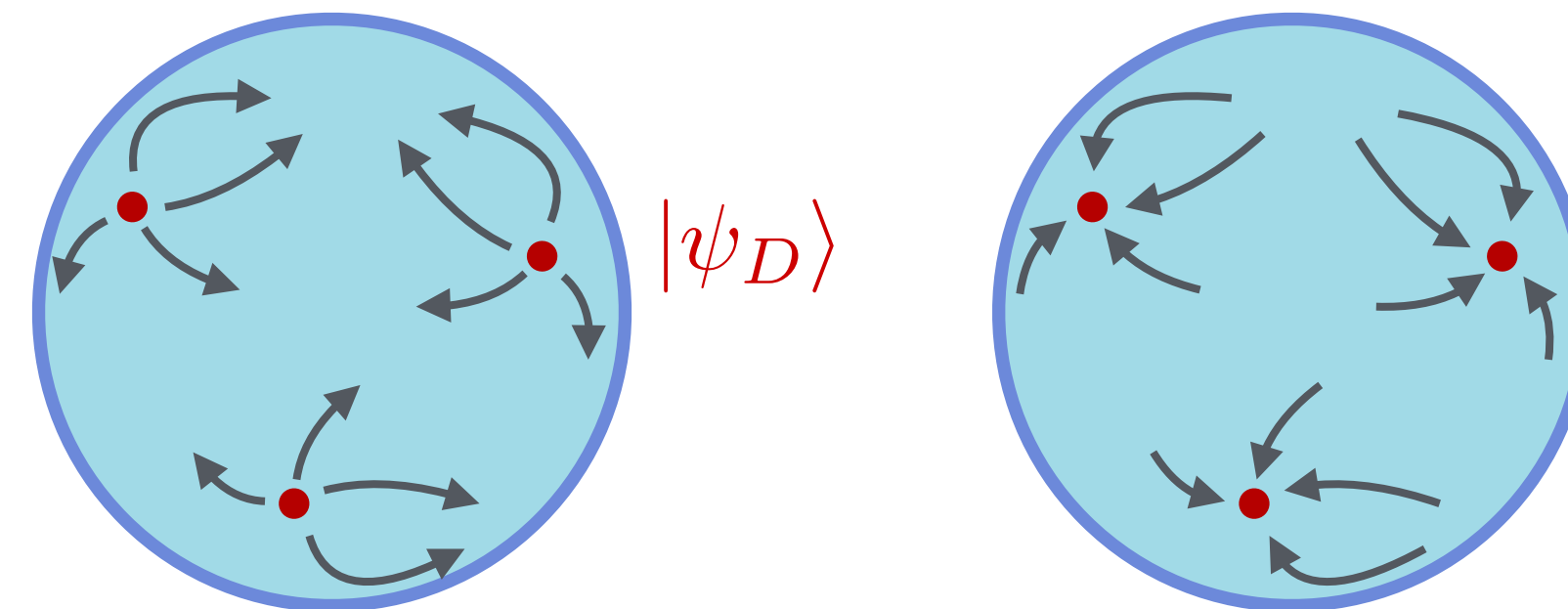
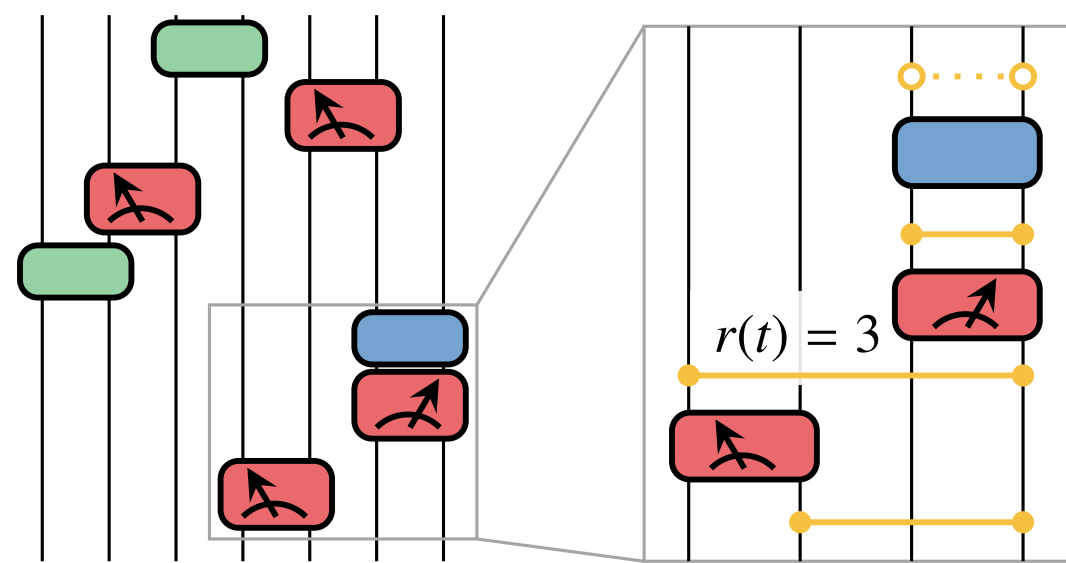


Entangled Attractors

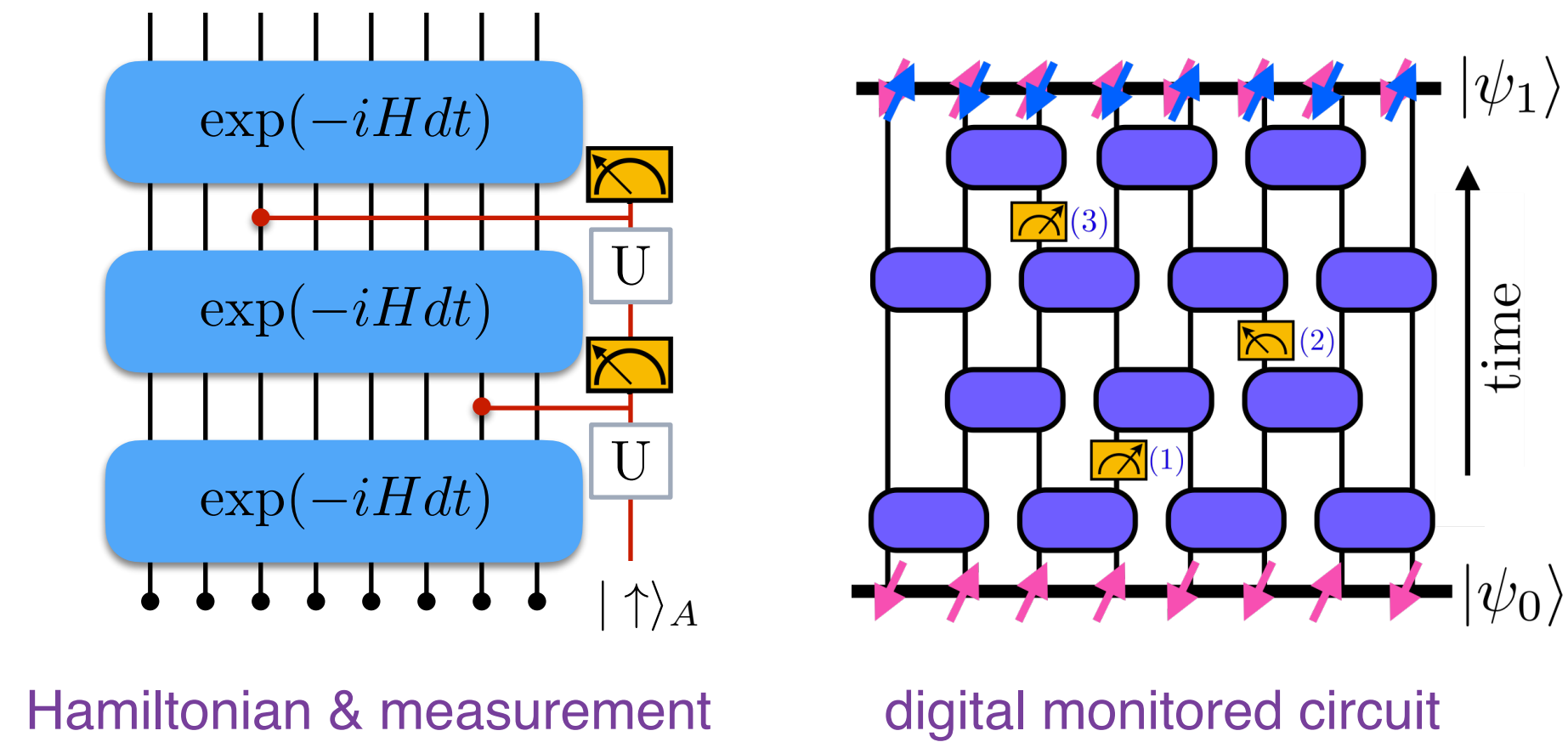
From Frustration-Free Control to Absorbing Scar States



Michael Buchhold, Universität Innsbruck
in collaboration with T. Dörstel, T.C. Lang, T. Iadecola, J.H. Wilson

Motivation

midcircuit measurement

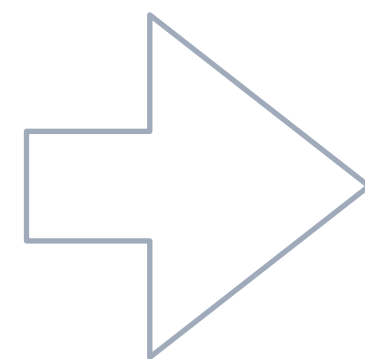


measure ,on-the-fly' — experiment continues

neutral atoms — photonics — trapped ions — SC circuits

monitored quantum many-body physics

- unitary evolution
- non-unitary evolution



monitored matter

- robustness — phases & transitions
- universality
- classification

Measurement as a dynamical resource

gain information

local projective / weak measurement

$$|\psi\rangle \rightarrow \lambda$$

collapse wave function

project onto eigenspace

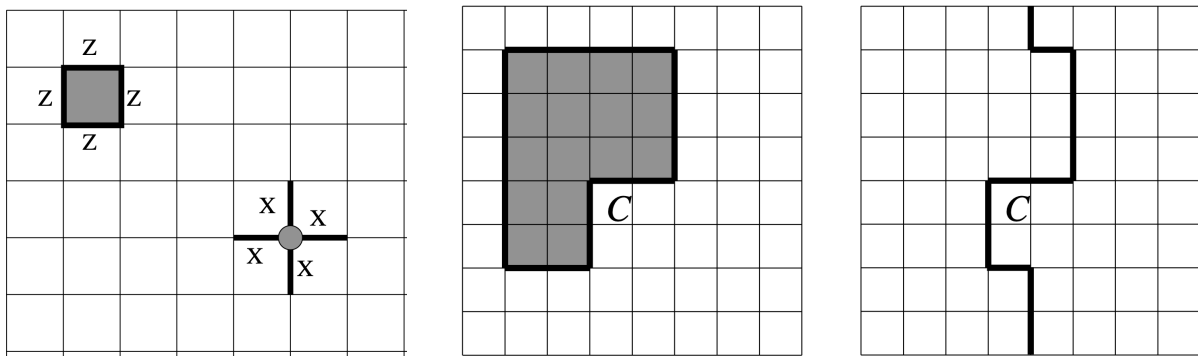
$$|\psi\rangle \rightarrow \lambda \rightarrow \hat{P}_\lambda |\psi\rangle$$

adaptive feedback

unitary conditioned on outcome

$$|\psi\rangle \rightarrow \lambda \rightarrow \hat{U}_\lambda \hat{P}_\lambda |\psi\rangle$$

quantum error correction

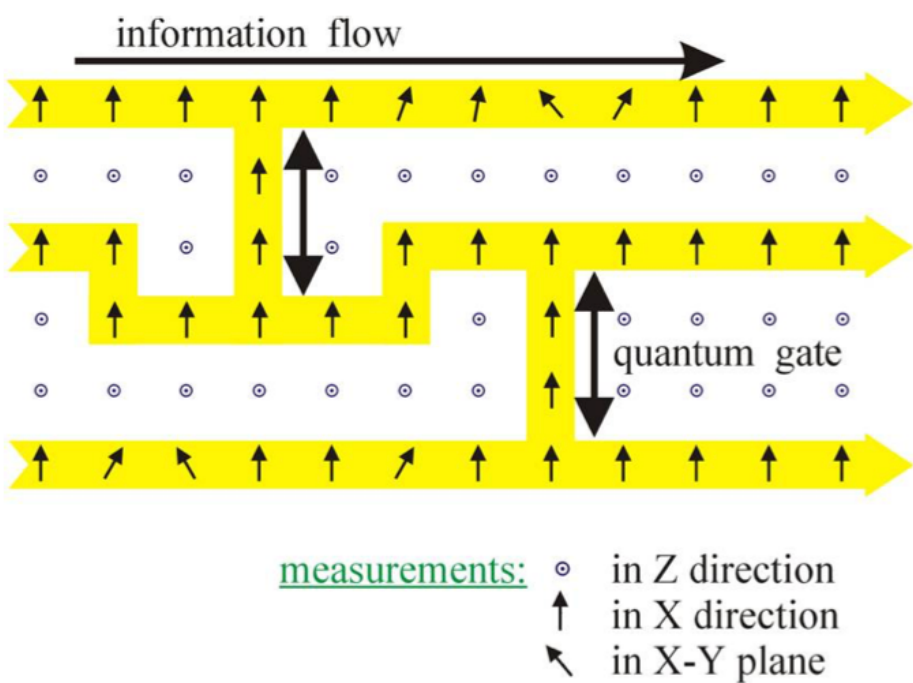


surface code:

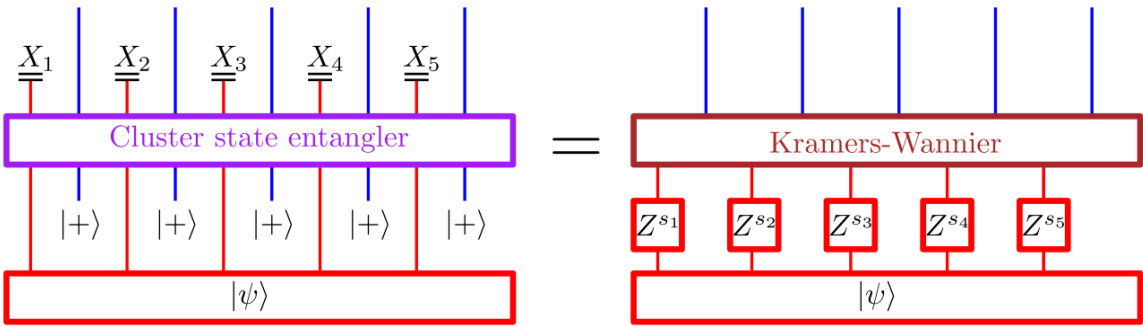
Dennis, Kitaev, Landahl, Preskill, J. Math. Phys. 2002

measurement-based QC

Raussendorf, Briegel
PRL 2001
Briegel et al. Nature
Physics 2009



state preparation



Pirolì, Styliaris, Cirac, PRL 2021
Tantivasdakarn et al. PRX 2024
Iqbal et al. (Quantinuum) Nature 2024
Chen et al (IBM) Nature Physics 2024

State preparation as an absorbing state problem

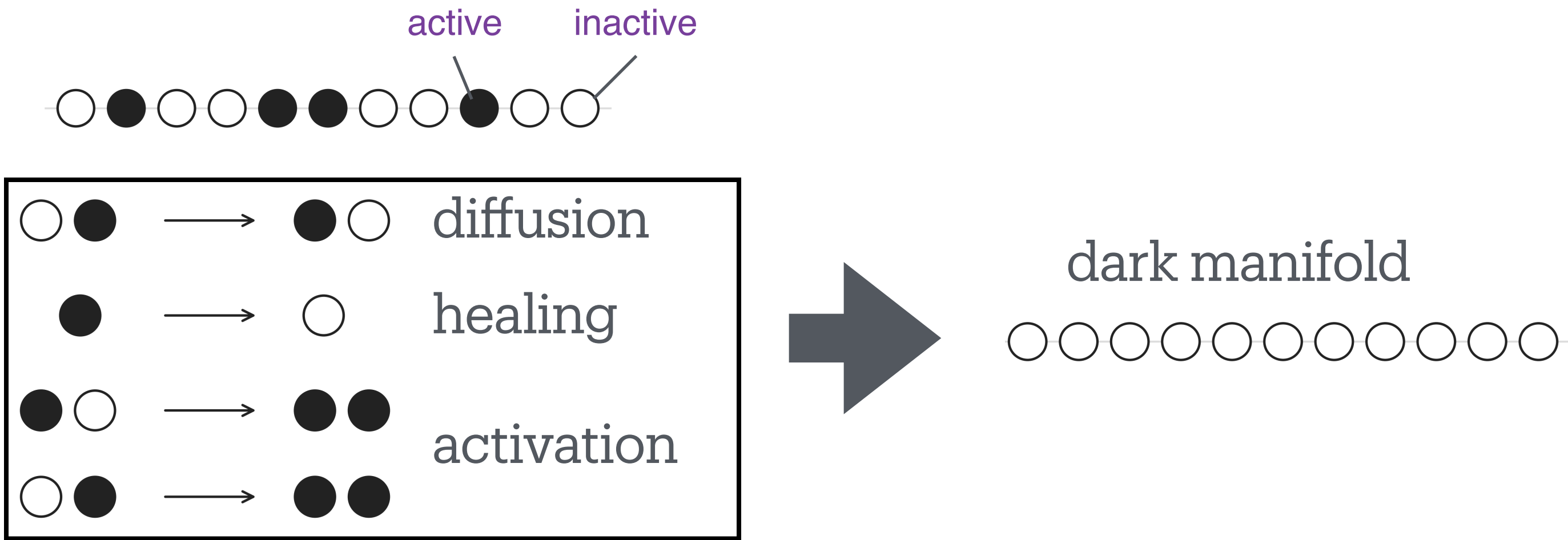
Markov dynamics & absorbing state

once entered cannot be left

paradigmatic example:

contact process / directed percolation

Janssen, Z. Phys. B (1981), Grassberger, Z. Phys. B (1982)
Hinrichsen, Advances in Physics (2000)



translate to state preparation

(how) is the dark manifold reached?

projectors $\hat{P}_\ell^2 = \hat{P}_\ell$

dark manifold $\hat{P}_\ell |\psi_D\rangle = 0$

example: GS of frustration free Hamiltonian

healing as measurement-feedback dynamics

$$\hat{P}_\ell = \begin{cases} 1 & \text{active} \\ 0 & \text{inactive} \end{cases}$$

local rotation to target $\hat{V}_\ell$

leave unchanged

$$\hat{H} = \sum_\ell \hat{P}_\ell$$

e.g., Ferromagnetic Heisenberg, AKLT, Toric Code, Cluster State

feedback condition $[\hat{V}_\ell, \hat{P}_\ell] \neq 0$

Dörstel, Iadecola, Wilson, MB, PRL (2026)
Feldmeier, Liu, Lukin, Choi, arXiv (2026)

State preparation as an absorbing state problem

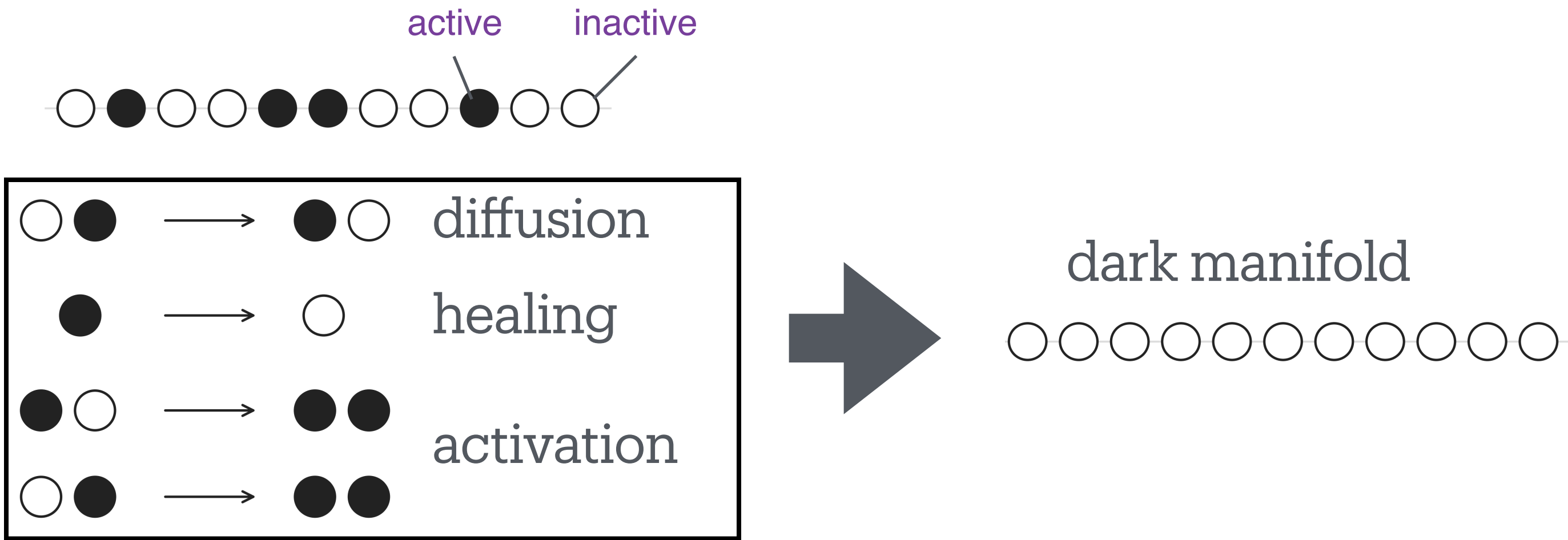
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Dörstel, Iadecola, Wilson, MB, PRL (2026)
Feldmeier, Liu, Lukin, Choi, arXiv (2026)

quantum channel

$$\hat{\rho} \mapsto \hat{K}_{\ell,0}\hat{\rho}\hat{K}_{\ell,0}^\dagger + \hat{K}_{\ell,1}\hat{\rho}\hat{K}_{\ell,1}^\dagger$$

$$\begin{aligned} \hat{K}_{\ell,0} &= \mathbb{I} - \hat{P}_\ell \\ \hat{K}_{\ell,1} &= \hat{V}_\ell \hat{P}_\ell \end{aligned}$$

non-unital

$$\hat{\rho}_D = |\psi_D\rangle\langle\psi_D| \mapsto \hat{\rho}_D$$

Defect detection & annihilation as nonlocal dynamics

so far: target = absorbing
entangled states $\neq$ product states

defects are nonlocal
feedback acts nonlocal

$[\hat{P}_{\ell'}, \hat{P}_{\ell}] \neq 0$
 $[\hat{P}_{\ell'}, \hat{V}_{\ell}] \neq 0$

singlets
singlets / cluster state

example: Dicke states from singlet constraints

$$\vec{J}^2 |\psi_D^Z\rangle = \frac{L(L+2)}{4} |\psi_D^Z\rangle$$

maximum total angular momentum

$$\hat{Z}_{\text{tot}} |\psi_D^Z\rangle = Z |\psi_D^Z\rangle$$

total-Z magnetization

$$S_{L/2}(Z=0) = \frac{1}{2} \log(L) + \mathcal{O}(1)$$

half-chain entanglement

$$\hat{P}_{n,m} = \frac{1}{4} [\mathbb{I} - \vec{\sigma}_n \cdot \vec{\sigma}_m]$$

singlet

$$\hat{P}_{n,m} |\psi_D\rangle = 0$$

fully symmetric

$$\hat{H}_{\text{FMH}} = J \sum_{\ell} \hat{P}_{\ell, \ell+1}$$

ferromagnetic Heisenberg

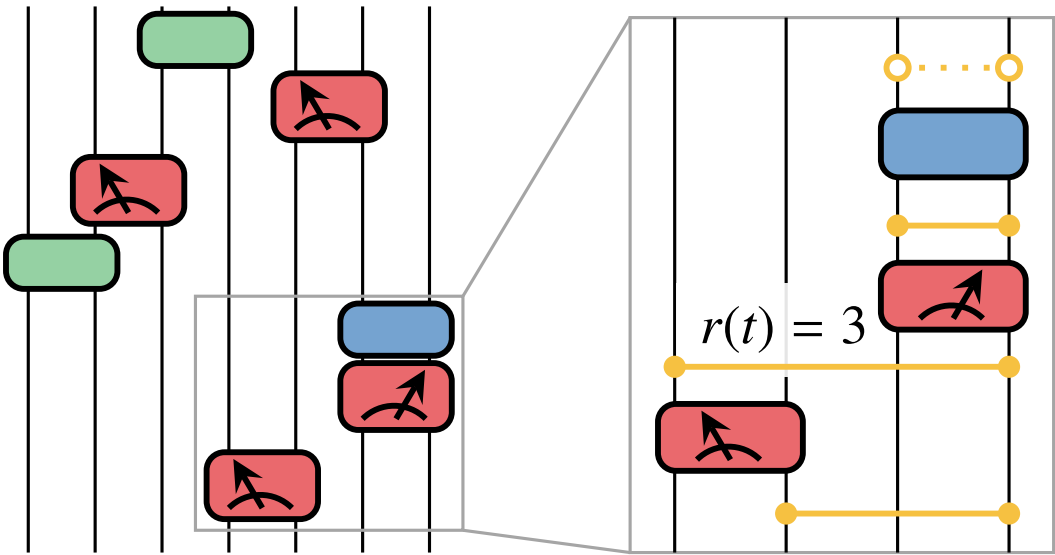
preparation as measurement-feedback dynamics

$$\hat{P}_{\ell, \ell+1} = \begin{cases} 1 & \text{singlet} \\ 0 & \text{triplet} \end{cases}$$

rotate

$$\hat{V}_{\ell, \ell+1} = \hat{Z}_{\ell}$$

$$\frac{|\uparrow\downarrow\rangle - |\downarrow\uparrow\rangle}{\sqrt{2}} \rightarrow \frac{|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle}{\sqrt{2}}$$



Defect detection & annihilation as nonlocal dynamics

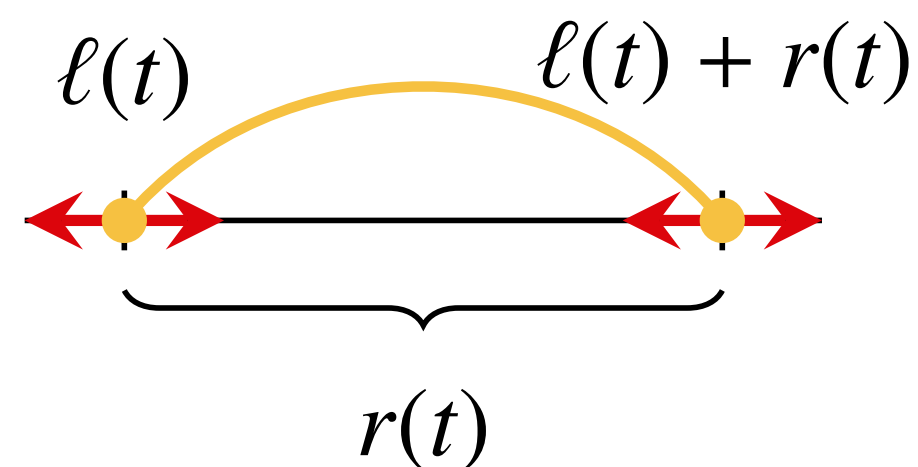
measurement-only — w/o feedback $\partial_t \hat{\rho} = \mathcal{L} \hat{\rho} = - \sum_{\ell} [\hat{P}_{\ell, \ell+1}, [\hat{P}_{\ell, \ell+1}, \hat{\rho}]]$

Dörstel, Iadecola, Wilson, **MB**, PRL (2026)
Li, Pollmann, Read, Sala, PRX (2025)

$[\vec{J}^2, \hat{P}_{n,m}] = 0 \quad \Rightarrow \quad \text{total angular momentum fixes singlet sector}$

$\partial_t \langle \hat{P}_{n,m} \rangle = \text{tr}(\hat{P}_{n,m} \mathcal{L} \hat{\rho}) = \frac{1}{2} \sum_{\ell} D_{n,\ell} \langle \hat{P}_{\ell,m} \rangle + \langle \hat{P}_{n,\ell} \rangle D_{\ell,m}$ random walk of singlet endpoints

lattice Laplace



random walk of singlet center & length

$\hat{\rho} \mapsto \mathbb{I}_J$ uniform distribution of singlet length & center

Feedback adds an absorbing boundary

measurement-feedback

$$\partial_t \hat{\rho} = \mathcal{L} \hat{\rho} = - \sum_{\ell} \left\{ \underbrace{[\hat{P}_{\ell, \ell+1}, [\hat{P}_{\ell, \ell+1}, \hat{\rho}]]}_{\text{dephasing}} + \underbrace{[\hat{P}_{\ell, \ell+1} \hat{\rho} \hat{P}_{\ell, \ell+1}, \hat{V}_{\ell}] \hat{V}_{\ell}^{\dagger}}_{\text{feedback}} \right\}$$

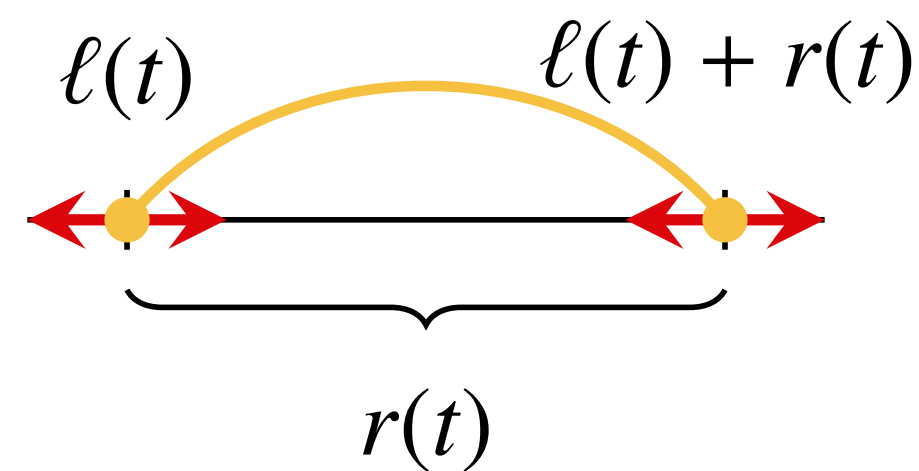
$$\partial_t \langle \hat{P}_{n, m} \rangle = \text{tr}(\hat{P}_{n, m} \mathcal{L} \hat{\rho}) = \frac{1}{2} \sum_{\ell} D_{n, \ell} \langle \hat{P}_{\ell, m} \rangle + \langle \hat{P}_{n, \ell} \rangle D_{\ell, m} - \lambda \langle \hat{P}_{n, m} \rangle \delta_{n, m \pm 1}$$

lattice Laplace

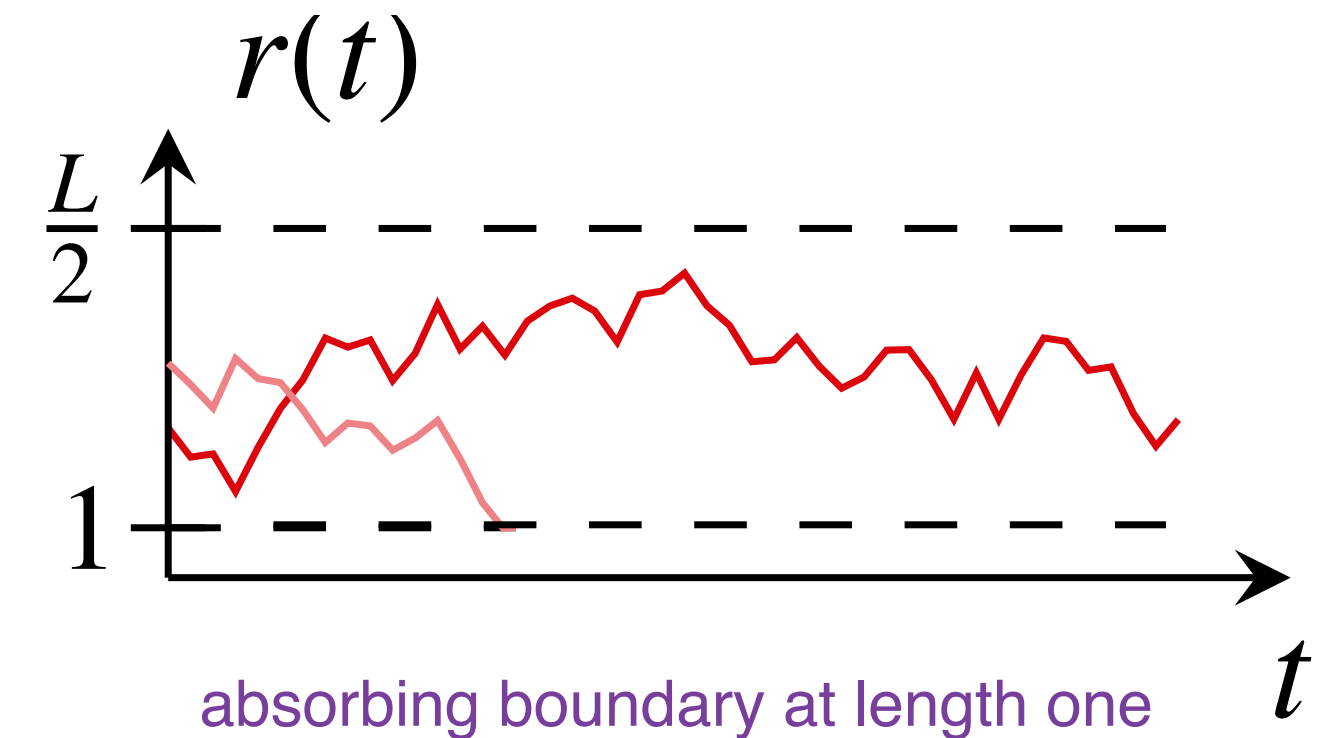
annihilation of singlets
with length one

linear absorbing hydrodynamics $\partial_t \mathcal{P} = M \mathcal{P}$

Dörstel, Iadecola, Wilson, MB, PRL (2026)



annihilation random walk of singlet lengths

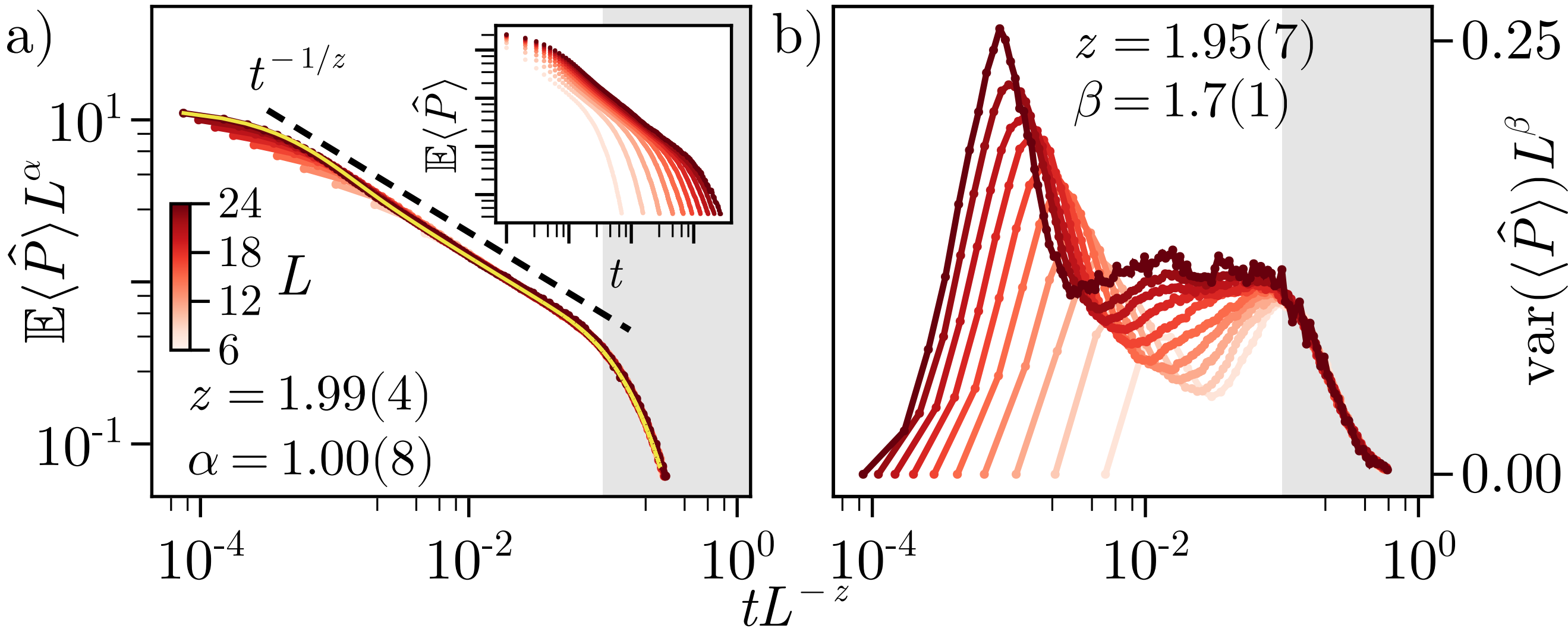


Convergence is an annihilation random walk

time governed by diffusive transport

d=1: $\mathbb{E}(\langle \hat{P} \rangle) \sim \begin{cases} t^{-1/2} & \text{for } t < L^2 \\ \exp(-tL^{-2}) & \text{for } t > L^2 \end{cases}$

number of singlets



preparation time = number of measurements / qubit

$t_{\text{prep}}(L) \sim \begin{cases} L^{2d} & \text{for } d = 1 \\ L^d \log(L) & \text{for } d = 2 \\ L^d & \text{for } d \geq 3 \end{cases}$

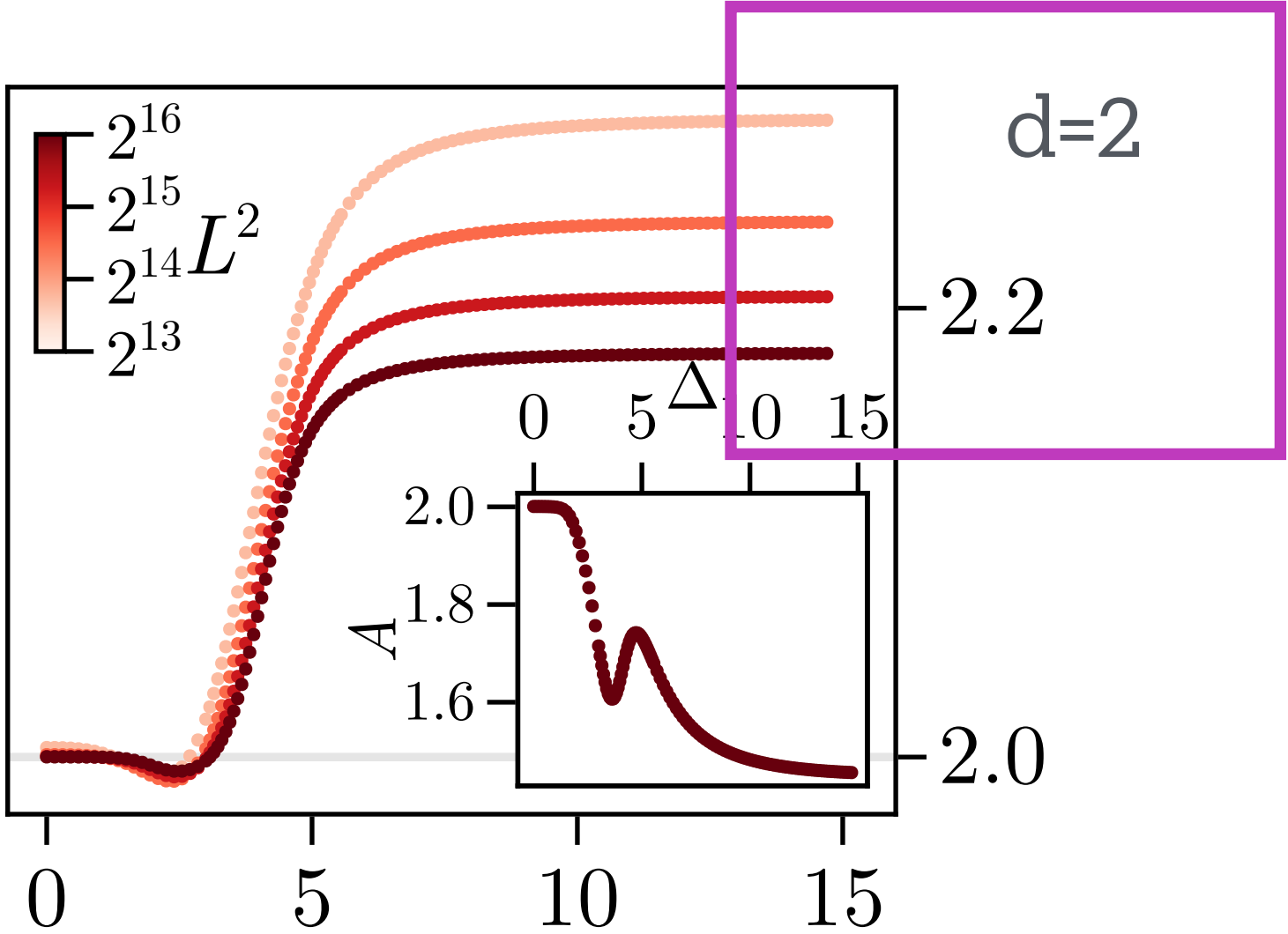
linear dimension

diffusion

mean-field

Dörstel, Iadecola, Wilson, MB, PRL (2026)
Feldmeier, Liu, Lukin, Choi, arXiv (2026)
Hauser, Li, Vijay, Fisher, PRB (2024)

diffusion limited annihilation



Speedup through transport

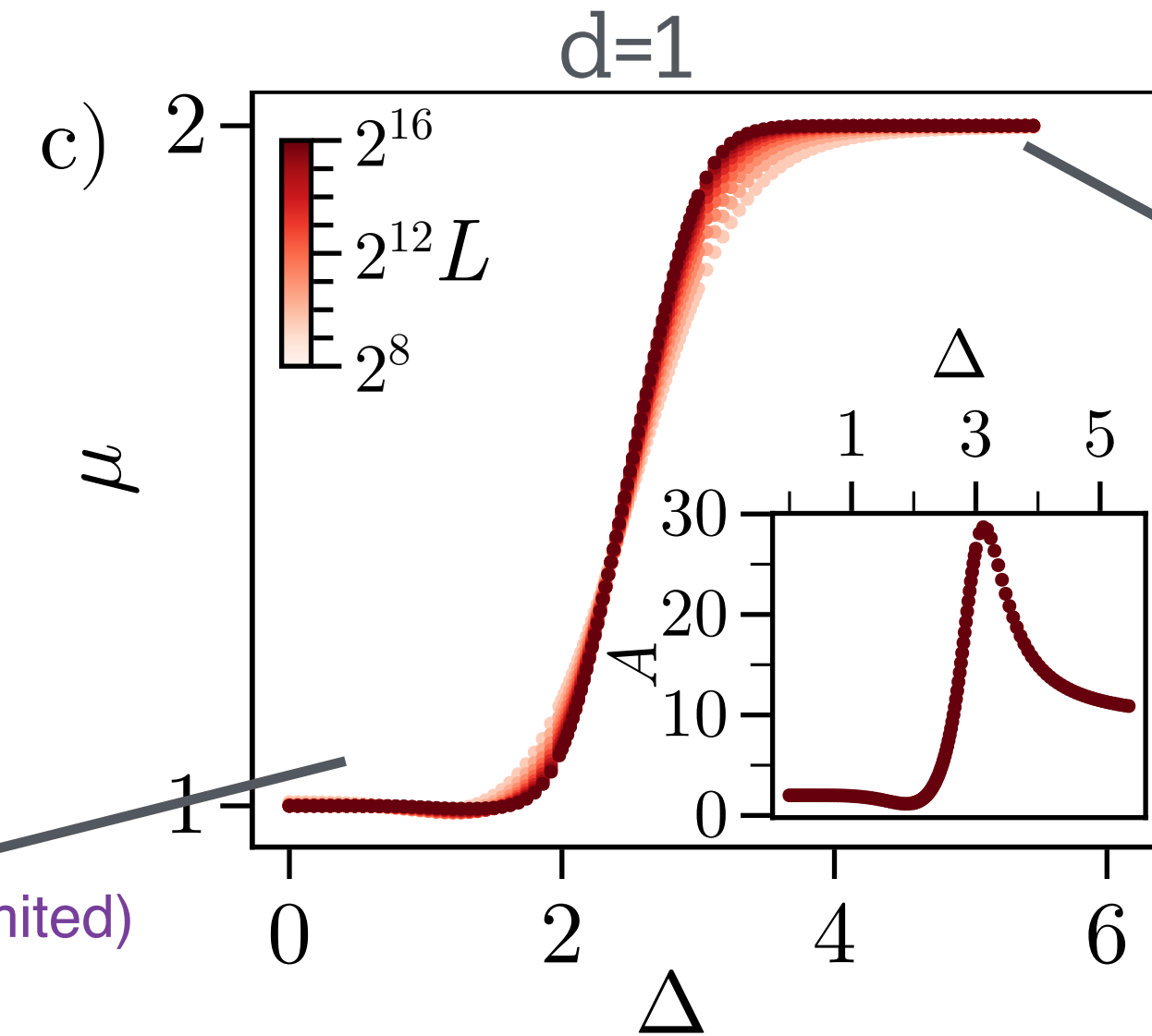
Dörstel, Iadecola, Wilson, **MB**, PRL (2026)

(a) modify geometry/range

measurement range $P_{\ell, \ell+m} \sim m^{-\Delta}$

$$t_{\text{prep}}(L) \sim AL^\mu$$

infinite-range (reaction limited)



short-range (diffusion limited)

(b) accelerate transport w/o measurement

add scrambling unitaries $\hat{U}_{\ell, \ell+1} = \exp(i\varphi \mathcal{S}_{\ell, \ell+1})$
SWAP

$$[\hat{U}_{\ell, \ell+1}, \hat{J}_{\text{tot}}] = 0$$

faster transport - no additional generation/annihilation

$$t_{\text{prep}}(L) \sim \frac{A}{1+R} L^{2-\alpha}$$

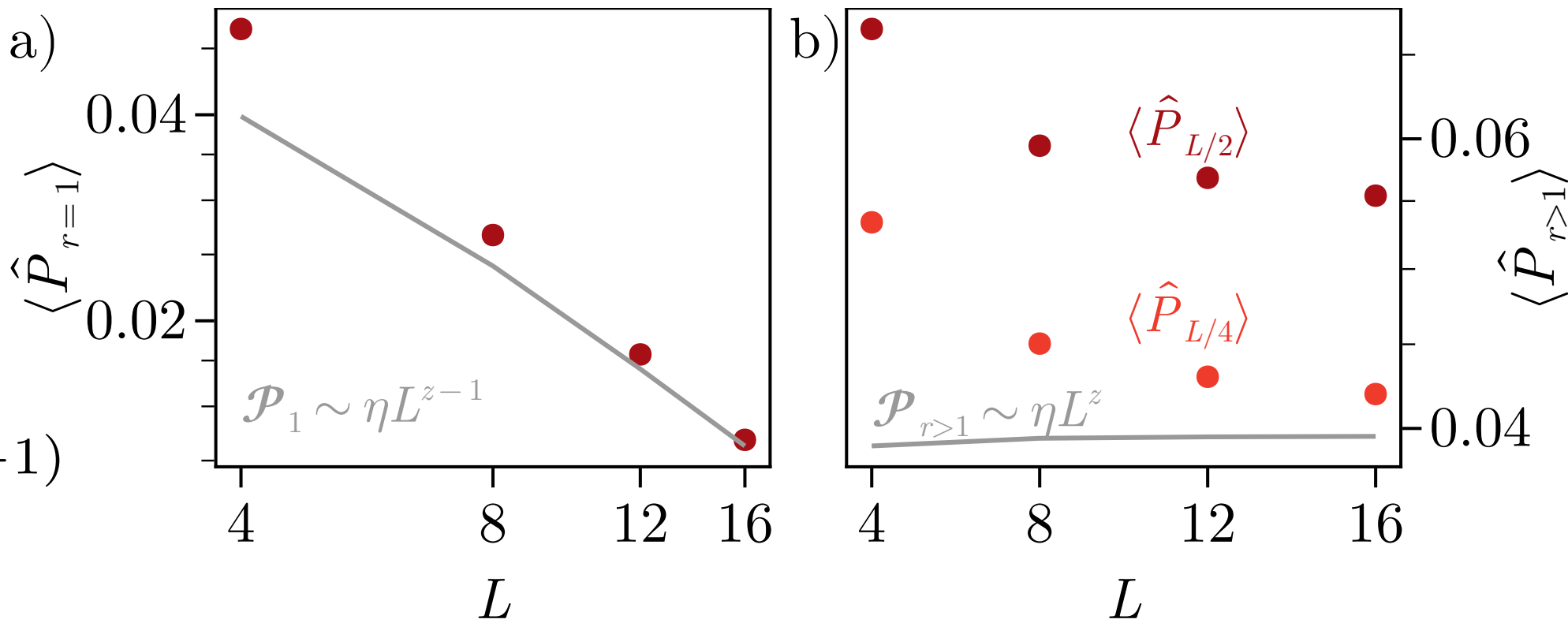
scrambling rate

Imperfections and generalization

measurement-feedback **imperfections** with rate η

compatible with absorbing state:
irrelevant

incompatible
 $\mathbb{E}(\langle \hat{P} \rangle) \sim \eta L^{\mu(-1)}$



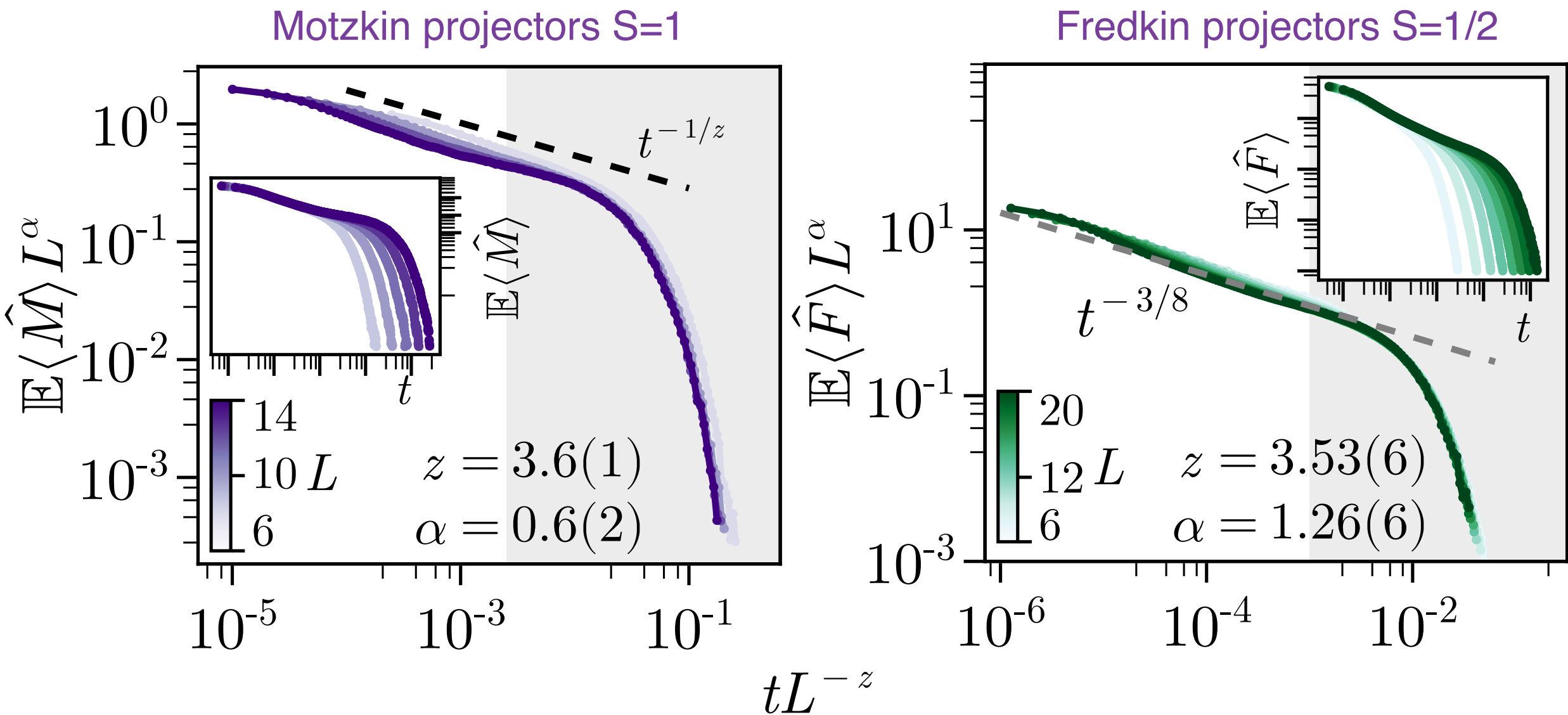
larger on-site Hilbert space $SU(2) \rightarrow SU(N)$

exactly solvable / same results

no closed defect picture

non-linear hydrodynamics: subdiffusion

Dörstel, Iadecola, Wilson, **MB**, PRL (2026)
Feldmeier, Liu, Lukin, Choi, arXiv (2026)



Takeaways

(Some) structured subspaces can be engineered as dynamical attractors

- measurements define defects
- feedback annihilates defects / makes subspace absorbing



J.H. Wilson



T. Iadecola

Thank you!