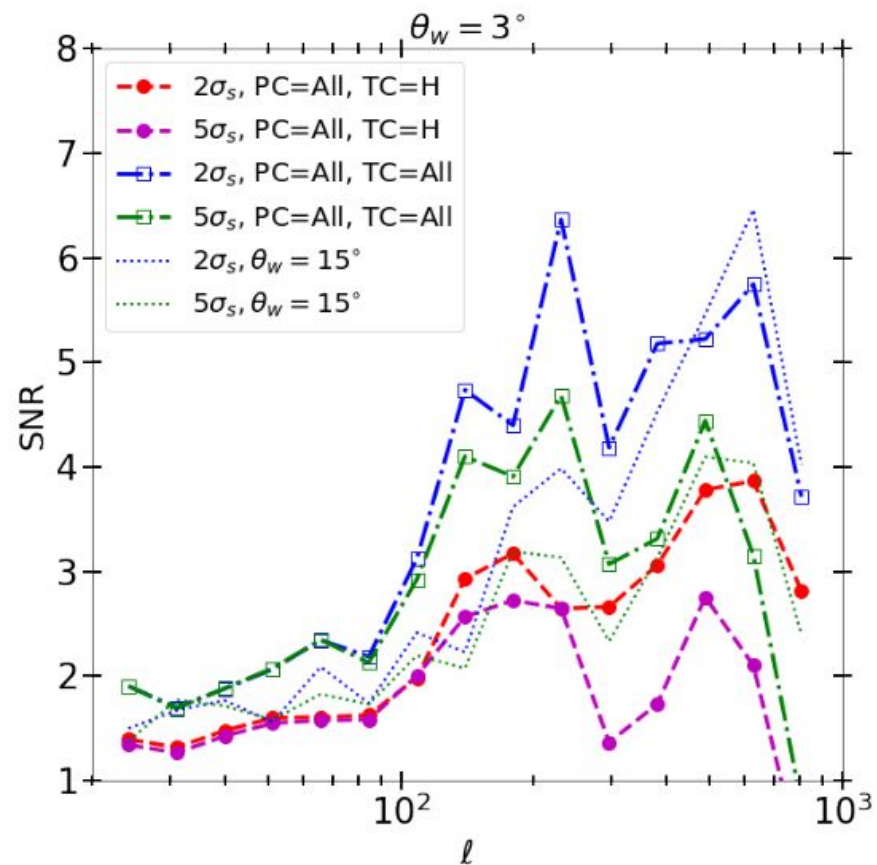
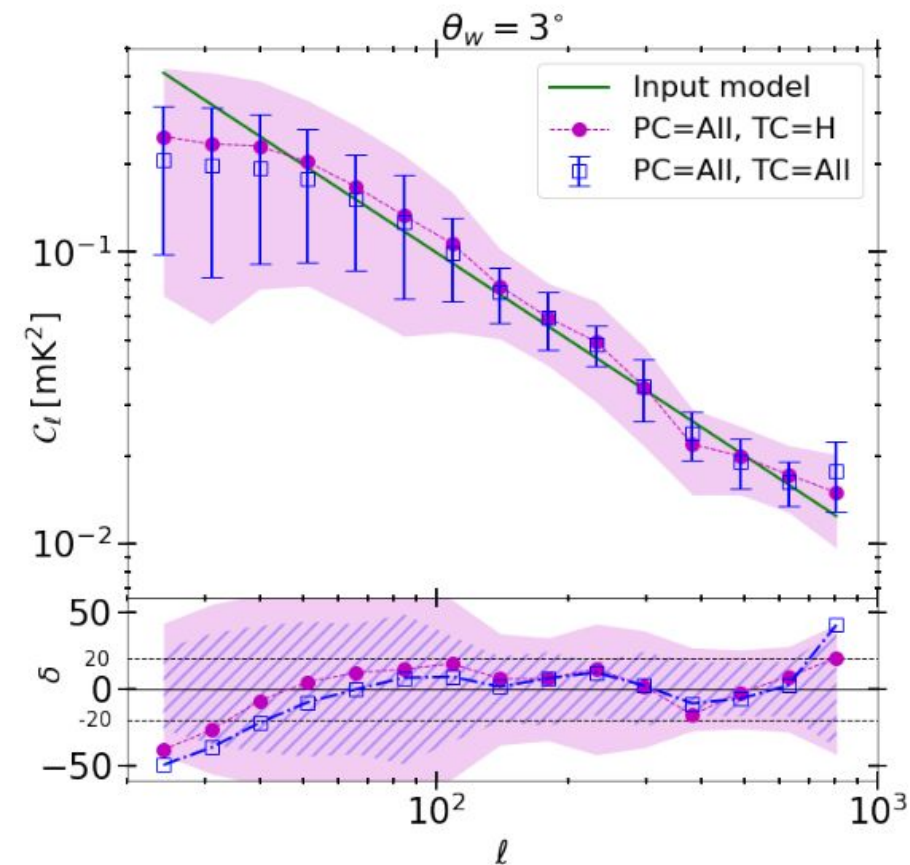
Results: Simulation



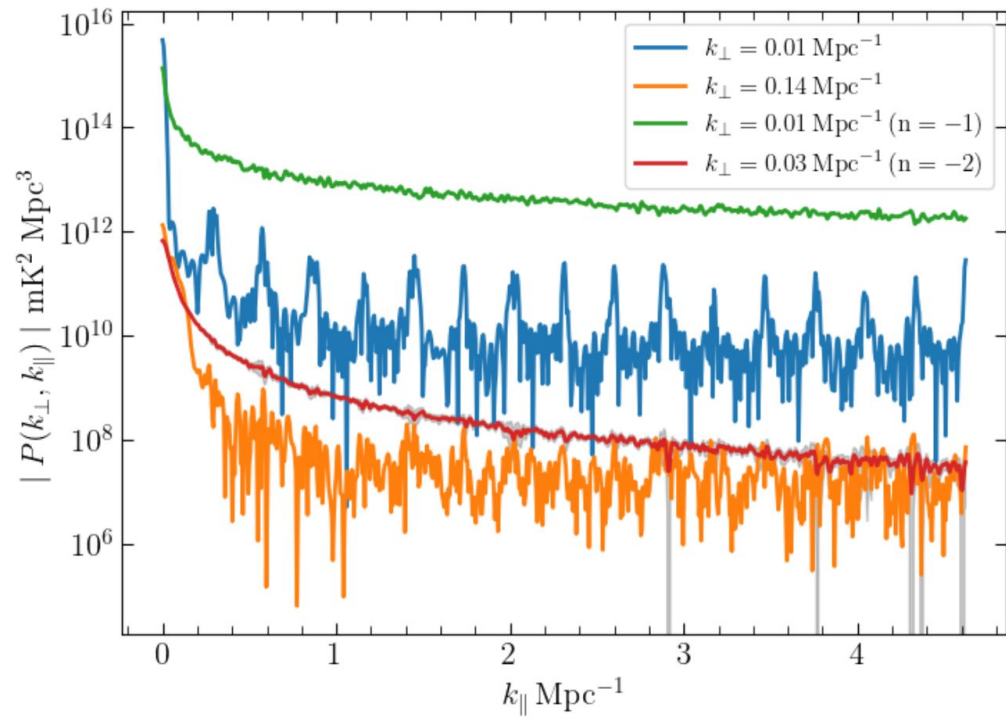
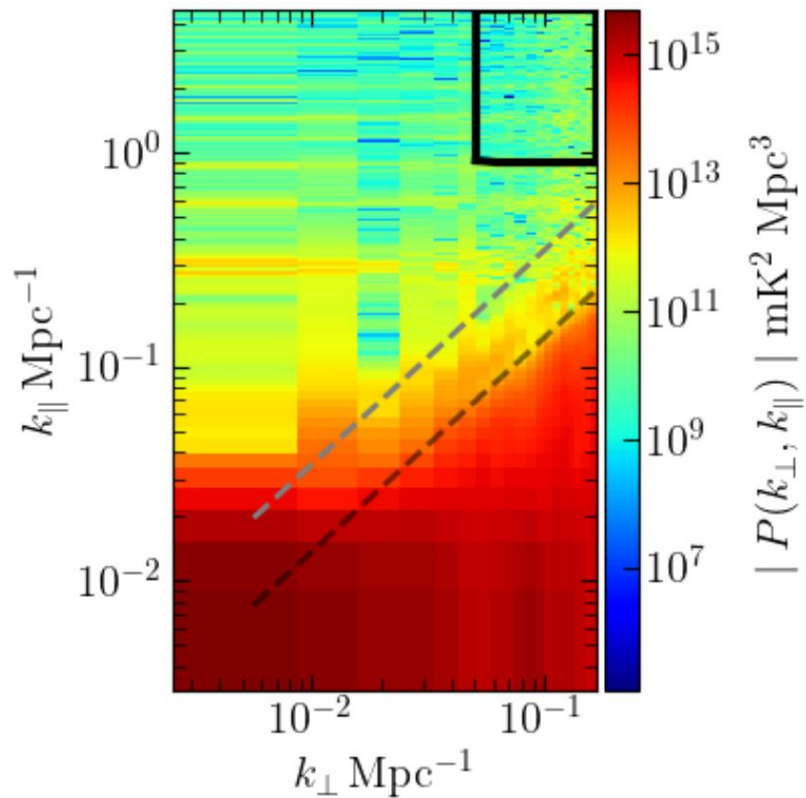
Results: Simulation



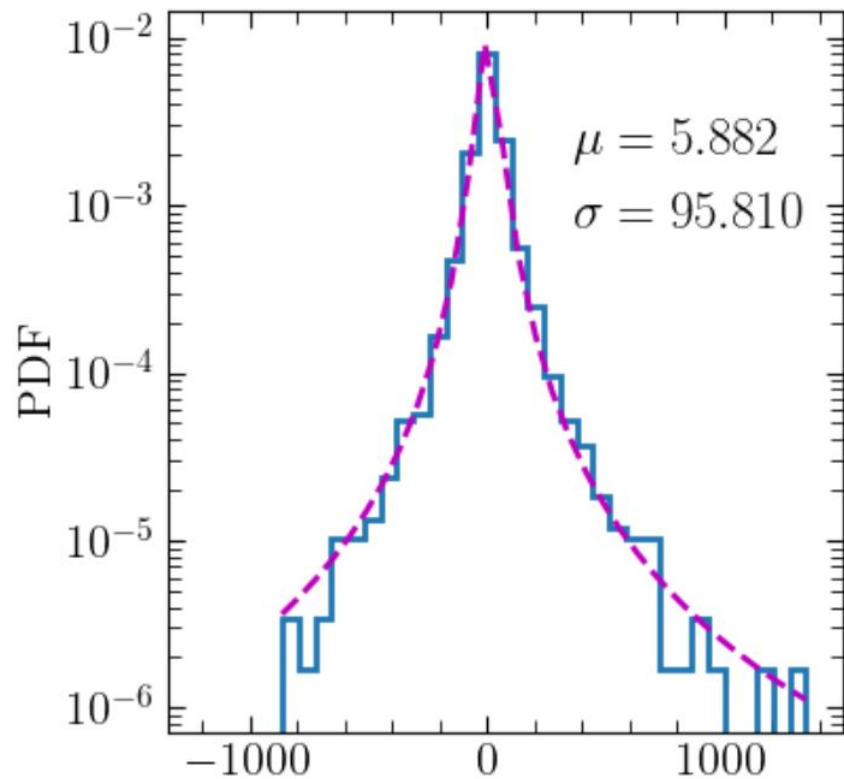
Results: Simulation



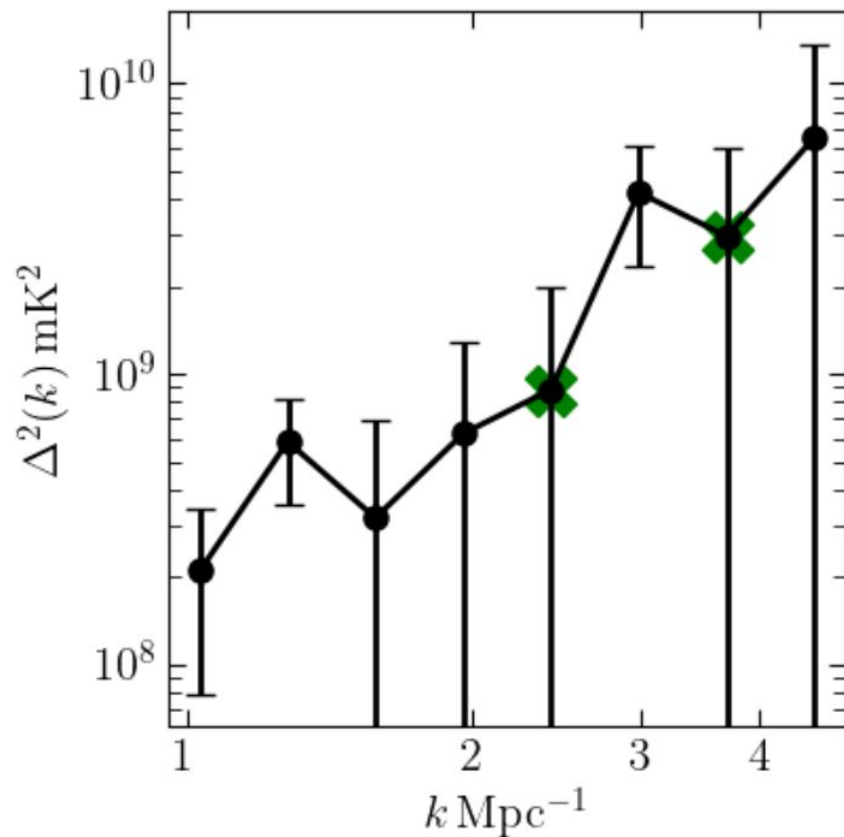
Results: Data



Results

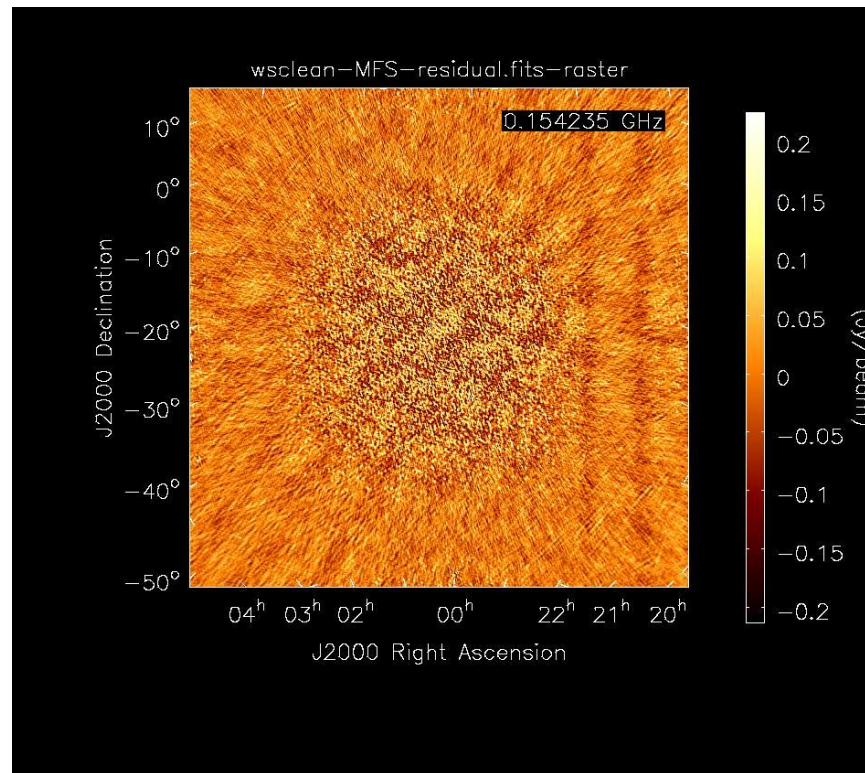
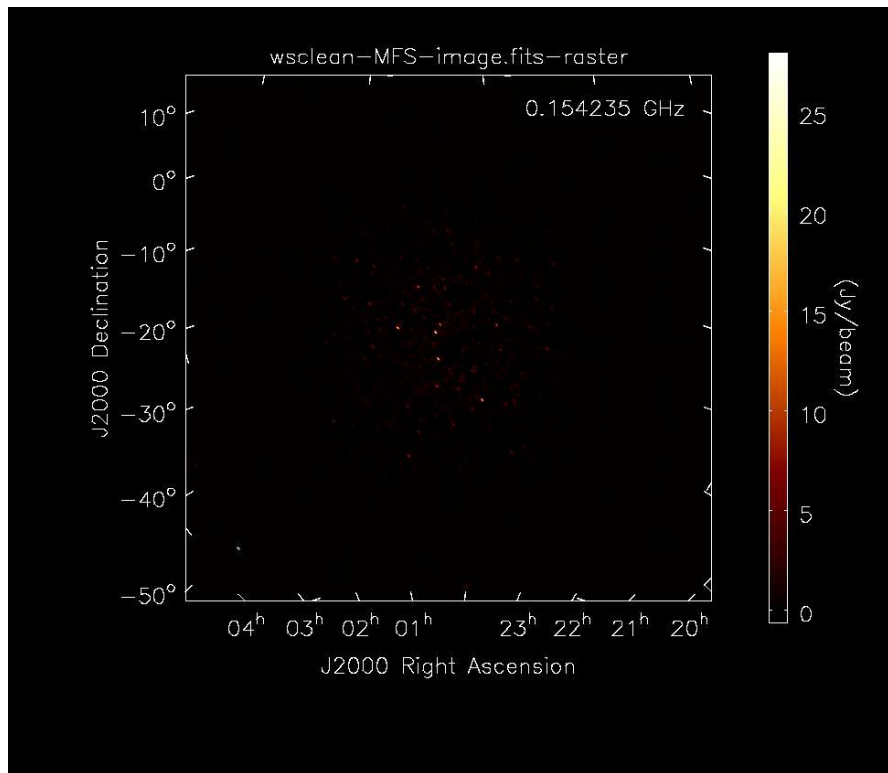


$$X = \frac{P(k_{\perp}, k_{\parallel})}{\delta P_N(k_{\perp}, k_{\parallel})}$$

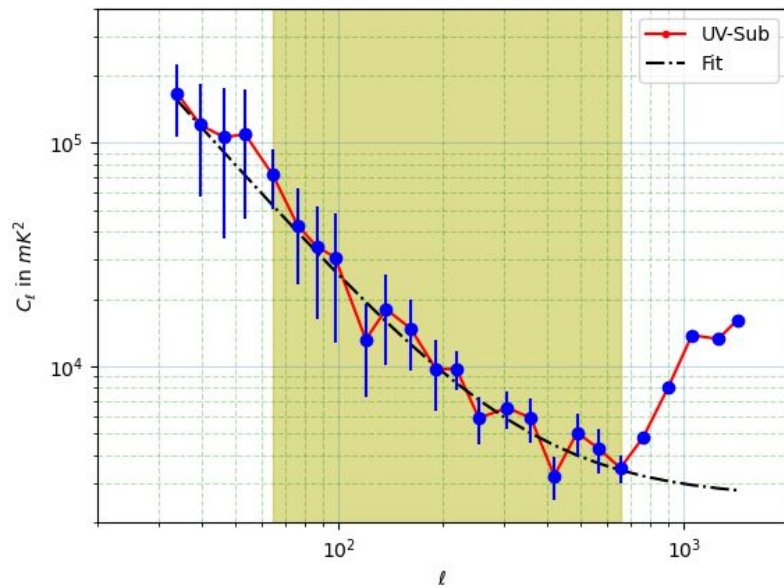
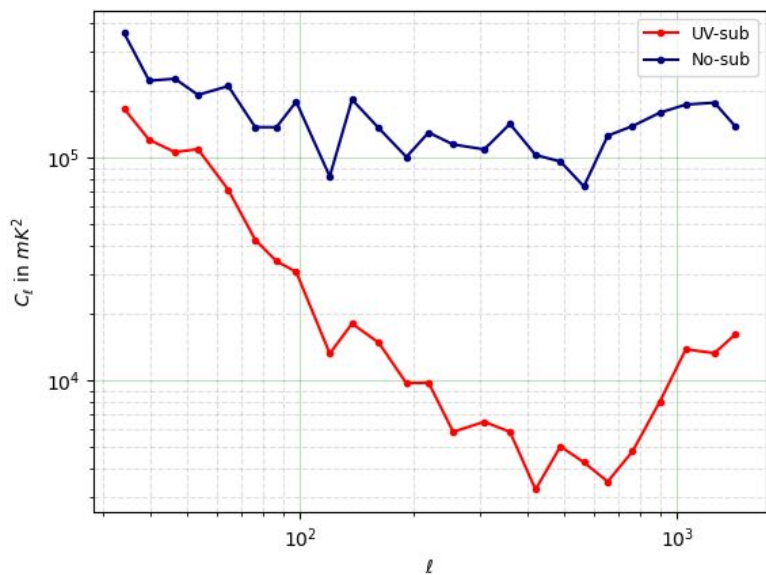


$$\Delta^2(\tilde{k}) < (1.85 \times 10^4)^2 \text{ mK}^2 \quad k = 1 \text{ Mpc}^{-1}$$

Results

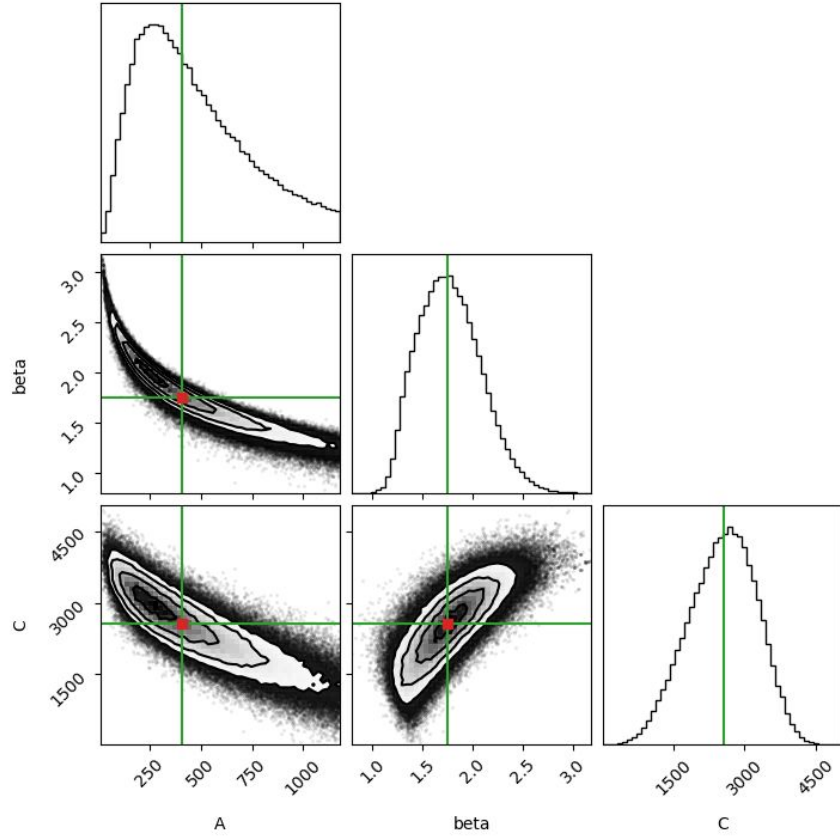


Results



$$C_\ell^M = A \times \left(\frac{1000}{\ell} \right)^\beta + C$$

Results



Summary

- We have developed a novel estimator tracking TGE for the drift scan radio observation.
- We combined different pointing and tracking centres to increase the SNR.
- We validated using MWA simulation with real flagging pattern.
- We applied in a small MWA drift scan data set to get an upper limit.

Thank You

MWA Observation

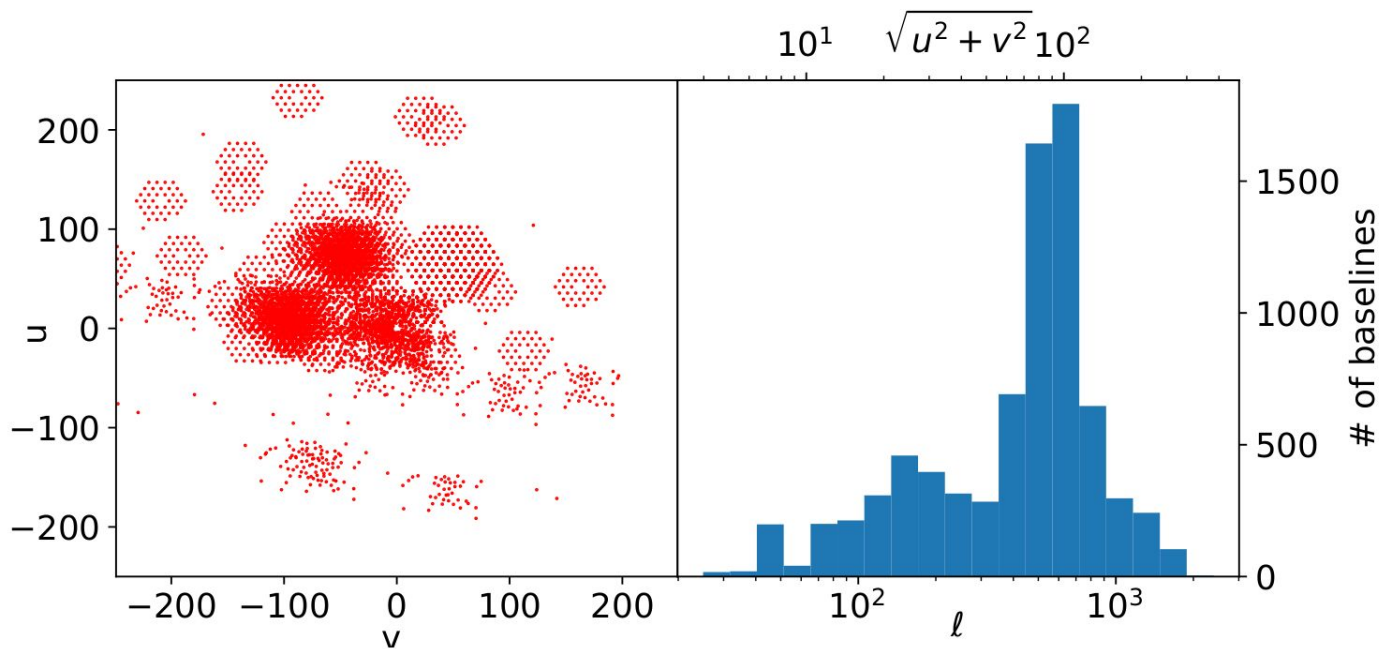
frequency bands ranging from 80 MHz to 300 MHz.

time resolution 0.5 s

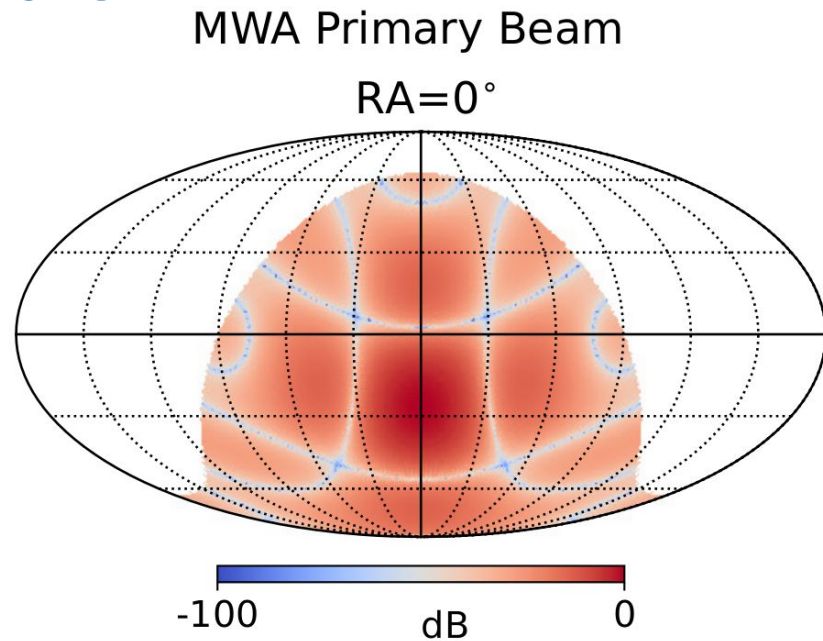
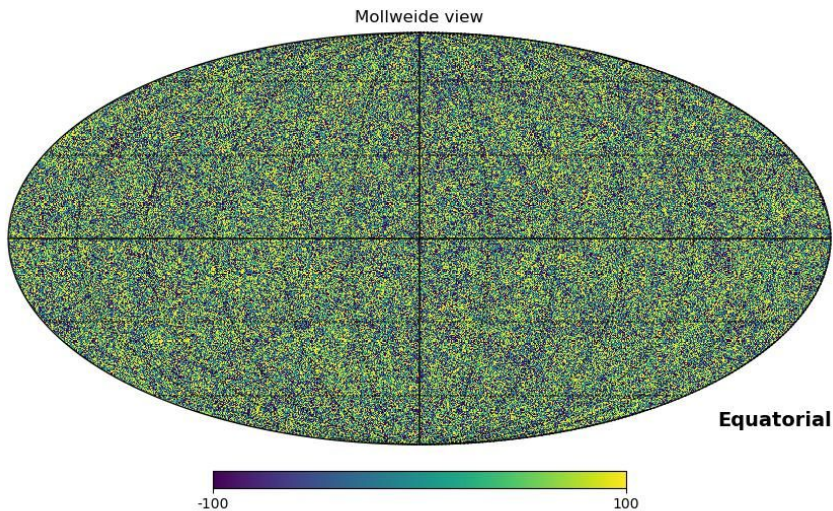
right ascension (RA) 349° to 70.3°

time duration of 5 hr 24 min.

Validation



Validation



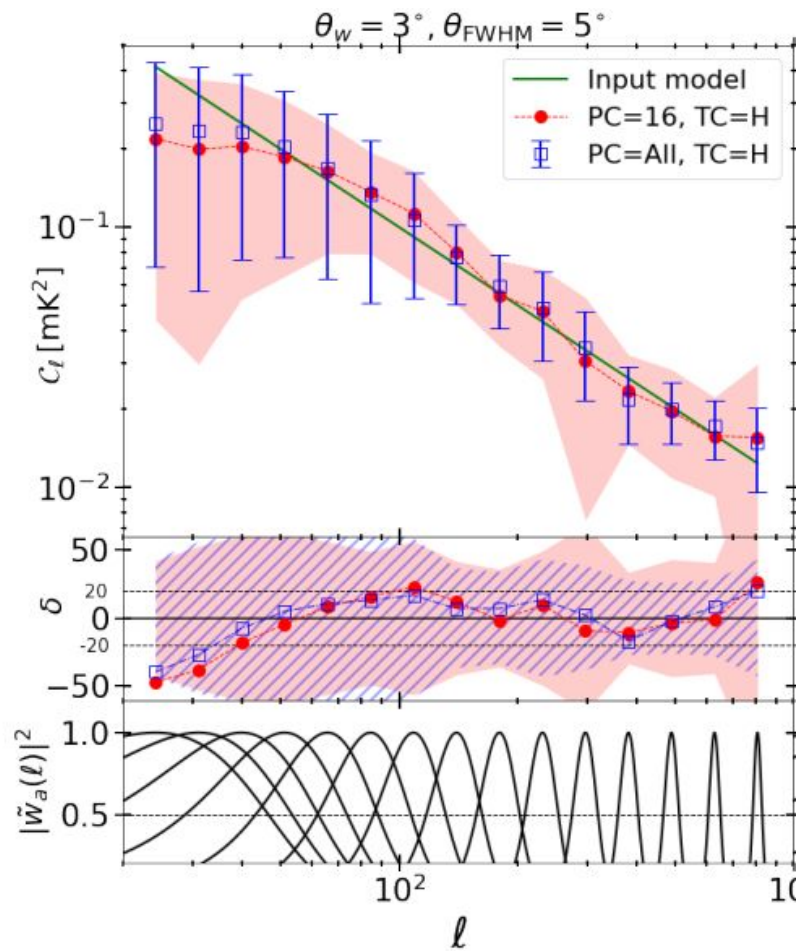
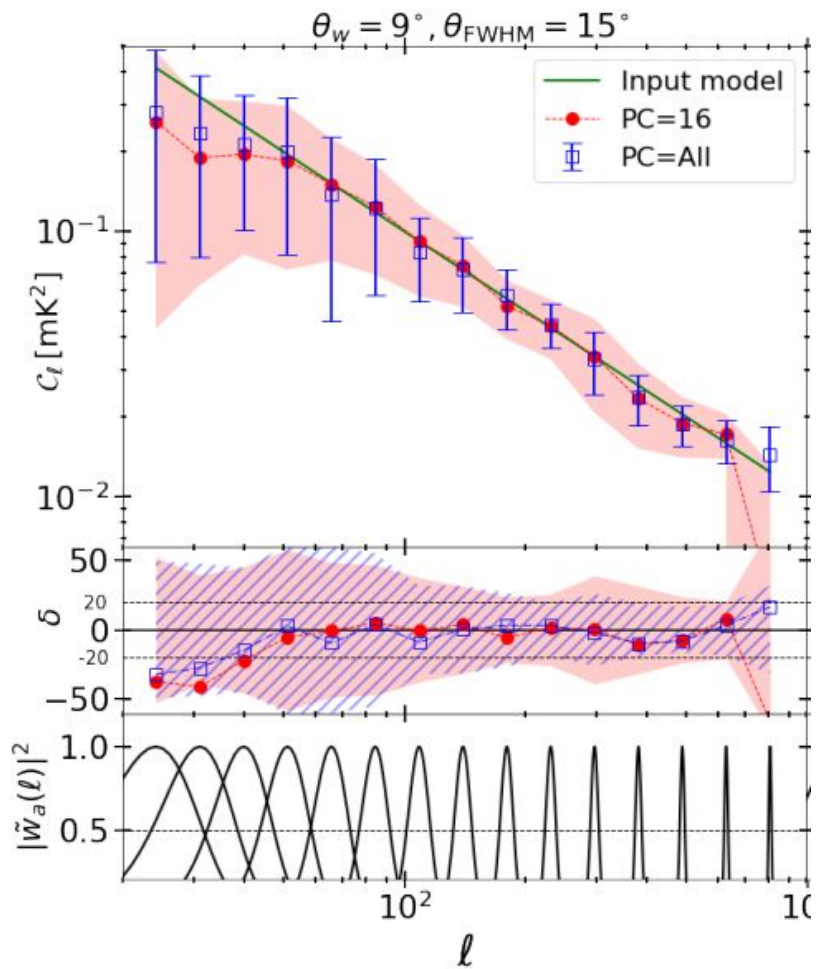
$$C_\ell^M = A \left(\frac{\ell}{\ell_0} \right)^n$$

$$A(\Delta \mathbf{n}, \nu) = \text{sinc}^2 \left(\frac{\pi b \nu \Delta \mathbf{n} \cdot \hat{\mathbf{e}}_1(\alpha_p)}{c} \right) \text{sinc}^2 \left(\frac{\pi b \nu \Delta \mathbf{n} \cdot \hat{\mathbf{e}}_2(\alpha_p)}{c} \right)$$

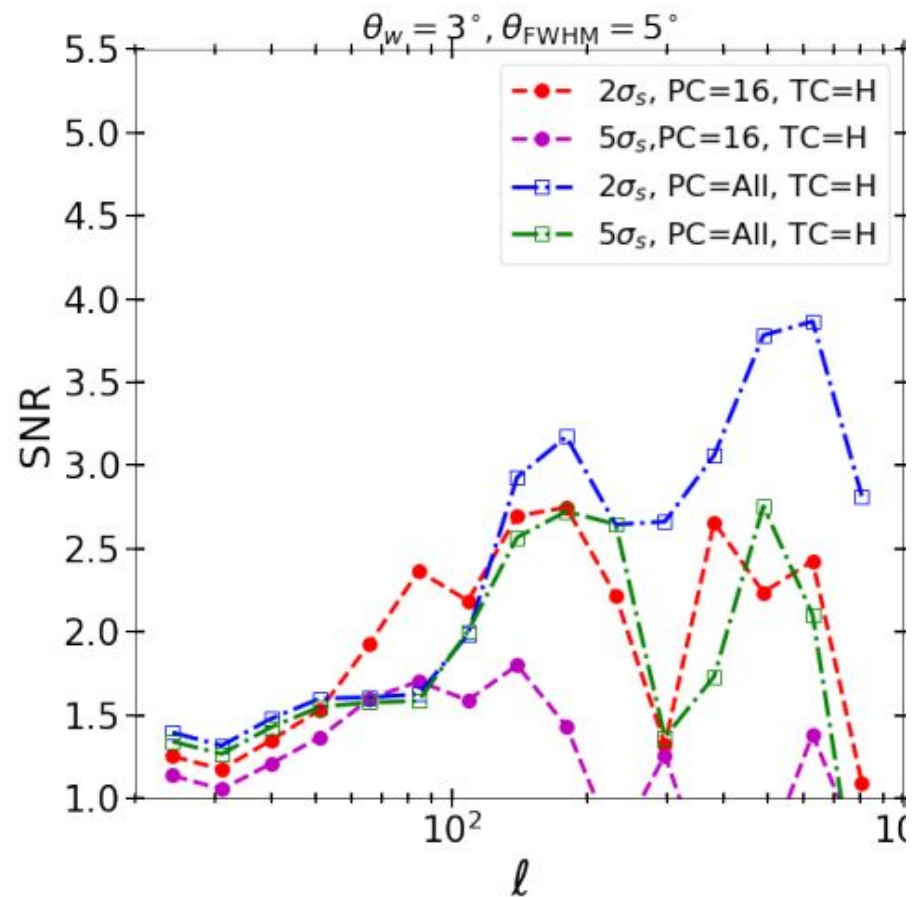
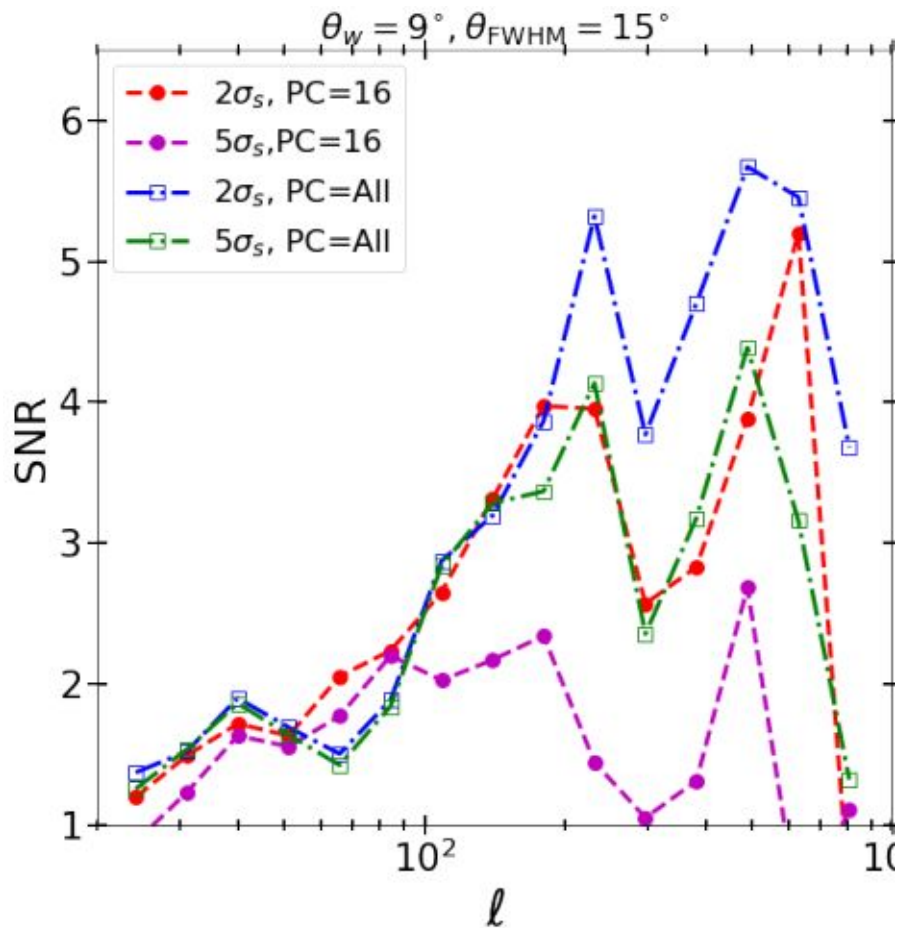
$$A = 10 \text{ mK}^2 \text{ at } \ell = \ell_0 = 1$$

$$n = -1$$

Results



Results



Results

